# Coarse differentiation of quasi-isometries II: Rigidity for Sol and lamplighter groups 

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#### Abstract

In this paper we prove quasi-isometric rigidity results concerning lattices in Sol and lamplighter groups. The paper builds in a substantial way on our earlier paper Coarse differentiation of quasi-isometries I: spaces not quasi-isometric to Cayley graphs.


## 1. Introduction and statements of results

This paper continues the work that was announced in [EFW07] and begun in [EFW12]. For a more detailed introduction, we refer the reader to those papers. As discussed in those papers, all our theorems stated above are proved using a new technique, which we call coarse differentiation. Even though quasi-isometries have no local structure and conventional derivatives do not make sense, we essentially construct a "coarse derivative" that models the large scale behavior of the quasi-isometry. From this point of view, the coarse derivatives of maps studied here are constructed in [EFW12] and this paper consists entirely of a coarse analysis of coarsely differentiable maps.

We now state the main results whose proofs are begun in [EFW12] and finished here. The group Sol $\cong \mathbb{R} \propto \mathbb{R}^{2}$ with $\mathbb{R}$ acting on $\mathbb{R}^{2}$ via the diagonal matrix with entries $e^{z / 2}$ and $e^{-z / 2}$. As matrices, Sol can be written as

$$
\mathrm{Sol}=\left\{\left.\left(\begin{array}{ccc}
e^{z / 2} & x & 0 \\
0 & 1 & 0 \\
0 & y & e^{-z / 2}
\end{array}\right) \right\rvert\,(x, y, z) \in \mathbb{R}^{3}\right\} .
$$

The metric $e^{-z} d x^{2}+e^{z} d y^{2}+d z^{2}$ is a left invariant metric on Sol. Any group of the form $\mathbb{Z} \ltimes_{T} \mathbb{Z}^{2}$ for $T \in \mathrm{SL}(2, \mathbb{Z})$ with $|\operatorname{tr}(T)|>2$ is a cocompact lattice in Sol.

The following theorem proves a conjecture of Farb and Mosher.
Theorem 1.1. Let $\Gamma$ be a finitely generated group quasi-isometric to Sol. Then $\Gamma$ is virtually a lattice in Sol.

[^0]We also prove rigidity results for wreath products $\mathbb{Z} \backslash F$ where $F$ is a finite group. The name lamplighter comes from the description $\mathbb{Z}\left\langle F=F^{\mathbb{Z}} \rtimes \mathbb{Z}\right.$ where the $\mathbb{Z}$ action is by a shift. The subgroup $F^{\mathbb{Z}}$ is thought of as the states of a line of lamps, each of which has $|F|$ states. The "lamplighter" moves along this line of lamps (the $\mathbb{Z}$ action) and can change the state of the lamp at her current position. The Cayley graphs for the generating sets $F \cup\{ \pm 1\}$ depend only on $|F|$, not the structure of $F$. Furthermore, $\mathbb{Z}\left\langle F_{1}\right.$ and $\mathbb{Z}\left\langle F_{2}\right.$ are quasi-isometric whenever there is a $d$ so that $\left|F_{1}\right|=d^{s}$ and $\left|F_{2}\right|=d^{t}$ for some $s, t$ in $\mathbb{Z}$. The problem of classifying these groups up to quasi-isometry, and in particular, the question of whether the 2 and 3 state lamplighter groups are quasi-isometric, were well-known open problems in the field; see [dlH00].

Theorem 1.2. The lamplighter groups $\mathbb{Z} \backslash F$ and $\mathbb{Z} \backslash F^{\prime}$ are quasi-isometric if and only if there exist positive integers $d, s, r$ such that $|F|=d^{s}$ and $\left|F^{\prime}\right|=d^{r}$.

For a rigidity theorem for lamplighter groups, see Theorem 1.3 below.
To state Theorem 1.3 we need to describe a class of graphs. These are the Diestel-Leader graphs, $\mathrm{DL}(m, n)$, which can be defined as follows. Let $T_{1}$ and $T_{2}$ be regular trees of valence $m+1$ and $n+1$. Choose orientations on the edges of $T_{1}$ and $T_{2}$ so each vertex has $n$ (resp. $m$ ) edges pointing away from it. This is equivalent to choosing ends on these trees. We can view these orientations at defining height functions $f_{1}$ and $f_{2}$ on the trees (the Busemann functions for the chosen ends). If one places the point at infinity determining $f_{1}$ at the top of the page and the point at infinity determining $f_{2}$ at the bottom of the page, then the trees can be drawn as


Figure 1. The trees for $\mathrm{DL}(3,2)$; figure borrowed from [PPS06].

The graph $\mathrm{DL}(m, n)$ is the subset of the product $T_{1} \times T_{2}$ defined by $f_{1}+f_{2}=0$. The analogy with the geometry of Sol is made clear in [EFW12, §3]. For $n=m$, the Diestel-Leader graphs arise as Cayley graphs of lamplighter groups $\mathbb{Z} \backslash F$ for $|F|=n$. This observation was apparently first made by R. Moeller and P. Neumann [Moe01] and is described explicitly, from two slightly different points of view, in [Woe05] and [Wor07]. We prove the following.

Theorem 1.3. Let $\Gamma$ be a finitely generated group quasi-isometric to the lamplighter group $\mathbb{Z} \backslash F$. Then there exist positive integers $d, s, r$ such that $d^{s}=$
$|F|^{r}$ and an isometric, proper, cocompact action of a finite index subgroup of $\Gamma$ on the Diestel-Leader graph $\mathrm{DL}(d, d)$.

Remark. The theorem can be reinterpreted as saying that any group quasiisometric to $\mathrm{DL}(|F|,|F|)$ is virtually a cocompact lattice in the isometry group of $\mathrm{DL}(d, d)$, where $d$ is as above.

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## 2. Results from [EFW12] and what remains to be done

Remark. All terminology in the following theorems is defined in [EFW12]. Most of it is recalled in Section 3 below. In particular, whenever we wish to make a statement that refers to either Sol or $\mathrm{DL}(m, m)$ we will use the notation $X(m)$ and refer to the space as the model space. As in [EFW12], $\operatorname{Sol}(m)$ denotes Sol with the dilated metric

$$
d s^{2}=d z^{2}+e^{-2 m z} d x^{2}+e^{2 m z} d y^{2}
$$

The main result of this paper is the following. The analogue of this theorem for $X(m, n)$ is proved in [EFW12, §5].

Theorem 2.1. For every $\delta>0, \kappa>1$ and $C>0$, there exists a constant $L_{0}>0$ (depending on $\left.\delta, \kappa, C\right)$ such that the following holds. Suppose $\phi$ : $X(n) \rightarrow X\left(n^{\prime}\right)$ is a $(\kappa, C)$ quasi-isometry. Then for every $L>L_{0}$ and every box $B(L)$, there exist a subset $U \subset B(L)$ with $|U| \geq(1-\delta)|B(L)|$ and a height-respecting map $\hat{\phi}(x, y, z)=(\psi(x, y, z), q(z))$ such that
(i) $d\left(\left.\phi\right|_{U}, \hat{\phi}\right)=O(\delta L)$.
(ii) For $z_{1}, z_{2}$ heights of two points in $B(L)$, we have

$$
\begin{equation*}
\frac{1}{2 \kappa}\left|z_{1}-z_{2}\right|-O(\delta L)<\left|q\left(z_{1}\right)-q\left(z_{2}\right)\right| \leq 2 \kappa\left|z_{1}-z_{2}\right|+O(\delta L) . \tag{1}
\end{equation*}
$$

(iii) For all $x \in U$, at least $(1-\delta)$ fraction of the vertical geodesics passing within $O(1)$ of $x$ are $(\eta, O(\delta L))$-weakly monotone.

This theorem, combined with results in [EFW12, §6], proves that any quasi-isometry $\phi: X(m) \rightarrow X\left(m^{\prime}\right)$ is within bounded distance of a heightrespecting quasi-isometry. This is done in two steps there; the first stated as [EFW12, Th. 6.1] roughly shows that $\phi$ respects height difference to sublinear error. Then in [EFW12, §6.2] we give an argument that shows this implies
$\phi$ is at bounded distance from height respecting. The deduction of Theorem 1.1 from this fact is already given explicitly in [EFW12, §7].

The proof of Theorem 2.1 uses the following consequence of [EFW12, Th. 4.1].

Theorem 2.2. Suppose $\varepsilon, \theta>0$. Let $\phi:$ Sol $\rightarrow$ Sol be a $(\kappa, C)$ quasiisometry. Then for any $L^{\prime}$ sufficiently large (depending on $\kappa, C, \theta$ ), there exist constants $R$ and $L$ with $C \ll R \ll L \ll L^{\prime}$ and $e^{\varepsilon R} \gg L^{\prime}$ such that for any box $B\left(L^{\prime}\right)$, there exist a collection of disjoint boxes $\left\{B_{i}(R)\right\}_{i \in I}$, a subset $I_{g}$ of $I$, and for each $i \in I_{g}$, a subset $U_{i} \subset B_{i}(R)$ with $\left|U_{i}\right| \geq(1-\theta)\left|B_{i}(R)\right|$ such that the following hold:

$$
\begin{gather*}
\bigsqcup_{i \in I_{g}} B_{i}(R) \subset \phi^{-1}\left(B\left(L^{\prime}\right)\right) \subset \bigsqcup_{i \in I} B_{i}(R) .  \tag{i}\\
\text { (ii) }\left|\bigsqcup_{i \in I_{g}} U_{i}\right| \geq(1-\theta)\left|\phi^{-1}\left(B\left(L^{\prime}\right)\right)\right| \text { and }\left|\phi\left(\bigsqcup_{i \in I_{g}} U_{i}\right)\right| \geq(1-\theta)\left|B\left(L^{\prime}\right)\right| .
\end{gather*}
$$

(iii) For each $i \in I_{g}$, there exists a product map $\hat{\phi}_{i}: B_{i}(R) \rightarrow$ Sol such that

$$
d\left(\left.\phi\right|_{U_{i}}, \hat{\phi}_{i}\right)=O(\varepsilon R)
$$

Proof. Choose $L$ large enough that [EFW12, Th. 4.1] holds with the given $\varepsilon$ and some $\theta_{0}<\theta$ for any box of size $L$. We cover $\phi^{-1}\left(B\left(L^{\prime}\right)\right)$ by boxes of size $L$ in the domain. Because $\phi$ is a quasi-isometry, $\phi^{-1}\left(B\left(L^{\prime}\right)\right)$ is a Fölner set which allows us to cover $\phi^{-1}\left(B\left(L^{\prime}\right)\right)$ by $\cup_{k \in K} B_{k}(L)$ such that the measure of $\cup_{k \in K} B_{k}(L)-\phi^{-1}\left(B\left(L^{\prime}\right)\right)$ is small provided $L^{\prime} \gg L$. We apply [EFW12, Th. 4.1] to the finite family of boxes $\left\{B_{k}(L) \mid k \in L\right\}$ and let $I_{g}$ be the good boxes that we index without reference to $k$. By choosing $\theta_{0}$ small enough and using the Fölner condition on $\phi^{-1}\left(B\left(L^{\prime}\right)\right)$, it is easy to see that the conclusions of the theorem are satisfied.

Recommendations to the reader. We strongly recommend that the reader study [EFW12] before this paper. In reading this paper, we recommend that the reader first assume that the map $\phi$ restricted to each $U_{i} \subset B_{i}(R)$ for $i \in I_{g}$ is within $O(\varepsilon R)$ of $b$-standard map, or better yet, the identity. (Replacing a $b$-standard map with the identity amounts to composing with a quasi-isometry of controlled constants and so has no real effect on our arguments.) This allows the reader to become familiar with the general outline of our arguments without becoming too caught up on technical issues.

The reader familiar with [EFW12] can then read Section 3 and essentially all of Section 5, skipping Section 4 entirely. In first reading Section 3, the reader might initially read Sections 3.1 through 3.4 and skip Section 3.5. This last subsection is only required in the case of solvable groups and then only
at the very end of Section 5.4. As remarked there, some of the definitions in Section 3.3 may also be omitted on first reading.

Remarks on the proof. It is possible to rewrite the arguments here and first prove that $\phi$ restricted to $U_{i} \subset B_{i}(R)$ for $i \in I_{g}$ is within $O(\varepsilon R)$ of a $b$-standard map. However, the arguments needed to prove this, while not so different in flavor from the arguments in Section 4, are extremely intricate and technical. The proof given here, while slightly more difficult in some later arguments, is essentially the same proof one would give after proving that fact. See Section 5 for more discussion.

## 3. Geometric preliminaries

In this section, we describe some key elements of the spaces we consider. There is some duplication with [EFW12], but the emphasis here is different.
3.1. Boxes, product maps, and almost product maps. We recall the notion of a box from [EFW12], first in $\operatorname{Sol}(m)$. Let

$$
B(L, \overrightarrow{0})=\left[-\frac{e^{2 m L}}{2}, \frac{e^{2 n L}}{2}\right] \times\left[-\frac{e^{2 m L}}{2}, \frac{e^{2 n L}}{2}\right] \times\left[-\frac{L}{2}, \frac{L}{2}\right] .
$$

In our current setting, $|B(L, \overrightarrow{0})| \approx L e^{2 L}$ and $\operatorname{Area}(\partial B(L, \overrightarrow{0})) \approx e^{2 L}$, so $B(L)$ is a Fölner set.

To define the analogous object in $\mathrm{DL}(m, m)$, we look at the set of points in $\mathrm{DL}(m, m)$ and we fix a basepoint $(\overrightarrow{0})$ and a height function $h$ with $h(\overrightarrow{0})=0$. Let $L$ be an even integer, and let $\mathrm{DL}(m, m)_{L}$ be the $h^{-1}\left(\left[-\frac{L+1}{2}, \frac{L+1}{2}\right]\right)$. Then $B(L, \overrightarrow{0})$ ) is the connected component of $\overrightarrow{0}$ in $\mathrm{DL}(m, m)_{L}$. We are assuming that the top and bottom of the box are midpoints of edges, to guarantee that they have zero measure.

We call $B(L, \overrightarrow{0})$ a box of size $L$ centered at the identity. In Sol, we define the box of size $L$ centered at a point $p$ by $B(L, p)=T_{p} B(L, \overrightarrow{0})$, where $T_{p}$ is left translation by $p$. We frequently omit the center of a box in our notation and write $B(L)$. For the case of $\mathrm{DL}(m, m)$, it is easiest to define the box $B(L, p)$ directly. That is, let $\mathrm{DL}(m, m)_{\left[h(p)-\frac{L+1}{2}, h(p)+\frac{L+1}{2}\right]}=$ $h^{-1}\left(\left[h(p)-\frac{L+1}{2}, h(p)+\frac{L+1}{2}\right]\right)$ and let $B(L, p)$ be the connected component of $p$ in $\mathrm{DL}(m, m)_{\left[h(p)-\frac{L+1}{2}, h(p)+\frac{L+1}{2}\right]}$. It is easy to see that isometries of $\mathrm{DL}(m, m)$ carry boxes to boxes.

For Sol, we write $B(R)=S_{X} \times S_{Y} \times S_{Z}$. We think of $S_{X}$ as a subset of the lower boundary, $S_{Y}$ as a subset of the upper boundary, and $S_{Z}$ as a subset of $\mathbb{R}$. In the $\mathrm{DL}(n, n)$ case, by $S_{X} \times S_{Y} \times S_{Z}$ we mean the set $\left\{p \in \mathrm{DL}(n, n): h(p) \in S_{Z}\right\}$ intersected with the union of all vertical geodesics connecting points of $S_{X}$ to points of $S_{Y}$. We also write $S_{Z}=\left[h_{\text {bot }}, h_{\text {top }}\right]$. We will use the notation $\partial^{+} X$ for the upper boundary and $\partial_{-} X$ for the lower boundary.

Definition 3.1 (Product Map, Standard Map). A map $\hat{\phi}: \operatorname{Sol} \rightarrow \operatorname{Sol}\left(n^{\prime}\right)$ is called a product map if it is of the form

$$
(x, y, z) \rightarrow(f(x), g(y), q(z)) \quad \text { or } \quad(x, y, z) \rightarrow(g(y), f(x), q(z)),
$$

where $f, g$, and $q$ are functions from $\mathbb{R} \rightarrow \mathbb{R}$. A product map $\hat{\phi}$ is called $b$-standard if it is the compostion of an isometry with a map of the form $(x, y, z) \rightarrow(f(x), g(y), z)$, where $f$ and $g$ are Bilipshitz with the Bilipshitz constant bounded by $b$.

The discussion of standard and product maps in the setting of $\mathrm{DL}(m, m)$ is slightly more complicated. We let $\mathbb{Q}_{m}$ be the $m$-adic rationals. The complement of a point in the boundary at infinity of $T_{m+1}$ is easily seen to be $\mathbb{Q}_{m}$. Let $x$ be a point in $\mathbb{Q}_{m}$ viewed as the lower boundary, and let $y$ be a point in $\mathbb{Q}_{m}$ (viewed as the upper boundary). There is a unique vertical geodesic in $\mathrm{DL}(m, m)$ connecting $x$ to $y$. To specify a point in $\mathrm{DL}(m, m)$ it suffices to specify $x, y$ and a height $z$. We will frequently abuse notation by referring to the $(x, y, z)$ coordinate of a point in $\mathrm{DL}(m, m)$ even though this representation is highly nonunique.

We need to define product and standard maps as in the case of solvable groups, but there is an additional difficulty introduced by the nonuniqueness of our coordinates. This is that maps of the form $(x, y, z) \rightarrow(f(x), g(y), q(z))$, even when one assumes they are quasi-isometries, are not well defined; different coordinates for the same points will give rise to different images. We will say a quasi-isometry $\psi$ is at bounded distance from a map of the form $(x, y, z) \rightarrow(f(x), g(y), q(z))$ if $d(\psi(p),(f(x), g(y), q(z)))$ is uniformly bounded for all points and all choices $p=(x, y, z)$ of coordinates representing each point. It is easy to check that $(x, y, z) \rightarrow(f(x), g(y), q(z))$ is defined up to bounded distance if we assume that the resulting map is a quasi-isometry. The bound depends on $\kappa, C, m, n, m^{\prime}$, and $n^{\prime}$.

Definition 3.2 (Product Map, Standard Map). A map $\hat{\phi}: \operatorname{DL}(m, m) \rightarrow$ $\mathrm{DL}\left(m^{\prime}, m^{\prime}\right)$ is called a product map if it is within bounded distance of the form $(x, y, z) \rightarrow(f(x), g(y), q(z))$ or $(x, y, z) \rightarrow(g(y), f(x), q(z))$, where $f: \mathbb{Q}_{m} \rightarrow$ $\mathbb{Q}_{m^{\prime}}\left(\right.$ or $\left.\mathbb{Q}_{n^{\prime}}\right), g: \mathbb{Q}_{n} \rightarrow \mathbb{Q}_{n^{\prime}}\left(\right.$ or $\left.\mathbb{Q} m^{\prime}\right)$, and $q: \mathbb{R} \rightarrow \mathbb{R}$. A product map $\hat{\phi}$ is called $b$-standard if it is the compostion of an isometry with a map within bounded distance of one of the form $(x, y, z) \rightarrow(f(x), g(y), z)$, where $f$ and $g$ are Bilipshitz with the Bilipshitz constant bounded by $b$.

Definition 3.3. Given a quasi-isometric embedding $\phi: B(R) \rightarrow X\left(n^{\prime}\right)$, we say $\phi$ is an $(\alpha, \theta)$ almost a product map if there exist subsets $U \subset B(R), E_{1} \subset$ $S_{X}$, and $E_{2} \subset S_{Y}$ of relative measure $1-\theta$ such that $U=\left\{(x, y, z): x \in E_{1}\right.$, $\left.y \in E_{2}, z \in S_{Z}\right\}$ and all geodesics connecting points in $E_{1}$ to points in $E_{2}$ have $\varepsilon$ monotone images under $\phi$.

Remark. We think of $f$ and $g$ as defined only on $E_{i}$. So by $f(I)$ we mean $f\left(I \cap E_{1}\right)$.

Lemma 3.4. Given a $(\alpha, \theta)$-almost product map $\phi$ there exist a subset $U^{*} \subset U$ with relative measure $1-128 \theta^{\frac{1}{2}}$ and a (partially defined) product map $\hat{\phi}: U^{*} \rightarrow X\left(m^{\prime}\right)$ such that

$$
d\left(\left.\phi\right|_{U}(p), \hat{\phi}(p)\right) \leq \alpha R
$$

for all $p \in U$.
Proof. This is the content of [EFW12, Lemma 4.11 and Prop. 4.12].
Remark. With an appropriate choice of constants, the converse of Lemma 3.4 is also true.

Notation. Using Lemma 3.4, we write an (almost) product map $\hat{\phi}: B(R)$ $\subset X(n) \rightarrow X\left(n^{\prime}\right)$ as $(x, y, z) \rightarrow(f(x), g(y), q(z))$, so the domain of $f$ is $S_{X}$, etc. We will always work with (almost) product maps of this kind; the arguments for those of the form $(x, y, z) \rightarrow(f(y), g(x), q(z))$ are almost identical. One can also formally deduce any result we need about almost product maps of the form $(x, y, z) \rightarrow(f(y), g(x), q(z))$ from the analogous fact about those of the form $(x, y, z) \rightarrow(f(x), g(y), q(z))$ by noting that these two forms of almost product map differ by either pre- or post-composition with an isometry.
3.2. Discretizing Sol. In this subsection, we introduce a discrete model for $\operatorname{Sol}(n)$ that has some technical advantages at some points in the argument. We will often make arguments for the discrete model instead of for $\operatorname{Sol}(n)$ itself. The discrete model is quasi-isometric to $\operatorname{Sol}(n)$ and in fact $\left(1, \rho_{1}\right)$ quasiisometric for a parameter $\rho_{1}$, which will we choose so that $C \ll \rho_{1} \ll \varepsilon R$.

The basic idea is to take a $\rho_{1}$ net in $\operatorname{Sol}(n)$ and replace $\operatorname{Sol}(n)$ by a graph on this net. It is possible to do this by taking an arithmetic lattice in Sol, taking a deep enough congruence subgroup, and taking the Cayley graph. More concretely, we write $\operatorname{Sol}(n)$ as $\mathbb{R} \ltimes \mathbb{R}^{2}$ and consider $\rho_{1} \mathbb{Z} \subset \mathbb{R}$ and $\rho_{1} \mathbb{Z}^{2} \subset \mathbb{R}^{2}$. Here we view $\mathbb{R}^{2} \subset \operatorname{Sol}(n)$ as the plane at height zero. We then form a $\rho_{1}$ net in $\operatorname{Sol}(n)$ by taking the union

$$
\mathcal{G}=\bigcup_{a \in \rho_{1} \mathbb{Z}} a \cdot \rho_{1} \mathbb{Z}^{2} .
$$

To make this a graph, we connect by an edge any pair of points in $\mathcal{G}$ whose heights differ by $\rho_{1}$ and that are within $10 \rho_{1}$ of one another. We metrize this graph by letting lengths of edges be the distance between the corresponding points in $\operatorname{Sol}(n)$, so all edges have length $O\left(\rho_{1}\right)$.

We can also replace $\mathrm{DL}(m, m)$ with a graph whose edges have length $O\left(\rho_{1}\right)$. For this we assume $\rho_{1} \in \mathbb{N}$. Consider only vertices in $\mathrm{DL}(m, m)$ in $h^{-1}\left(\rho_{1} \mathbb{Z}\right)$. Join two vertices by an edge of length $\rho_{1}$ if there is a monotone
vertical path between them. The resulting graph is clearly quasi-isometric to $\mathrm{DL}(m, m)$ and is in fact $\mathrm{DL}\left(m^{\rho_{1}}, m^{\rho_{1}}\right)$ but with the edge length fixed as $\rho_{1}$ instead of 1 .

We remark here that constants that are said to depend only on $K, C$ and the model geometries often also depend on the discretization scale. This is because the discretization process effectively replaces the model space with a graph.

### 3.3. Shadows, slabs, and coarsenings.

Shadows and projections. Let $H$ be a subset of an $y$-horocycle, and suppose $\rho>1$. By the $\rho$-shadow of $H$, denoted $\operatorname{Sh}(H, \rho)$, we mean the union of the vertical geodesic rays that start within distance $\rho$ of $H$ and go down. If $H$ is an $x$-horocycle, then the we use the same definition except that the geodesic rays are going up.

Given a subset of a $y$-horocycle $H$, we let $\pi_{-}(H)=\partial_{-} X \cap \operatorname{Sh}\left(H, \rho_{1}\right)$. We define $\pi^{+}(H)$ for a subset of an $x$-horocycle similarly. Note that we are suppressing $\rho_{1}$ in the notation. In any context where $\pi^{+}$or $\pi_{-}$are used, $\rho_{1}$ will be fixed in advance.

The number $\Delta(H)$. For a horocycle $H$ in a box $B(R)$, let

$$
\Delta(H)=\min \left(h_{\mathrm{top}}-h(H), h(H)-h_{\mathrm{bot}}\right) .
$$

Thus, $\Delta(H)$ measures how far $H \cap B(R)$ is from the top and bottom of $B(R)$.
The branching numbers $B_{X}$ and $B_{X}^{\prime}$. We define $B_{X}$ to be the branching constant of $X$. For solvable Lie groups, $B_{X(n)}=n$. For Diestal-Leader graphs, $B_{X(n)}=\log (n)$. We use the shorthand $B_{X}^{\prime}$ for $B_{X\left(n^{\prime}\right)}$.

Measures on the boundary at infinity. Note that the boundaries $\partial_{-}(X)$ and $\partial^{+}(X)$ are homogeneous spaces and thus have a natural Haar measure. (This measure is Lebesque measure on $\mathbb{R}$ if $X=$ Sol and the natural measure on the Cantor set if $X=\mathrm{DL}(n, n)$.) We normalize the measures by requiring that the shadow of a point at height 0 has measure 1 . These measures are all denoted by the symbol $|\cdot|$. Note that for any point $p \in X$,

$$
\begin{equation*}
\left|\pi_{-}(\{p\})\right| e^{-B_{X} h(p)}=1 . \tag{2}
\end{equation*}
$$

The parameter $\beta^{\prime \prime}$. We choose an arbitrary $\beta^{\prime \prime}$ with $\beta^{\prime \prime} \ll 1$, with the understanding that $\varepsilon$ and $\theta$ will be chosen so that $\varepsilon \ll \beta^{\prime \prime}$ and $\theta \ll \beta^{\prime \prime}$. The parameter $\beta^{\prime \prime}$ will be fixed until Section 5.5.

Slabs. The objects we refer to as slabs will always be subsets of the part of the box $B(R)$ that is at least $4 \kappa^{2} \beta^{\prime \prime} R$ from the boundary of $B(R)$, will always be defined in reference to a horocycle $H$ in $B(R)$, and are always contained in
$\operatorname{Sh}(H, \rho)$. We give definitions only for slabs in shadows of $y$ horocycles; those for $x$ horocycles are analogous and can be obtained by applying an appropriate flip. If we choose $h_{2}<h_{1}<h(H)$, a slab in $B(R)$ below $H$ is the subset $\mathrm{Sl}_{2}^{1}(H)$ that is defined to be the subset of the shadow of $H$ that is between heights $h_{2}$ and $h_{1}$.

Recommendation to the reader. The remainder of this subsection might be omitted on first reading.

Coarsening. In order to work with more regular sets, we define an operation to coarsen subsets of either boundary.

Let $a_{1}, a_{2}$ be two points in a (log model) hyperbolic plane (which we think of as the $x z$ plane in Sol). Let $h^{+}\left(a_{1}, a_{2}\right)$ be the height at which vertical geodesics leaving $a_{1}$ and $a_{2}$ are one unit apart. This function clearly extends to the lower boundary of the hyperbolic plane. We further extend the function to Sol by letting $h^{+}\left(p_{1}, p_{2}\right)=h^{+}\left(\pi_{x z}\left(p_{1}\right), \pi_{x z}\left(p_{2}\right)\right)$, where $\pi_{x z}(x, y, z)=(x, z)$. If $I=[a, b]$ is an interval, we write $h^{+}(I)$ for $h^{+}(a, b)$. Note that we can define $h_{-}$ similarly in a $y z$ plane. For $\mathrm{DL}(n, n)$, we define $h^{+}\left(a_{1}, a_{2}\right)$ as the height in $T_{n}$ at which vertical geodesics leaving $a_{1}$ and $a_{2}$ meet. Again $h_{-}$is defined similarly.

The operation of coarsening replaces any set $F$ by a set $\mathcal{C}_{z}(F)$ that is a union of open intervals of a certain size depending on $z$. For $F \subset \partial_{-} X$ and $z \in \mathbb{R}$, let $\mathcal{C}_{z}(F)$ denote the set of $x \in \partial_{-} X$ such that there exists $x^{\prime} \in F$ with $h^{+}\left(x, x^{\prime}\right)<z$. Similarly, for $F \subset \partial^{+} X$ and $z \in \mathbb{R}$, let $\mathcal{C}_{z}(F)$ denote the set of $y \in \partial^{+}(X)$ such that there exists $y^{\prime} \in F$ with $h^{-}\left(y, y^{\prime}\right)>z$.

Generalized slabs. Given two sets $E^{+} \subset \partial^{+} X$ and $E_{-} \subset \partial_{-} X$ and two heights $h_{2}<h_{1}$, we define a set

$$
S\left(E_{-}, E^{+}, h_{2}, h_{1}\right)=\left\{(x, y, z) \text { such that } h_{2}<z<h_{1} \text { and } x \in E_{-}, y \in E_{+}\right\} .
$$

In words, $S\left(E_{-}, E^{+}, h_{2}, h_{1}\right)$ is the set of points on geodesics joining $E^{+}$to $E_{-}$with height between $h_{1}$ and $h_{2}$. We refer to these sets as generalized slabs, though in general their geometry can be very bad, depending on the geometry of $E^{+}$and $E_{-}$. Generalized slabs will always be subsets of the part of the box $B(R)$ which is at least $4 \kappa^{2} \beta^{\prime \prime} R$ from the boundary of $B(R)$, even if this is not explicit in our specification of $E^{+}$and $E^{-}$. In particular, slabs as defined above are special cases of generalized slabs, with $\mathrm{SL}_{2}^{1}(H)=S\left(\pi_{-}(H), S_{Y}, h_{2}, h_{1}\right)$, where $h_{2}<h_{1}<h(H)$.

Clearly boxes are very special generalized slabs, and we prefer to work in general with generalized slabs that are unions of boxes. One can obtain a generalized slab that is a union of boxes by coarsening $E^{+}$and $E_{-}$. Let $h_{3}$ and $h_{4}$ be two additional heights, and consider $S\left(\mathcal{C}_{h_{3}}\left(E_{-}\right), \mathcal{C}_{h_{4}}\left(E^{+}\right), h_{2}, h_{1}\right)$. Observe that as long as $h_{3} \leq h_{2}$ and $h_{4} \geq h_{1}$, we have

$$
S\left(E_{-}, E^{+}, h_{2}, h_{1}\right)=S\left(\mathcal{C}_{h_{3}}\left(E_{-}\right), \mathcal{C}_{h_{4}}\left(E^{+}\right), h_{2}, h_{1}\right) .
$$

We will need some information concerning the geometry of coarse enough generalized slabs.

Lemma 3.5. Choose $h_{3} \geq h_{1}$ and $h_{4} \leq h_{2}$. Then any generalized slab of the form $S\left(\mathcal{C}_{h_{3}}\left(E_{-}\right), \mathcal{C}_{h_{4}}\left(E^{+}\right), h_{2}, h_{1}\right)$ is a union of boxes of size $h_{1}-h_{2}$. In the $\mathrm{DL}(m, m)$ case, $S\left(\mathcal{C}_{h_{3}}\left(E_{-}\right), \mathcal{C}_{h_{4}}\left(E^{+}\right), h_{2}, h_{1}\right)$ is a disjoint union of boxes of size $h_{1}-h_{2}$. In the Sol case, $S\left(\mathcal{C}_{h_{3}}\left(E_{-}\right), \mathcal{C}_{h_{4}}\left(E^{+}\right), h_{2}, h_{1}\right)$ is not a disjoint union of boxes, but any such set contains a disjoint union of boxes of height $h_{1}-h_{2}$ that contain $\frac{1}{25}$ of the volume of $S\left(\mathcal{C}_{h_{3}}\left(E_{-}\right), \mathcal{C}_{h_{4}}\left(E^{+}\right), h_{2}, h_{1}\right)$. Furthermore, the number of vertical geodesics in $S\left(\mathcal{C}_{h_{3}}\left(E_{-}\right), \mathcal{C}_{h_{4}}\left(E^{+}\right), h_{2}, h_{1}\right)$ is comparable to

$$
\frac{\operatorname{Vol}\left(\left(\mathcal{C}_{h_{3}}\left(E_{-}\right), \mathcal{C}_{h_{4}}\left(E^{+}\right), h_{2}, h_{1}\right)\right)}{h_{1}-h_{2}} e^{B_{X}\left(h_{1}-h_{2}\right)} ;
$$

i.e., it is comparable to the area of the cross-section times $e^{B_{X}\left(h_{1}-h_{2}\right)}$

Proof. That $S\left(\mathcal{C}_{h_{3}}\left(E_{-}\right), \mathcal{C}_{h_{4}}\left(E^{+}\right), h_{2}, h_{1}\right)$ is a union of boxes is clear from the definition of coarsening. In the $\mathrm{DL}(m, m)$ case, the set between $h_{1}$ and $h_{2}$ is a disjoint union of boxes of size $h_{1}-h_{2}$, so the result follows. For Sol, one proves the result by considering the set $W=S\left(\mathcal{C}_{h_{3}}\left(E_{-}\right), \mathcal{C}_{h_{4}}\left(E^{+}\right), h_{2}, h_{1}\right) \cap h^{-1}(z)$ for any $z \in\left(h_{2}, h_{1}\right)$. It is clear that $W$ is covered by its intersection with boxes of size $h_{1}-h_{2}$, all of which are rectangles of the same size and shape. Using the Vitali covering lemma, one finds a subset of the boxes that cover a fixed fraction of the measure of $W$. Since the volume of $S\left(\mathcal{C}_{h_{3}}\left(E_{-}\right), \mathcal{C}_{h_{4}}\left(E^{+}\right), h_{2}, h_{1}\right)$ is the area of the cross section times $h_{1}-h_{2}$, we are done.

The claim concerning numbers of vertical geodesics is obvious for a box. The proof, in general, can be reduced to that case using the earlier parts of this lemma.
3.4. The trapping lemma. In this subsection we state some results relating to areas, lengths, and shadows. These are used in the proof of Theorem 5.24. Some similar statements are contained in [EFW12, §5.2].

Lemma 3.6. Let $Q$ be a subset of an $x$-horocycle $H$. Then $\pi_{-}(Q)=\pi_{-}(H)$ and

$$
\ell(Q) \approx\left|\pi_{-}(H) \| \pi_{+}(Q)\right|
$$

where by $\ell(Q)$ we mean the length of the intersection of the $3 \rho$ neighborhood of $Q$ with $H$, and the implied constants depend on $\rho$.

Proof. This follows from (2).
Lemma 3.7. Suppose $\gamma \subset B(R)$ is a path. Let $L$ be a Euclidean plane intersecting $B(R)$, and suppose $U \subset L \cap B(R)$. Suppose also that any vertical geodesic segment from the bottom of $B(R)$ to the top of $B(R)$ that intersects
$U$ also intersects the $\rho$-neighborhood of $\gamma$. Then,

$$
\ell(\gamma) \geq c(\rho) \operatorname{Area}(U)
$$

(In the above, $c(\rho)$ is a constant, and both the length and the area are measured using the $X(n)$ metric.)

Proof. First note that if $L^{\prime}$ is another Euclidean plane, and $U^{\prime}$ is the (vertical) projection of $U$ on $L^{\prime}$, then $\operatorname{Area}\left(U^{\prime}\right)=\operatorname{Area}(U)$.

Now subdivide $\gamma$ into $k$ segments of length $\rho$. Let $x_{i}$ be the midpoints of such a segment. Let $R_{i}$ be a rectangle at the same height as $i$, such that $x_{i}$ is in the center of $R_{i}$ and the sides of the rectangle have length $2 \rho$. Then the $X(n)-$ area of $R_{i}$ is independent of $i$ and the projection of the union of the $R_{i}$ to $L$ must cover $U$. Therefore $k>c_{2}(\rho)$ Area $(U)$, and hence $\ell(\gamma)>c_{1}(\rho)$ Area $(U)$.

Lemma 3.8 (Trapping Lemma). Suppose $\rho_{1} \gg C, \phi: X(n) \rightarrow X(n)$ is $a(\kappa, C)$ quasi-isometry and $H$ is a subset (not necessarily connected) of an $x$-horocycle in $X(n)$.

Suppose $Q$ is a subset of a finite union of horocycles in $X(n)$ such that the $\kappa \rho_{1}$-neighborhood of $\phi(Q)$ intersects every vertical geodesic starting from the $\rho_{1}$-neighborhood of $H$ and going down. Then

$$
\ell(Q) \geq c_{1} \ell(H)
$$

where $c_{1}=c_{1}\left(\rho_{1}\right)$.
Proof. Discretize $H$ on the scale $\rho_{1}$, and apply Lemma 3.7.
Lemma 3.8 is sufficient for applications to $\mathrm{DL}(n, n)$. For applications to Sol, we will need a generalization that is stated in the next subsection.
3.5. Tangling and generalized trapping. The following (obvious) result about DL graphs is used implicitly in the proof of Theorem 5.24.

Lemma 3.9. Suppose $\rho>1$ and $p$ and $q$ are two points in $\mathrm{DL}(n, n)$. Suppose also $p \in \operatorname{Sh}(H, \rho), q \in \operatorname{Sh}(H, \rho)^{c}$. Then any path connecting $p$ to $q$ passes within $\rho$ of $H$.

Proof. The point is simply that if $\pi_{T}$ is the projection to the tree $T_{n+1}$ transverse to $H$, then $\pi_{T}(\operatorname{Sh}(H, \rho))$ is exactly the set directly below the unique point $x$ which is $\rho$ units above the projection of $\pi_{T}(H)$. And removing $x$ disconnects $T_{n+1}$.

The lemma above is false for the case of Sol. We will need the following variant. Fix an integer $\rho>100$ for the remainder of this section.

Definition 3.10 (Tangle). Let $H$ be a horocycles. We say that a path $\bar{\gamma}$ tangles with $H$ within distance $D$ if either $\bar{\gamma}$ intersects the $\rho$ neighborhood of
$H$ or

$$
\tau(\bar{\gamma}, H)=\sum_{j=1}^{\frac{D}{\rho}} \frac{\ell(\bar{\gamma} \cap\{p: j a \leq d(p, H) \leq(j+1) 3 \rho\})}{\nu(j a)}>100 .
$$

Here $\nu(r)$ is the volume of the ball of radius $r$ in the hyperbolic plane. Informally, in order for the path $\bar{\gamma}$ to tangle with the horocycle $H, \bar{\gamma}$ has to spend a lot of time near $H$, with the closest approaches to $H$ carrying more weight.

We say $\bar{\gamma}$ tangles with a finite union of horocycles $\mathcal{H}$ within distance $D$ if

$$
\sum_{H \in \mathcal{H}} \tau(\bar{\gamma}, H)>100,
$$

where $D$ is implicit in our definition of $\tau$.
We first state an easy lemma to illustrate situations in which paths can be forced to tangle with a horocycle.

Lemma 3.11. Let $\rho$ be as above, and let $H$ be horocycle in Sol. Suppose $p$ and $q$ are two points in Sol such that $p \in \operatorname{Sh}(H, \rho / 3)$ and $q \in \operatorname{Sh}(H, \rho)^{c}$. Then any path from $p$ to $q$ of length less than $L$ tangles with $H$ at distance $\log (L)$.

Proof. This is an easy hyperbolic geometry argument applied to the projection of the path a hyperbolic plane transverse to $H$.

For our applications, we require a more technical variant of Lemma 3.11. In our arguments, we deal with $\operatorname{Sh}\left(H, \rho_{1}\right)$, where $\rho_{1}$ is the discretization scale. For this reason, $\operatorname{Sh}\left(H, \frac{\rho_{1}}{3}\right)$ is not a good notion and we need to specify the set we consider differently. Given an horocycle $H$ and constant $D^{\prime}$, we say a point $p$ is $D^{\prime}$-deep in $\operatorname{Sh}(H, \rho)$ if $p$ is more than $D^{\prime}$ below $H$ and more than $\frac{D}{9}$ from the edges of the shadow.

Lemma 3.12. Let $\rho$ be as above, and choose constants $\rho \ll D_{1} \ll D_{2}$. Let $H$ be a horocycle, and suppose $p$ and $q$ are two points in Sol such that $p$ is $D_{2}$-deep in $\operatorname{Sh}(H, \rho)$ and $q \in \operatorname{Sh}(H, \rho)^{c}$. Then any path from $p$ to $q$ of length less than $e^{D_{1}}$ tangles with $\mathcal{H}$ within distance $D_{2}$.

Proof. This is an easy hyperbolic geometry argument applied to the projection of the path a hyperbolic plane transverse to $H$.

For a family $\mathcal{F}$ of vertical geodesic segments, we let $\|\mathcal{F}\|$ denote the area of $\mathcal{F} \cap P$, where $P$ is a Euclidean plane intersecting all the segments in $\mathcal{F}$. (If there is no such plane, we break up $\mathcal{F}$ into disjoint subsets $\mathcal{F}_{i}$ for which such planes exist, and we define $\|\mathcal{F}\|=\sum_{i}\left\|\mathcal{F}_{i}\right\|$.)

Lemma 3.13 (Generalized Trapping Lemma). Let $\rho \ll D_{2}$ be constants as above. Suppose $\mathcal{F}$ is a family of vertical geodesic segments, and suppose $Q$ is a subset of a finite union $\mathcal{H}$ of horocycles. Suppose also that for each $\gamma \in \mathcal{F}$, $\gamma$ tangles with $\mathcal{H}$ within distance $D_{2}$ and that $\gamma$ is contained in $N\left(Q^{c}, D_{2}\right)$.

Then, $\ell(Q) \geq \omega\|\mathcal{F}\|$, where $\omega$ depends only on $\kappa, C, n$, and the constants in the definition of tangle.

Proof. We assume $P$ is a Euclidean plane intersecting all the geodesics in $\mathcal{F}$; the general case is not much harder. Let $S(r)=\{p: r \leq d(p, Q) \leq r+a\}$. Then, $|S(r)|=c \ell(Q) \nu(r)$, where $c$ depends only on $a$. Then, we have by [EFW12, Prop. 5.4],

$$
\begin{aligned}
\ell(Q)=\frac{|S(r)|}{c \nu(r)} \geq \omega_{1} \frac{|(S(r))|}{\nu(r)} & \geq \omega_{1} \int_{\mathcal{F} \cap P} \frac{\ell(\gamma \cap(S(r)))}{\nu(r)} d \gamma \\
& \geq \omega_{2} \int_{\mathcal{F} \cap P} \frac{\ell(\gamma) \cap S(r))}{\nu(r)} d \gamma,
\end{aligned}
$$

where we have identified the space of vertical geodesics with $P$ and $\omega_{1}$ and $\omega_{2}$ depend only on ( $\kappa, C, a$ ). After writing $r=j a$, summing the above equation over $j$ and using the assumption that $\gamma$ tangles with $\mathcal{H}$ within distance $D_{2}$ and is contained in $N\left(Q^{c}, D_{2}\right)$ for all $\gamma \in \mathcal{F}$, we obtain that $\ell(Q) \geq \omega|\mathcal{F} \cap P|$ as required.

## 4. Improving almost product maps

In this section, we make some arguments that improve the information available concerning $\left.\phi\right|_{B_{i}(R)}$ where $i \in I_{g}$. More or less, by throwing away another set of small measure, we show that $\phi$ maps many slabs to particular nice generalized slabs. We also show that the map $q$ can be taken to be a linear map.

Recommendation to the reader. The reader may wish to skip this section on first reading and continue reading assuming that $\left.\phi\right|_{U_{i}}$ is $b$-standard or within $O(\varepsilon R)$ of a $b$-standard map. All the results in this section are somewhat technical in nature.
4.1. Bilipschitz in measure bounds. It is clear that the image of a slab under a product map is a generalized slab and that the image of a slab under a $b$-standard map is a slab. We need to work instead with images of slabs under almost product maps. Given an almost product map $\phi: B(R) \rightarrow$ Sol one wants to understand the image of $\mathrm{SL}_{2}^{1}(H)$. In general, there is not an obvious relation between $\phi\left(\mathrm{Sl}_{2}^{1}(H)\right)$ and $S\left(f\left(\pi_{-}(H)\right), g\left(S_{Y}\right), q\left(h_{2}\right), q\left(h_{1}\right)\right)$. We will show that this is true, at least up to sets of small measure, for appropriately chosen slabs, once we coarsen the image of the slab. To this end we let $h=h(H)$ and fix a height $h_{1}<h$. We define

$$
\begin{equation*}
\widehat{\mathrm{SL}}_{2}^{1}(H)=S\left(\mathcal{C}_{q\left(h_{1}\right)}\left(f\left(\pi_{-}(H)\right)\right), \mathcal{C}_{g\left(h_{2}\right)}\left(g\left(S_{Y}\right)\right), q\left(h_{2}\right), q\left(h_{1}\right)\right) . \tag{3}
\end{equation*}
$$

Note that $\widehat{\mathrm{SL}}_{2}^{1}(H)$ is a union of boxes of size $q\left(h_{1}\right)-q\left(h_{2}\right)$. When the choice of $H$ is clear, we suppress reference to $H$ and consider $h_{1}, h_{2}$. We also write $h$ for $h(H)$.

In this section, we prove two lemmas that show we can restrict attention to $\mathrm{SL}_{2}^{1}(H)$ that are almost entirely in $U^{*}$ and whose (coarsened) image is mostly a collection of boxes contained in (a small neighborhood) of the image of $U^{*}$.

Terminology. In order to discuss properties of $\widehat{\mathrm{Sl}}_{2}^{1}(H)$ without fixing either the orientation of $H$ or the almost product map on $B_{i}(R)$, we introduce some terminology. This terminology is justified by comparison with the case where $\widehat{\mathrm{Sl}}_{2}^{1}(H)$ is a slab. We refer to the direction in $z$ that goes from $q\left(h_{2}(H)\right)$ to $q(h(H))$ as towards the horocycle and the opposite direction as away from the horocycle. Similarly, there is a direction, either $x$ or $y$, that one can think of as being along the horocycle where the other direction is transverse to the horocycle. If $H$ is an $x$ horocycle and our product map is of the form $(x, y, z) \rightarrow(f(x), g(y), q(z))$, then $x$ is along the horocycle and $y$ is transverse to the horocycle.

Let $\phi$ be an $(\varepsilon, R)$ almost product map and $\hat{\phi}$ the corresponding (partially defined) product map. The following equation follows from the definitions. It says that the image of the intersection of certain slabs with the good set is essentially contained in a corresponding slab:

$$
\begin{equation*}
\phi\left(\mathrm{Sl}_{2}^{1}(H) \cap U_{*}\right) \subset N_{O(\varepsilon R)} \hat{\phi}\left(\mathrm{SL}_{2}^{1}(H) \cap U_{*}\right) \subset N_{O(\varepsilon R)}\left(\widehat{\mathrm{SL}}_{2}^{1}(H)\right) . \tag{4}
\end{equation*}
$$

The following two lemmas yield a strengthening of the equation above. The first lemma provides a lower bound on the measure of $\mathrm{Sl}_{2}^{1}(H) \cap U_{*}$ and so on the measure of $N_{O(\varepsilon R)}\left(\widehat{\mathrm{SL}}_{2}^{1}(H)\right)$ for most choices of $H$. The second lemma provides an upper bound on $N_{O(\varepsilon R)}\left(\widehat{\mathrm{SL}}_{2}^{1}(H)\right)$ and even $N_{O\left(\rho_{1}\right)}\left(\widehat{\mathrm{SL}}_{2}^{1}(H)\right)$ for a more restricted set of choices of $H$. To do this, we actually need to modify $\widehat{\mathrm{SL}}_{2}^{1}(H)$ in a way that we describe in Lemma 4.2.

Given any subset $A \subset B(R)$ and any constant $d<1$, we denote by $A^{d}$ the intersection of $A$ with the points in $B(R)$ more than $d R$ of the $\partial B(R)$.

Lemma 4.1. Given $\beta^{\prime} \gg \beta \gg \alpha \gg 1$, there exist constants $c_{1}, c_{2}$ depending on $\varepsilon, \theta$ and $\beta^{\prime}$ and a subset $E_{* *}$ of $S_{X}$ with $\left|S_{X} \backslash E_{* *}\right| \leq c_{1}\left(\theta, \varepsilon, \beta^{\prime}\right)\left|S_{X}\right|$ with the following properties. Given a $y$-horocycle $H$ intersecting $B(R)$ more than $2 \kappa \beta^{\prime} R$ away from $\partial B(R)$ and with $\pi_{-}(H)$ containing a point of $E_{* *}$ and any slab $\mathrm{SL}_{2}^{1}(H)$ such that $\beta^{\prime} R>\left|h_{1}(H)-h_{2}(H)\right|>\beta R, 4 \beta R>\left|h(H)-h_{1}(H)\right|>$ $2 \alpha R$, we have

$$
\begin{equation*}
\left|\mathrm{SL}_{2}^{1}(H) \cap U_{*}\right| \geq\left(1-c_{2}(\theta, \varepsilon)\right)\left|\mathrm{SL}_{2}^{1}(H)\right| . \tag{5}
\end{equation*}
$$

Our current notion of $\widehat{\mathrm{Sl}}_{2}^{1}(H)$ is a bit too coarse. In particular, there can be points in this set that are $O(R)$ away from $\phi\left(\mathrm{SL}_{2}^{1}(H)\right)$. We introduce some notations needed to describe a subset of $\widehat{\mathrm{Sl}}_{2}^{1}(H)$ that can be controlled more easily. Given a set $D \subset B(R)$, we denote by $S_{Y} \cap D$ the set in $S_{Y}$ consisting of
$y$ coordinates of points in $D$. We then define

$$
\widetilde{\mathrm{S}}_{2}^{1}(H, D)=S\left(\mathcal{C}_{q\left(h_{c}\right)}\left(f\left(\pi_{-}(H)\right)\right), \mathcal{C}_{g\left(h_{2}\right)}\left(g\left(S_{Y} \cap D\right)\right), q\left(h_{2}\right), q\left(h_{1}\right)\right) .
$$

The fact that we only intersect the $y$ coordinate with $D$ is not an accident; it is due to the fact that we consider sets that are "large" in the $y$ direction and "small" in the $x$ direction.

Lemma 4.2. Given $\beta^{\prime \prime} \gg \beta^{\prime} \gg \beta \gg \alpha \gg 1$, there exist constants $c_{3}, c_{4}$ depending on $\varepsilon, \theta$ and $\beta^{\prime}$ and a subset $E_{*}$ of $S_{X}$ with $\left|S_{X} \backslash E_{*}\right| \leq c_{3}(\theta, \varepsilon)\left|S_{X}\right|$ with the following properties. For any $y$-horocycle $H_{0}$ intersecting $B(R)$ more than $4 \kappa^{2} \beta^{\prime \prime} R$ away from $\partial B(R)$ with $\pi_{-}\left(H_{0}\right)$ containing a point of $E_{*}$, consider all horocycles $H$ in $S=S\left(\pi_{-}\left(H_{0}\right), S_{Y}, h\left(H_{0}\right), h\left(H_{0}\right)+\beta^{\prime \prime} R\right) \cap U_{*}$ with $\pi_{-}(H)$ containing a point of $E_{*}$ and any constants $\beta^{\prime} R>\left|h_{1}(H)-h_{2}(H)\right|>\beta R$, $4 \beta R>\left|h(H)-h_{1}(H)\right|>\alpha R$ such that the slab $\mathrm{SL}_{2}^{1}(H)$ is also contained in $S$. Letting $\widetilde{\mathrm{S}}_{2}^{1}(H)=\widetilde{\mathrm{Sl}}_{2}^{1}(H, \phi(S))$, we have

$$
\begin{equation*}
\left|\widetilde{\mathrm{Sl}}_{2}^{1}(H) \cap N_{\rho_{1}}\left(\phi\left(U_{*} \cap \mathrm{SL}_{2}^{1}(H)\right)\right)\right| \geq\left(1-c_{4}(\theta, \varepsilon)\right)\left|\widetilde{\mathrm{Sl}}_{2}^{1}(H)\right| . \tag{6}
\end{equation*}
$$

For $i=3,4$, we have $c_{i}(\theta, \varepsilon)=c_{i}(\theta, \varepsilon) \rightarrow 0$ as $\varepsilon \rightarrow 0$ and $\theta \rightarrow 0$.
Saying $H_{0}$ intersects $B(R)$ more than $4 \beta^{\prime \prime 2} R$ from $\partial B(R)$ is the same as saying $H_{0}$ intersects the box $B\left(\left(1-2 \beta^{\prime \prime}\right) R\right)$ with the same center as $B(R)$. The point is to stay away from the edge of the box. See the remarks in the definition of slabs and generalized slabs.

While the proof of Lemma 4.1 is essentially an application of the Vitali covering lemma, the proof of Lemma 4.2 depends on the fact that quasi-isometries roughly preserve volume. We will also need this fact to deduce some corollaries from Lemmas 4.1 and 4.2. We recall a precise statement from [EFW12].

Proposition 4.3. Let $\phi: X \rightarrow X^{\prime}$ be a continuous $(\kappa, C)$ quasi-isometry. Then for any $a \gg C$, there exists $\omega_{1}>1$ with $\log \omega_{1}=O(a)$ such that for any $U \subset X$,

$$
\omega_{1}^{-1}\left|\phi\left(N_{a}(U)\right)\right| \leq\left|N_{a}(U)\right| \leq \omega_{1}\left|N_{a}(\phi(U))\right|,
$$

where $N_{a}(U)=\{x \in X \quad: \quad d(x, U)<a\}$.
As explained in [EFW12], this fact holds much more generally for metric measure spaces that satisfy relatively mild conditions on the growth of balls.

Before proving the lemma, we state and prove a corollary concerning measures of cross sections. We note that by the definitions of the measures on the boundary, for a generalized slab $S\left(E_{-}, E^{+}, h_{2}, h_{1}\right)$, and $h_{1}<z<h_{2}$, the area (or equivalently volume) of the $O(1)$ neighborhood of the cross section at height $z$ (i.e., of $\left.S\left(E_{-}, E^{+}, h_{2}, h_{1}\right) \cap h^{-1}(z)\right)$ is $\left|\mathcal{C}_{z}\left(E_{+}\right)\right|\left|\mathcal{C}_{z}\left(E_{-}\right)\right|$.

Corollary 4.4. Assume that $H$ satisfies the hypotheses of Lemmas 4.1 and 4.2. Let $w_{1}, w_{2}$ be such that $2 \kappa \alpha R<\left|h(H)-w_{1}\right|<\frac{2}{\kappa} \beta R$ and $2 \kappa \beta R<$
$\left|w_{2}-w_{1}\right|<\frac{1}{2 \kappa} \beta^{\prime} R$. Then

$$
\begin{equation*}
\left|\mathcal{C}_{w_{1}}\left(f\left(\pi_{-}(H)\right)\right)\right|\left|\mathcal{C}_{\left.w_{2}\right)}\left(g\left(S_{Y} \cap S\right)\right)\right| \geq \omega\left|\pi_{-}(H)\right|\left|S_{Y}\right| \tag{7}
\end{equation*}
$$

and

$$
\begin{equation*}
\left|\mathcal{C}_{w_{1}}\left(f\left(\pi_{-}(H)\right)\right)\right|\left|\mathcal{C}_{w_{2}}\left(g\left(S_{Y} \cap S\right)\right)\right| \leq b\left|\pi_{-}(H)\right|\left|S_{Y}\right|, \tag{8}
\end{equation*}
$$

where $\omega$ and $b$ depend only on $\kappa$ and $C$.
Proof of Corollary. Note that from the structure of $U$ and the fact that $\phi$ is a quasi-isometry, it follows that for $z_{1}, z_{2} \in S_{Z}$, we have

$$
\begin{equation*}
\frac{1}{2 \kappa}\left|z_{1}-z_{2}\right|-O(\varepsilon R)<\left|q\left(z_{1}\right)-q\left(z_{2}\right)\right| \leq 2 \kappa\left|z_{1}-z_{2}\right|+O(\varepsilon R) \tag{9}
\end{equation*}
$$

In particular, $q$ is essentially monotone (up to $O(\varepsilon R)$ error).
Given $w_{1}, w_{2}$ as in the corollary, there exist heights $h_{1}(H)$ and $h_{2}(H)$ satisfying the hypotheses of Lemmas 4.1 and 4.2 such that $q\left(h_{1}(H)\right)=w_{1}, q\left(h_{2}(H)\right)$ $=w_{2}$. We apply those lemmas to the resulting $\mathrm{SL}_{2}^{1}(H)$ and $\widetilde{\mathrm{Sl}}_{2}^{1}(H)$.

Let $\operatorname{Vol}^{\prime}(X)=\left|N_{\rho_{1}}(X)\right|$ with $\varepsilon R \gg \rho_{1} \gg C$. Recall that $\left|h_{1}-h_{2}\right|>\beta R$ for some $\beta \gg \varepsilon$. By Lemma 3.5 and the fact that the measure of the $O(\varepsilon R)$ neighborhood of a box of size $\beta R$ is comparable to the measure of a box of size $\beta R$, we have

$$
\begin{equation*}
(1-c) \operatorname{Vol}^{\prime}\left(N_{O(\varepsilon R)}\left(\widetilde{\mathrm{Sl}}_{2}^{1}(H)\right)\right) \leq \operatorname{Vol}^{\prime}\left(\widetilde{\mathrm{Sl}}_{2}^{1}(H)\right) \tag{10}
\end{equation*}
$$

where $c$ is a constant that depends only on $\frac{\varepsilon}{\beta}$ and that goes to 0 as $\varepsilon$ goes to zero.

Note that (4) continues to hold when we replace $\widehat{\mathrm{Sl}}_{2}^{1}(H)$ by $\widetilde{\mathrm{Sl}}_{2}^{1}(H)$. Therefore, by (4) and (6), we have

$$
\begin{equation*}
\left(1-c_{3}\right)(1-c) \operatorname{Vol}^{\prime}\left({\widetilde{\mathrm{SL}_{2}}}_{2}^{1}(H)\right) \leq(1-c) \operatorname{Vol}^{\prime}\left(\phi\left(\operatorname{Sl}_{2}^{1}(H) \cap U_{*}\right)\right) \leq \operatorname{Vol}^{\prime}\left(\widetilde{\mathrm{SL}}_{2}^{1}(H)\right) \tag{11}
\end{equation*}
$$

But by Proposition 4.3 and (5),

$$
\begin{equation*}
\omega_{1}^{-1} \operatorname{Vol}^{\prime}\left(\operatorname{SL}_{2}^{1}(H)\right) \leq \operatorname{Vol}^{\prime}\left(\phi\left(\mathrm{Sl}_{2}^{1}(H) \cap U_{*}\right)\right) \leq \omega_{1} \operatorname{Vol}^{\prime}\left(\operatorname{SL}_{2}^{1}(H)\right), \tag{12}
\end{equation*}
$$

where $\omega_{1}$ depends only on $(\kappa, C)$. Now (7) and (8) follow from (12), (11), (9), and the fact that the volume of a sufficiently coarsened generalized slab is the area of the cross section times the difference in height.
4.2. Proof of Lemmas 4.1 and 4.2. We first prove a preliminary estimate.

Lemma 4.5. Given $p_{1}, p_{2}$ in $U^{*}$, then

$$
h^{+}\left(\phi\left(p_{1}\right), \phi\left(p_{2}\right)\right)=q\left(h^{+}\left(p_{1}, p_{2}\right)\right)+O(\varepsilon R) .
$$

Proof. By the definition of $U^{*}$ we can find $\tilde{p}_{i}$ in $U^{*}$ with $\pi_{x z}\left(\tilde{p}_{i}\right)=\pi_{x z}\left(p_{i}\right)$ and vertical geodesic segments $\gamma_{i} \subset U$ going up from $\tilde{p}_{i}$, which come within $O(1)$ at $h^{+}\left(p_{1}, p_{2}\right)$. Since each $\gamma_{i}$ is in $U$, each $\phi\left(\gamma_{i}\right)$ is within $O(\varepsilon R)$ of a
vertical geodesic $\tilde{\gamma}_{i}$ and the $\tilde{\gamma}_{i}$ come within $O(\varepsilon R)$ of one another only at $h^{+}\left(\phi\left(p_{1}\right), \phi\left(p_{2}\right)\right)+O(\varepsilon R)$. But by the definition of the product map, $\tilde{\gamma}_{1}$ is within $O(\varepsilon R)$ of $\tilde{\gamma}_{2}$ at $q\left(h^{+}\left(p_{1}, p_{2}\right)\right)$.

Proof of Lemma 4.1. Let $c_{2}=c_{2}(\varepsilon, \theta)$ be a constant to be chosen later. Fix $i<j$. Let $E_{1} \subset S_{X}$ be such that for $x \in E_{1}$, there exists a horocycle $H_{x}$ such that $x \in I_{x} \equiv \pi_{-}\left(H_{x}\right)$ and (5) fails for some slab $\mathrm{SL}_{2}^{1}\left(H_{k}\right)$ as in the statement of the lemma. Note that by assumption $\mathrm{SL}_{2}^{1}\left(H_{k}\right) \subset B(R)$. Thus we have a cover of $E_{1}$ by the intervals $I_{x}$. Then, by the Vitali covering lemma there are intervals $I_{k}=\pi_{-}\left(H_{k}\right)$ such that the inequality opposite to (5) holds for $H_{k}, \sum_{k}\left|I_{k}\right| \geq(1 / 5)\left|E_{1}\right|$, and also the $I_{k}$ are strongly disjoint, i.e., for $j \neq k$, $d\left(I_{j}, I_{k}\right) \geq(1 / 2) \max \left(\left|I_{j}\right|,\left|I_{k}\right|\right)$. Then the sets $\mathrm{SL}_{2}^{1}\left(H_{k}\right)$ are also disjoint. By construction, $\left|\mathrm{SL}_{2}^{1}\left(H_{k}\right) \cap U_{*}^{c}\right| \geq c_{2}\left|\mathrm{Sl}_{2}^{1}\left(H_{k}\right)\right|$. Summing this over $k$, we get that

$$
\left|B(R) \cap U_{*}^{c}\right| \geq c_{2} \sum_{k}\left|\operatorname{SL}_{2}^{1}\left(H_{k}\right)\right| \geq\left(c_{2} / 2\right) \sum_{k}\left|h_{1}\left(H_{k}\right)-h_{2}\left(H_{k}\right)\right|\left|I_{k}\right|\left|S_{Y}\right| .
$$

Since $\left|B(R) \cap U_{*}^{c}\right| \leq \theta R\left|S_{X}\right|\left|S_{Y}\right|$, we get

$$
\left|E_{1}\right| \leq 5 \sum_{k}\left|I_{k}\right| \leq \frac{10 \theta}{\beta^{\prime} c_{2}}\left|S_{X}\right| .
$$

If $c_{1} c_{2} \beta^{\prime}=20 \theta$, this implies that $\left|E_{1}\right|<\frac{c_{1}}{2}\left|S_{X}\right|$. So letting $E_{* *}=S_{X} \backslash E_{1}$, we are done.

Proof of Lemma 4.2. We construct $E_{*}$ as a subset of $E_{* *}$ from Lemma 4.1, so any $H$ satisfying the hypotheses of Lemma 4.2 satisfies the conclusions of Lemma 4.1.

We now show that $\widetilde{\mathrm{S}}_{2}^{1}(H) \subset \phi(B(R))$. Recall that $H_{0}$ is more than $4 \kappa^{2} \beta^{\prime \prime} R$ from the edge of $B(R)$. By definition,

$$
\widetilde{\mathrm{S}}_{2}^{1}(H)=S\left(\mathcal{C}_{q\left(h_{c}\right)}\left(f\left(\pi_{-}(H)\right)\right), \mathcal{C}_{g\left(h_{2}\right)}\left(g\left(S_{Y} \cap S\right)\right), q\left(h_{2}\right), q\left(h_{1}\right)\right) .
$$

Since $S \subset U_{*}$, for any $y \in S_{Y} \cap S$ there is a point $p=(x, y, z) \in S$ such that $\phi$ maps $p$ to within $O(\varepsilon R)$ of $(f(x), g(y), q(z))$ with $x$ in $\pi_{-}(H)$. The point $p$ is at most $\beta^{\prime \prime} R$ from $H_{0}$, and $\phi(p)$ is within $O(\varepsilon R)$ of a vertical geodesic $\gamma$ that stays within $O(\varepsilon R)$ of the image of a vertical geodesic through $p$. Note that any point $q$ in $S\left(f\left(\pi_{-}(H)\right), g\left(S_{Y} \cap S\right), q\left(h_{2}\right), q\left(h_{1}\right)\right)$ is on a vertical geodesic $\gamma^{\prime}$ that stays within $\varepsilon R$ of the image of a geodesic that passes through $S$ and therefore through $H_{0}$. The point $\phi(p)$ is within $\kappa \beta^{\prime \prime} R$ of where the geodesics $\gamma$ and $\gamma^{\prime}$ come within $O(\varepsilon R)$ since $p$ is within $\beta^{\prime \prime} R$ of the point where the corresponding geodesics in the domain come close. This implies that $q$ is within $3.1 \kappa \beta^{\prime \prime} R$ of $\phi(p)$. By the definition of coarsening, this implies that any point in $S\left(\mathcal{C}_{q\left(h_{c}\right)}\left(f\left(\pi_{-}(H)\right)\right), \mathcal{C}_{g\left(h_{2}\right)}\left(g\left(S_{Y} \cap S\right)\right), q\left(h_{2}\right), q\left(h_{1}\right)\right)$ is within $4 \kappa \beta^{\prime \prime} R$ of $\phi(p)$. By our assumptions on $S$ and $p$, this shows that $\widetilde{\mathrm{Sl}}_{2}^{1}(H) \subset \phi(B(R))$.

Let $c_{3}=c_{3}\left(\varepsilon, \theta, \beta^{\prime}\right)$ be a constant to be chosen later. Let $E_{2} \subset S_{X} \backslash E_{1}$ be such that for $x \in E_{2}$, there exists a horocycle $H_{x}$ such that $x \in I_{x} \equiv \pi_{-}\left(H_{x}\right)$ and (6) fails. Thus we have a cover of $E_{1}$ by the intervals $I_{x}$. Then, by the Vitali covering lemma there are intervals $I_{k}=\pi_{-}\left(H_{k}\right)$, such that the inequality opposite to (6) holds for $H_{k}$ instead of $H, \sum_{k}\left|I_{k}\right| \geq(1 / 5)\left|E_{2}\right|$, and also the $I_{k}$ are strongly disjoint, i.e., for $l \neq k, d\left(I_{l}, I_{k}\right) \geq(1 / 2) \max \left(\left|I_{l}\right|,\left|I_{k}\right|\right)$.

We now claim that

$$
\begin{equation*}
\phi\left(\operatorname{Sh}\left(H_{k}, O(1)\right)^{c} \cap U_{*}\right) \cap \widetilde{\operatorname{Sl}}_{2}^{1}\left(H_{k}\right)=\emptyset . \tag{13}
\end{equation*}
$$

Indeed, suppose $p \in \operatorname{Sh}\left(H_{k}, O(1)\right)^{c} \cap U_{*}$ and $\phi(p) \in \widetilde{\mathrm{Sl}}_{2}^{1}\left(H_{k}\right)$. By the definition of $\widehat{\mathrm{Sl}}_{2}^{1}\left(H_{k}\right), \pi_{-}(\phi(p)) \subset \mathcal{C}_{q\left(h_{c}(H)\right)}\left(f\left(\pi_{-}\left(H_{k}\right)\right)\right)$. Hence, by the definition of coarsening, there exists $p^{\prime} \in \operatorname{Sh}\left(H_{k}, O(1)\right) \cap U_{*}$ such that $h^{+}\left(\phi(p), \phi\left(p^{\prime}\right)\right)=$ $q\left(h_{c}(H)\right)+O(1)$. Since $p_{1} \in \operatorname{Sh}\left(H_{k}, O(1)\right)^{c}$ and $p_{2} \in \operatorname{Sh}\left(H_{k}, O(1)\right)$, we have $h^{+}\left(p_{1}, p_{2}\right)>h\left(H_{k}\right)+O(1)$. This contradicts Lemma 4.5, and thus (13) holds. The same argument shows that the sets $\widetilde{\mathrm{Sl}}_{2}^{1}\left(H_{k}\right)$ are disjoint.

Suppose $p \in \widetilde{\mathrm{~S}}_{2}^{1}\left(H_{k}\right), q\left(h_{2}\left(H_{k}\right)\right)+O(\varepsilon R)<h(p)<q\left(h_{1}\left(H_{k}\right)\right)-O(\varepsilon R)$, and $p \notin N_{O(\varepsilon R)}\left(\phi\left(\mathrm{SL}_{2}^{1}\left(H_{k}\right) \cap B(R)\right)\right)$. We claim that $p \notin \phi\left(U_{*}\right)$. Indeed, if $p=\phi\left(p^{\prime}\right)$ where $p^{\prime} \in U_{*}$, then by (13), $p^{\prime} \notin \operatorname{Sh}\left(H_{k}, O(1)\right)^{c}$. But since $h_{2}\left(H_{k}\right)<h\left(p^{\prime}\right)<$ $h_{1}\left(H_{k}\right)$, we have $p^{\prime} \in \mathrm{SL}_{2}^{1}\left(H_{k}\right) \cap B(R)$. This is a contradiction, and hence $p \notin \phi\left(U_{*}\right)$. This implies that $\phi\left(U^{*} \cap \mathrm{SL}_{2}^{1}\left(H_{k}\right)^{c}\right) \cap \widehat{\mathrm{Sl}}_{2}^{1}\left(H_{k}\right)$ contributes negligibly to the measure of $\widehat{\mathrm{Sl}}_{2}^{1}\left(H_{k}\right)$; i.e., the contribution goes to zero as $\varepsilon$ goes to zero. So to complete the proof, we need only control $\operatorname{Vol}^{\prime}\left(\widetilde{\mathrm{Sl}}_{2}^{1}\left(H_{k}\right) \cap \phi\left(B(R) \cap U_{*}^{c}\right)\right)$.

Thus, since we are assuming the opposite inequality to (6), we have $\operatorname{Vol}^{\prime}\left(\widetilde{\mathrm{Sl}}_{2}^{1}\left(H_{k}\right) \cap \phi\left(B(R) \cap U_{*}^{c}\right)\right) \geq c_{3}\left|\widetilde{\mathrm{Sl}}_{2}^{1}\left(H_{k}\right)\right|$. But then, using the disjointness of the $\widetilde{\mathrm{Sl}}_{2}^{1}\left(H_{k}\right)$, we get

$$
\begin{align*}
\operatorname{Vol}^{\prime}\left(\phi\left(B(R) \cap U_{*}^{c}\right)\right) & \geq c_{3} \sum_{k}\left|\widehat{\mathrm{Sl}}_{2}^{1}\left(H_{k}\right)\right| \geq\left(c_{3}\right)(1-c) \operatorname{Vol}^{\prime}\left(\phi\left(\mathrm{SL}_{2}^{1}\left(H_{k}\right) \cap U_{*}\right)\right)  \tag{14}\\
& \geq \omega_{3} c_{3} \sum_{k}\left|\mathrm{SL}_{2}^{1}\left(H_{k}\right) \cap U_{*}\right| \geq \omega_{4} c_{3} \beta R \sum_{k}\left|I_{k}\right|\left|S_{Y}\right|
\end{align*}
$$

The first inequality is our assumption. The second uses equation (11). The third is Proposition 4.3 and also uses the fact that each $I_{k}$ contains a point of $S_{X} \backslash E_{1}$ to conclude that $\left|\mathrm{SL}_{2}^{1}\left(H_{k}\right) \cap U_{*}\right| \geq(1 / 2)\left|\mathrm{SL}_{2}^{1}\left(H_{k}\right)\right|$.

Since by Proposition 4.3, $\operatorname{Vol}^{\prime}\left(\phi\left(B(R) \cap U_{*}^{c}\right)\right) \leq \omega_{5} \theta R\left|S_{X}\right|\left|S_{Y}\right|$, we get

$$
\left|E_{2}\right| \leq 5 \sum_{k}\left|I_{k}\right| \leq \frac{\omega_{6} \theta}{c_{3} \beta}\left|S_{X}\right| .
$$

And so $\left|E_{2}\right|<\frac{c_{1}}{2}$, provided $c_{3} c_{1} \beta=2 \omega_{6} \theta$. So after letting $E_{*}=S_{X} \backslash E_{1} \cup E_{2}$, the proof is complete.
4.3. The map on heights. Suppose $B(R) \subset X(n)$ is a box, and suppose $\phi: B(R) \rightarrow X\left(n^{\prime}\right)$ is an $(\varepsilon, \theta)$ almost-product map. Then by definition, there exist a partially defined product map $\hat{\phi}=(f, g, q)$ and a subset $U \subset B(R)$ with $|U| \geq(1-\theta)|B(R)|$ such that

$$
\begin{equation*}
d\left(\left.\phi\right|_{U}, \hat{\phi}\right)=O(\varepsilon R) . \tag{15}
\end{equation*}
$$

Proposition 4.6 (Map on heights). Let $\beta \ll \beta^{\prime} \ll \beta^{\prime \prime} \ll 1$ be as in Section 4.1. Write $B(R)=S_{X} \times S_{Y} \times\left[h_{\mathrm{bot}}, h_{\mathrm{top}}\right]$. Suppose the following hold:

- $h_{\text {bot }}<z_{\text {bot }}<z_{\text {top }}<h_{\text {top }}$.
- $4 \beta R \leq\left|z_{\text {top }}-z_{\text {bot }}\right| \leq \beta^{\prime} R$.
- $\left|h_{\text {top }}-z_{\text {top }}\right|>4 \kappa^{2} \beta^{\prime \prime} R$.
- $\left|z_{\text {bot }}-h_{\text {bot }}\right|>4 \kappa^{2} \beta^{\prime \prime} R$.

Then there exists a set $S \subset B(R)$ as in Lemma 4.2 and a function $\varepsilon^{\prime}=$ $\varepsilon^{\prime}(\varepsilon, \theta)$ with $\varepsilon^{\prime} \rightarrow 0$ as $\varepsilon \rightarrow 0$ and $\theta \rightarrow 0$ such that for all $z \in\left[z_{\mathrm{bot}}, z_{\mathrm{top}}\right]$,

$$
q(z)=A z-\frac{1}{B_{X}^{\prime}} \log \frac{\left|\mathcal{C}_{q\left(z_{\mathrm{bot}}\right)}\left(g\left(S_{Y} \cap S\right)\right)\right|}{\left|S_{Y}\right|}+O\left(\varepsilon^{\prime} R\right),
$$

where $A=B_{X(n)} / B_{X\left(n^{\prime}\right)}=B_{X} / B_{X}^{\prime}$ is the ratio of branching constants. In particular, if $n=n^{\prime}$, then $A=1$.

Remark. In all applications of Proposition 4.6, we change $q$ by $O\left(\varepsilon^{\prime} R\right)$ in order to have (4.6) hold with no error term.

Remark. For any $n, n^{\prime}$ there exists a standard map $\hat{\phi}=(f, g, q): X(n) \rightarrow$ $X\left(n^{\prime}\right)$ with $q(z)=A z$. For solvable groups, $\hat{\phi}$ is simply a homothety. For Diestal-Leader graphs, it is given by collapsing levels.

The rest of this subsection will consist of the proof of Proposition 4.6. Apply Lemmas 4.1 and 4.2 to get a set $E_{*} \subset S_{X}$. Let $H, H_{0}$ be $y$ horocycles that satisfy the conditions of Lemmas 4.1 and 4.2 with $h\left(H_{0}\right)>h(H)>$ $z_{\text {top }}$. In particular, $\pi_{-}(H)$ contains a point of $E_{*}$. Choose an arbitrary $z \in$ [ $z_{\text {bot }}, z_{\text {top }}$ ], and let $h_{1}=z, h_{2}=z_{\text {bot }}$. For the remainder of this subsection we simplify notation by writing $g\left(S_{Y}\right)$ for $g\left(S_{Y} \cap S\right)$.

Lemma 4.7. There exists a function $\varepsilon^{\prime}=\varepsilon^{\prime}(\varepsilon, \theta)$ with $\varepsilon^{\prime} \rightarrow 0$ as $\varepsilon \rightarrow 0$ and $\theta \rightarrow 0$ such that the following hold. Let $\mathcal{F}$ denote the set of vertical geodesic segments in $\mathrm{SL}_{2}^{1}(H)$, and let $\hat{\mathcal{F}}$ denote the set of vertical geodesic segments in $\widetilde{\mathrm{Sl}}_{2}^{1}(H)$. Then there exist a subset $\mathcal{F}^{\prime} \subset \mathcal{F}$ with $\left|\mathcal{F}^{\prime}\right| \geq(1 / 2)|\mathcal{F}|$ and a map $\psi: \mathcal{F}^{\prime} \rightarrow \hat{\mathcal{F}}$ that is at most $e^{\varepsilon^{\prime} R}$ to one. Also there exists a subset $\hat{\mathcal{F}}^{\prime} \subset \hat{\mathcal{F}}$ with $\left|\hat{\mathcal{F}}^{\prime}\right| \geq(1 / 2)|\hat{\mathcal{F}}|$ and a map $\hat{\mathcal{\psi}}: \hat{\mathcal{F}}^{\prime} \rightarrow \mathcal{F}$ that is at most $e^{\varepsilon^{\prime} R}$ to one. Hence,

$$
\begin{equation*}
\log |\mathcal{F}|=\log |\hat{\mathcal{F}}|+O\left(\varepsilon^{\prime} R\right) \tag{16}
\end{equation*}
$$

Proof. Let $c_{2}$ be as in (5). We let $\mathcal{F}^{\prime}$ be the set of vertical geodesics in $\mathrm{SL}_{2}^{1}(H)$ that are more than $O(\varepsilon R)$ from the edges and that spend at least
$1-\sqrt{c_{2}}$ fraction of their length in $U_{*}$. Then, by (5), $\left|\mathcal{F}^{\prime}\right| \geq(1 / 2)|\mathcal{F}|$. Now since $\phi$ is an almost-product map, for each $\gamma \in \mathcal{F}^{\prime}$ there exists a geodesic $\hat{\gamma} \in \hat{\mathcal{F}}$ such that $\phi\left(\gamma \cap U_{*}\right)$ is within $O(\varepsilon R)$ of $\hat{\gamma}$. We define $\psi(\gamma)=\hat{\gamma}$. The map $\psi$ is at most $e^{O\left(\varepsilon R+\sqrt{c_{2}} R\right)}$ to one since two geodesics with the same image must be within $\varepsilon R$ of each other whenever they are in $U_{*}$. By assumption, there exist points in $U_{*}$ on each geodesic within $O\left(\sqrt{c_{2}} R\right)$ of $h_{\text {top }}$ and $h_{\text {bot }}$.

The construction of the "inverse" map $\hat{\psi}$ is virtually identical, except that one uses (6) instead of (5) and $c_{3}$ instead of $c_{2}$. In the end, we can choose $\varepsilon^{\prime}=O\left(\varepsilon+\sqrt{c_{2}}+\sqrt{c_{3}}\right)$.

Lemma 4.8. For all $z \in\left[z_{\text {bot }}, z_{\text {top }}\right]$,

$$
q(z)-q\left(z_{\mathrm{bot}}\right)=A\left(z-z_{\mathrm{bot}}\right)+O\left(\varepsilon^{\prime} R\right)
$$

Proof. We count vertical geodesics using Lemma 4.7. Note that

$$
|\mathcal{F}| \sim\left|\pi_{-}(H)\right|\left|S_{Y}\right| e^{B_{X}\left(h_{1}-h_{2}\right)}
$$

and by Lemma $3.5,|\hat{\mathcal{F}}|$ is comparable to

$$
\mid \mathcal{C}_{h_{1}}\left(f\left(\pi_{-}(H)\right)| | \mathcal{C}_{h_{2}}\left(g\left(S_{Y}\right)\right) \mid e^{B_{X^{\prime}}\left(q\left(h_{1}\right)-q\left(h_{2}\right)\right)}\right.
$$

where as above, $h_{1}=z, h_{2}=z_{\text {bot }}$. Then, by (16),
$q\left(h_{1}\right)-q\left(h_{2}\right)=A\left(h_{1}-h_{2}\right)+\frac{1}{B_{X}^{\prime}} \log \frac{\left|\mathcal{C}_{q\left(h_{1}\right)}\left(f\left(\pi_{-}(H)\right)\right)\right|\left|\mathcal{C}_{q\left(h_{2}\right)}\left(g\left(S_{Y}\right)\right)\right|}{\left|\pi_{-}(H)\right|\left|S_{Y}\right|}+O\left(\varepsilon^{\prime} R\right)$.
Now by Corollary 4.4 , the logarithm is bounded between two constants which depend only on $\kappa$ and $C$.

Proof of Proposition 4.6. Choose $h_{1}=\left(z_{\mathrm{top}}+z_{\mathrm{bot}}\right) / 2, h_{2}=z_{\mathrm{bot}}$. By Lemma 4.1 there exists a horocycle $H^{\prime}$ with $h\left(H^{\prime}\right)=z_{\text {top }}$ so that (7) and (8) hold for $H^{\prime}$. Then

$$
\begin{equation*}
\log \frac{\left|\mathcal{C}_{q\left(h_{1}\right)}\left(f\left(\pi_{-}\left(H^{\prime}\right)\right)\right)\right|\left|\mathcal{C}_{q\left(z_{\mathrm{bot}}\right)}\left(g\left(S_{Y}\right)\right)\right|}{\left|\pi_{-}\left(H^{\prime}\right)\right|\left|S_{Y}\right|}=O(1) \tag{17}
\end{equation*}
$$

By Lemma 4.5, equation (2), and the fact that we coarsen below the horocycle, we see that

$$
\log \frac{\left|\mathcal{C}_{q\left(h_{1}\right)}\left(f\left(\pi_{-}\left(H^{\prime}\right)\right)\right)\right| e^{-B_{X}^{\prime} q\left(h\left(H^{\prime}\right)\right)}}{\left|\pi_{-}\left(H^{\prime}\right)\right| e^{-B_{X} h\left(H^{\prime}\right)}}=O(\varepsilon R)
$$

Since $h\left(H^{\prime}\right)=z_{\text {top }}$, after rearranging we get

$$
\frac{1}{B_{X}^{\prime}} \log \frac{\left|\mathcal{C}_{q\left(h_{1}\right)}\left(f\left(\pi_{-}\left(H^{\prime}\right)\right)\right)\right|}{\left|\pi_{-}\left(H^{\prime}\right)\right|}=q\left(z_{\mathrm{top}}\right)-A z_{\mathrm{top}}+O(\varepsilon R)
$$

Substituting into (17), we get

$$
\begin{equation*}
\frac{1}{B_{X}^{\prime}} \log \frac{\left|\mathcal{C}_{q\left(z_{\mathrm{bot}}\right)}\left(g\left(S_{Y}\right)\right)\right|}{\left|S_{Y}\right|}=A z_{\mathrm{top}}-q\left(z_{\mathrm{top}}\right)=A z_{\mathrm{bot}}-q\left(z_{\mathrm{bot}}\right) \tag{18}
\end{equation*}
$$

where we have used Lemma 4.8 for the last equality. Now Proposition 4.6 follows from (18) and Lemma 4.8.

## 5. Proof of Theorem 2.1

In this section we prove Theorem 2.1. The basic strategy is to show that for most horocycles $H$ intersecting $\phi^{-1}\left(B\left(L^{\prime}\right)\right)$, the image $\phi(H)$ is within $\varepsilon R$ of a horocycle, at least for most of its measure. This argument occupies the first four subsections. Section 5.5 completes the proof in a manner analogous to [EFW12, §5.4].

A key ingredient in our proofs is Lemma 5.19. The reader should think of this "illegal circuit lemma" as a generalization or strengthening of the "quadrilaterals lemma" [EFW12, Lemma 3.1]. The greater generality comes from making weaker assumptions on the paths forming the "legs" of the "quadrilateral." Lemma 5.19 is used much like [EFW12, Lemma 3.1] to show that points along a horocycle must map by $\phi$ to points approximately along a horocycle.

Recommendation to the reader. We recommend that the reader read this section first assuming that, for each $i \in I_{g}$, the map $\phi$ restricted to $U_{i}$ in $B_{i}(R)$ is within $O(\varepsilon R)$ of a $b$-standard map. Under this assumption, the construction of the $\widehat{S}$-graph can be omitted since it suffices to consider only the $S$-graph. The reader will find that proofs in Sections 5.2 and 5.3 simplify somewhat under this hypothesis, but the main arguments in Section 5.4 remain essentially the same.

The primary difficulty that occurs here in dropping the assumption that $\left.\phi_{i}\right|_{U_{i}}$ is within $O(\varepsilon R)$ of a $b$-standard map is in guaranteeing that the map preserves the "divergence conditions" on pairs of vertical geodesics required to control paths by the methods of Section 5.3.
5.1. Constructing the $\widehat{S}$ graph and the $H$-graph. Given a "good enough" horocycle $H$ mostly contained in $\phi^{-1}\left(B\left(L^{\prime}\right)\right)$, in this section we construct a graph that we use to control $\phi(H)$. To begin, we choose constants and make precise the notion of a "good enough" horocycle.

Choosing constants. Let $\phi: X(n) \rightarrow X\left(n^{\prime}\right)$ be a $(\kappa, C)$ quasi-isometry. Choose $\rho_{1} \gg C$, and discretize on scale $\rho_{1}$ as described in Section 3.2. Let $B_{X}$ (resp. $B_{X^{\prime}}$ ) be the branching constant of the resulting graph, and let $B=\max \left\{B_{X}, B_{X^{\prime}}\right\}$. Let $\varepsilon>0$ and $\theta>0$ be constants to be specified below, let $L^{\prime}$ be sufficiently large so that Theorem 2.2 applies, and fix a box $B\left(L^{\prime}\right)$. We call the graph that is the discretization of $B\left(L^{\prime}\right)$ the $S$-graph.

We now apply Theorem 2.2 to $B\left(L^{\prime}\right)$. We fix $\varepsilon \ll \alpha \ll \beta \ll \beta^{\prime} \ll \beta^{\prime \prime}$ and apply the arguments described in Section 4 to each box $B_{i}(R)$ for $i \in I_{g}$, as in the conclusion of Theorem 2.2, to obtain sets $\left(E_{*}^{+}\right)_{i} \subset \partial^{+} X$ and $\left(E_{*}^{-}\right)_{i} \subset \partial_{-} X$.

After replacing the set $U_{i}$ from Theorem 2.2 with a slightly smaller set, we can make sure that for all $(x, y, z) \in U_{i}, x \in\left(E_{*}^{+}\right)_{i}, y \in\left(E_{*}^{-}\right)_{i}$. We still have $\left|U_{i}\right| \geq\left(1-\delta_{0}\right)\left|B_{i}(R)\right|$, where $\delta_{0} \rightarrow 0$ as $\varepsilon \rightarrow 0$ and $\theta \rightarrow 0$. As remarked following Proposition 4.6, we further modify $q_{i}$ so that it satisfies (4.6) with no error term. This makes $\hat{\phi}_{i}$ within $O\left(\varepsilon^{\prime} R\right)$ of $\phi$ where $\varepsilon^{\prime}$ goes to zero as $\varepsilon \rightarrow 0$ and $\theta \rightarrow 0$.

We then choose $0<\eta \ll 1$ such that $\rho_{1} \ll 1 / \eta$. (We mean that for any function $f\left(\rho_{1}\right)$ and any quantity $u$ which is labeled $O(\eta)$ in the argument, $f\left(\rho_{1}\right)$ is much less than 1.)

We then choose $\rho_{2} \gg \rho_{1}$ so that $f\left(\rho_{1}\right) / B^{\rho_{2}} \ll \eta$, where $f\left(\rho_{1}\right)$ is any function of $\rho_{1}$ that arises during the proof. Now pick $\rho_{3}, \rho_{4}, \rho_{5}$ so that $\rho_{2} \ll$ $\rho_{3} \ll \rho_{4} \ll \rho_{5}$.

Choose $0<\delta_{0} \ll 1$ so that $\rho_{5} \ll 1 / \delta_{0}$. The last inequality means that for any function $f\left(\rho_{5}\right)$ and any function $g\left(\delta_{0}\right)$ going to 0 as $\delta_{0} \rightarrow 0$ that arise during the argument, $f\left(\rho_{5}\right) g\left(\delta_{0}\right) \ll 1$. We also assume that $1 / \eta \ll 1 / \delta_{0}$; i.e., for any quantity $u$ labeled $O(\eta)$ and any function of $g\left(\delta_{0}\right)$ going to 0 as $\delta_{0} \rightarrow 0$ that arises during the proof, we have $f\left(\delta_{0}\right) \ll u$.

Recap. We have

$$
C \ll \rho_{1} \ll \rho_{2} \ll \rho_{3} \ll \rho_{4} \ll \rho_{5} \ll\left(1 / \delta_{0}\right) .
$$

Also,

$$
\rho_{1} \ll 1 / \eta \ll 1 / \delta_{0}
$$

and

$$
\rho_{5} \ll \varepsilon^{\prime} R \ll R \ll L^{\prime} .
$$

We do not assume, for example, that $e^{\varepsilon^{\prime} R} \delta_{0}$ is small.
Note. We assume $e^{\varepsilon^{\prime} R} \gg L^{\prime}$. Both of these are consequences of the proof of Theorem 2.2. We always assume that any path we consider has length $O\left(L^{\prime}\right)$, which is much smaller then $e^{\varepsilon^{\prime} R}$.

The sets $U^{\prime}$ and $U$. Let $U_{i}, i \in I_{g}$ be as in the second paragraph of this subsection. Let $U^{\prime}=\bigcup_{i} U_{i}$. Then $\left|U^{\prime c} \cap \phi^{-1}\left(B\left(L^{\prime}\right)\right)\right| \leq 2 \delta_{0}\left|\phi^{-1}\left(B\left(L^{\prime}\right)\right)\right|$.

Let $U^{\prime \prime}$ denote the subset of $\phi^{-1}\left(B\left(L^{\prime}\right)\right)$ that is distance at most $\rho_{1}$ from $U^{\prime}$. Then $\left|U^{\prime \prime}\right| \geq\left|U^{\prime}\right| \geq\left(1-\delta_{0}^{\prime}\right)\left|\phi^{-1}\left(B\left(L^{\prime}\right)\right)\right|$. Also note that since $\rho_{1} \ll \varepsilon^{\prime} R$, for $i \in I_{g}$, the restriction of $\phi$ to $U \cap B_{i}(R)$ is an $\left(\varepsilon^{\prime} R+\rho_{1}, \theta\right)$-almost product map. We define a set $U$ by $U^{c}=N_{\rho_{5}+\rho_{1}}\left(U^{\prime \prime c}\right)$. An elementary covering lemma argument shows that $|U| \geq\left(1-\delta_{0}^{\prime \prime}\right)\left|\phi^{-1}\left(B\left(L^{\prime}\right)\right)\right|$ where $\delta_{0}^{\prime \prime}$ goes to zero with $\delta_{0}^{\prime}$.

Favorable horocycles. We define a horocycle $H$ to be favorable if $H$ does not stay within $\beta^{\prime \prime} R$ of the walls of the $B_{i}(R)$, and also

$$
\left|H \cap U^{\prime}\right| \geq\left(1-\delta_{0}^{\prime \prime \prime}\right) \mid H \cap \phi^{-1}\left(B\left(L^{\prime}\right)\right) .
$$

We call $H$ very favorable if the same holds with $U$ in place of $U^{\prime}$.

Remark. If a horocycle is very favorable, any horocycle within $\rho_{5}$ of it is favorable.

Lemma 5.1. There exists $\hat{\theta}>0$ such that the fraction of $B\left(L^{\prime}\right)$ that is contained in the image of a very favorable $x$-horocycle, and a very favorable $y$-horocycle is at least $(1-\hat{\theta})$. Here $\hat{\theta}$ is a function of $\delta_{0}$ and $\beta^{\prime \prime}$ that goes to 0 as $\delta_{0} \rightarrow 0$ and $\beta^{\prime \prime} \rightarrow 0$.

Proof. This is immediate from the construction.
Notation. For most of the argument, we fix a very favorable horocycle $H$, whose image $\phi(H)$ intersects $B\left(L^{\prime}\right)$. For notational simplicity, we assume that $H$ is a $y$-horocycle. We also fix a favorable horocycle $H_{0}$ so that $\rho_{5} / 2<$ $d\left(H, H_{0}\right)<\rho_{5}$ and $H \subset \operatorname{Sh}\left(H_{0}, \rho_{1}\right)$.

The sets $I_{g}(H), \tilde{B}$ and $U_{*}$. Let $I_{g}(H)$ denote the set of indices $i \in I_{g}$ such that

$$
\begin{equation*}
\left|H \cap U^{\prime} \cap B_{i}(R)\right| \geq\left(1-\delta_{0}^{\prime \prime}\right)\left|H \cap B_{i}(R)\right|>0 \tag{19}
\end{equation*}
$$

Now let $\tilde{B}=\bigcup_{i \in I_{g}(H)} B_{i}(R)$, and let $U_{*}=U^{\prime} \cap \tilde{B}$.
Good and bad boxes. We refer to boxes $B_{i}(R)$ with $i \in I_{g}(H)$ as "good boxes", and to boxes $B_{i}(R)$ intersecting $H$ with $i \in I \backslash I_{g}(H)$ as "bad boxes."

Shadows of $H$ and $\phi(H)$. Let $h_{1}=h(H)-(\alpha+\beta) R$ and $h_{2}=h(H)-$ $\left(\alpha+\beta+\frac{\beta^{\prime}}{2}\right) R$. For each $i \in I_{g}$, we let $h_{0}^{i}$ to be specified below be such that $\left(\alpha+\frac{\beta}{2}\right) R<\left|h(H)-h_{0}^{i}\right|<(\alpha+\beta) R$. For each $B(R)_{i}$ intersecting $H$, we denote $W(H)_{i}=h^{-1}\left(h_{0}\right) \cap \operatorname{Sh}\left(H_{0}, \rho_{1}\right)$. For all bad boxes, we fix $h_{0}^{i}=h(H)-(\alpha+\beta) R$. For good boxes, $h_{0}^{i}$ will be fixed during the proof of Lemma 5.2 below. For each $B_{i}(R)$ intersecting $H$ with $i \in I_{g}$, we let

$$
\hat{W}(H)_{i}=\left\{(x, y, z) \mid x \in \mathcal{C}_{q\left(h_{1}\right)}\left(f\left(\pi_{-}\left(H_{0}\right)\right), y \in \mathcal{C}_{q\left(h_{2}\right)}\left(g\left(S_{Y} \cap Y\right), z=q\left(h_{0}\right)\right\} .\right.\right.
$$

Let $W(H)=\cup_{i \in I} W(H)_{i}$ and $\hat{W}(H)=\cup_{i \in I_{g}} \hat{W}(H)_{i}$. We define these sets in terms of $H_{0}$ not $H$ so as to be able to consider points above $H$ in certain arguments below. Recall $q$ is fixed so that the $O\left(\varepsilon^{\prime} R\right)$ term in Proposition 4.6 is 0 . We let $R_{i}^{\prime}=h(H)-h_{0}^{i}$. We frequently suppress reference to $i$ in our notation for $R^{\prime}$ and $h_{0}$.

Shadow vertices. We now define a set of shadow vertices in the discretization of $X\left(n^{\prime}\right)$. By shifting the discretization, we can assume that $\hat{W}(H)$ contains a $\rho_{1}$ net of $S$-vertices. Every $S$-vertex in $\hat{W}(H)$ is a shadow vertex. If some vertical geodesic going down $\beta^{\prime} R$ from $s$ contains a point of $\phi\left(U^{\prime}\right)$ below $h_{1}$ and $s$ is not within $10 \kappa \varepsilon^{\prime} R$ of an edge of $\hat{W}(H)$, then we call $s$ a good shadow vertex. Any $S$-vertex in $\hat{W}(H)$ that is not a good shadow vertex is a bad shadow vertex. We now add additional shadow vertices, not necessarily in
$\hat{W}(H)$. We also make any $S$ vertex in $N_{\rho_{1}} \phi\left(U_{*}{ }^{c} \cap W(H)\right)$ a bad shadow vertex, even if it is a good shadow vertex by our previous definition. The bad shadow vertices in $N_{\rho_{1}} \phi\left(U_{*}^{c} \cap W(H)\right)$ are not necessarily close to $\hat{W}(H)$, even if they come from good boxes. While these bad shadow vertices are not well controlled, they make up a small proportion of all shadow vertices and so do not interfere with our arguments; see Lemma 5.2.

For either good boxes or bad boxes, the number of shadow vertices coming from $B_{i}$ is proportional to the length of $H \cap B_{i}$. The proportionality constant depends only on $\kappa, C$ and the geometry of the model spaces.

Lemma 5.2. There is a constant $c_{4}\left(\delta_{0}, \varepsilon^{\prime}\right)$ such that, for appropriate choices of $h_{0}^{i}$, only $c_{4}$ fraction of all shadow vertices are bad and $c_{4}$ goes to zero as $\delta_{0}, \varepsilon^{\prime}$ go to zero.

Proof. Bad shadow vertices are defined in two stages. First we have the set $S_{1}$ of vertices in $\hat{W}(H)_{i}$ not within $10 \kappa \varepsilon^{\prime} R$ of an edge and not within $\beta R$ of a point in $\phi\left(U^{\prime}\right)$ below $h_{0}$. That this set has small measure in $\hat{W}(H)_{i}$ follows from two facts. First, the subset within $10 \kappa \varepsilon^{\prime} R$ of the boundary has measure going to zero with $\varepsilon^{\prime}$. Second, if $S_{1}$ contains $\theta$ fraction of the vertices in $\hat{W}(H)_{i}$, then the set of points on geodesics going down $\beta^{\prime} R$ from $S_{1}$ contains $\frac{\theta}{2}$ fraction of the measure of $\widetilde{\mathrm{S}}_{2}^{1}\left(H_{0}\right)$. But $\phi\left(U^{\prime}\right)$ contains $1-c_{4}$ of the measure in $\widetilde{\mathrm{Sl}}_{2}^{1}\left(H_{0}\right)$ by Lemma 4.1, so this implies that $\theta<2 c_{4}$. Since $c_{4}$ goes to zero with $\varepsilon^{\prime}$ and $\delta_{0}$, this implies $\left|S_{1}\right|$ goes to zero with them as well.

In the second stage, we enlarge the set of bad vertices in $\hat{W}(H)$ by adding the set $\left.N_{\rho_{1}} \phi\left(U^{\prime c} \cap W(H)\right)\right)$ to the set of bad vertices. The fraction of shadow vertices coming from bad boxes, being proportional the the fraction of the length of $H$ in bad boxes, clearly goes to zero as $\delta_{0}$ goes to zero. So it suffices to control the size of $\left.N_{\rho_{1}} \phi\left(U_{*}^{c} \cap W(H)_{i}\right)\right)$. To show that $W(H)_{i} \cap U_{*}^{c}$ contains a small fraction of the measure of $W(H)_{i}$, we use the flexibility in our choice of $h_{0}^{i}$. Here we make this flexibility explicit by letting $W(H)_{i}\left(h_{0}^{i}\right)$ be the set of possible $W(H)_{i}$ 's, parametrized by choices of $h_{0}^{i}$. Let $\rho\left(h_{0}^{i}\right)$ be the fraction of $W(H)_{i}\left(h_{0}^{i}\right)$ contained in $W(H)_{i} \cap U_{*}^{c}$. Consider the slab $\mathrm{SL}_{2}^{1}\left(H_{0}\right)$ with $h_{1}=\left(\alpha+\frac{\beta}{2}\right) R$ and $h_{2}=h(H)-(\alpha+2 \beta) R$. Since all $W(H)_{i}\left(h_{0}^{i}\right)$ are contained in $\mathrm{SL}_{2}^{1}(H)$, using Lemma 4.1, we have that

$$
\sum_{h_{0}=\left(\alpha+\frac{\beta}{2}\right) R}^{(\alpha+\beta) R} \rho\left(h_{0}\right) \leq 2 c_{3}\left(\varepsilon^{\prime}, \theta\right)
$$

which implies that for some $h_{0}^{i}$, we have $\rho\left(h_{0}\right)<2 \sqrt{c_{3}}$. We fix some $h_{0}^{i}$ with this property.

Lastly we need to see that this contribution remains small relative to the number of good shadow vertices coming from $B_{i}(R)$. To see this, we use

Corollary 4.4, which implies that $\left|W(H)_{i}\right| \sim\left|\hat{W}(H)_{i}\right|$ for constants depending only on $\kappa$ and $C$. Combined with Proposition 4.3 , this implies that the ratio of $\left.\mid N_{\rho_{1}} \phi\left(U_{*}^{c} \cap W(H)_{i}\right)\right) \mid$ to the number of good vertices in $\hat{W}(H)_{i}$ goes to zero with $\varepsilon^{\prime}$ and $\delta_{0}$.

The $\widehat{S}$-graph. It is convenient to modify the $S$-graph near the image of $H$. For $x \in \partial_{-} X, y \in \partial^{+} X$, and $t \in\left[q\left(h_{0}\right), q\left(h\left(H_{0}\right)\right)-\frac{\rho_{5}}{4}\right]$, let $\gamma_{x, y}(t)=(x, y, t)$ so that $\gamma_{x, y}$ is a vertical geodesic segment of length $q\left(h\left(H_{0}\right)\right)-\frac{\rho_{5}}{4}-q\left(h_{0}\right)$. Let $K_{i}$ be the union of $\gamma_{x, y}$ where $x, y, q\left(h_{0}\right) \in \hat{W}(H)_{i}$. We begin by replacing $K_{i}$ as a subset of the $S$ graph by the disjoint union of the $\gamma_{x, y}$. We then define the $\widehat{S}$ graph by defining a new set of vertices and a new incidence relation on $K_{i}$. For $1 \leq j \leq q\left(h\left(H_{0}\right)\right)-\frac{\rho_{5}}{4}-q\left(h_{0}\right) / \rho_{1}$, let $t_{j}=q_{i}\left(h_{0}\right)+j \rho_{1}$. We introduce prevertices along each $\gamma_{x, y}$ at each $t_{j}$. An irregular $\widehat{S}$-vertex will be an equivalence class of pre-vertices. Each pre-vertex has coordinates $\left\{x, y, t_{j}\right\}$. At each height level $t_{j}$ in $X^{\prime}(n)$, we tile the $y$-horocycle by by disjoint segments $T_{y}$ of length $10 \rho_{1}$. At each height level $q^{-1}\left(t_{j}\right)$ in $X(n)$, we tile each $x$ horocycle by disjoint segments $T_{x}$ of length $10 \kappa^{2} \rho$. (These tilings are best thought of as tilings of horocycles in the corresponding trees or hyperbolic planes.) We identify two pre-vertices if
(1) their projections to the $y t$ plane are in the same $T_{y}$ and
(2) the points $\left(f_{i}^{-1}(x), q_{i}^{-1}\left(t_{j}\right)\right) ;\left(f_{i}^{-1}\left(x^{\prime}\right), q_{i}^{-1}\left(t_{j}^{\prime}\right)\right)$ are in the same $T_{x}$;
(3) $\pi_{-}\left(T_{x}\right) \cap f\left(\left(E_{*}{ }^{-}\right)_{i}\right)$ contains at least half the measure in $\pi_{-}\left(T_{x}\right)$.

Any segment ending at a bad shadow vertex is removed. The $\widehat{S}$-vertices that are $S$-vertices outside of $K_{i}$ are called regular.

The cloud of an $\widehat{S}$-vertex. Note that for any $\widehat{S}$-vertex $v, h(v)$ and the $y$-coordinate of $v$ are well defined. For an irregular $\widehat{S}$-vertex, the $x$ coordinate is "fuzzy." More precisely, the cloud of an $\widehat{S}$-vertex $v$ is the set of points at height $h(v)$ that are on the vertical segments incident to $v$. Then for a regular $\widehat{S}$-vertex, the cloud is essentially a point (it has size $O\left(\rho_{1}\right)$ ), whereas for an irregular $\widehat{S}$-vertex, the cloud can have size $D \varepsilon^{\prime} R$, where $D$ is a constant depending only on $\kappa, C$, and the model geometry.

The set $\hat{\phi}\left(H^{\prime}\right)$. Note that if $H^{\prime}$ is within $\rho_{4}$ of $H$, then the set $\hat{\phi}_{i}\left(H^{\prime}\right)$ consisting of the $\widehat{S}$-vertices $v$ with $q_{i}\left(h\left(H^{\prime}\right)\right)=h(v)+O\left(\rho_{1}\right)$ and the $x$-coordinate of $H^{\prime}$ is $f_{i}^{-1}(v)+O\left(\rho_{1}\right)$ is well defined. (The notation is explained by the fact that for any $v \in \hat{\phi}_{i}\left(H^{\prime}\right), \hat{\phi}_{i}^{-1}(v)$ is within $O\left(\rho_{1}\right)$ of $H^{\prime}$.) We then define $\hat{\phi}\left(H^{\prime}\right)$ to be $\bigcup_{i \in I_{g}} \hat{\phi}_{i}\left(H^{\prime}\right)$.

Lemma 5.3. There exist constants $M_{l}$ and $M_{u}$ depending only on $\kappa, C$ such that for any two $\widehat{S}$-vertices $v_{1}$ and $v_{2}$ in $B\left(L^{\prime}\right)$, the ratio of the number
of vertical geodesics in $B\left(L^{\prime}\right)$ passing through $v_{1}$ to the number of vertical geodesics in $B\left(L^{\prime}\right)$ passing through $v_{2}$ is bounded between $M_{l}$ and $M_{u}$.

Proof. The proof is mainly a computation of the valence of (i.e., the number of vertical paths incident to) an irregular vertex. We give the proof in the DL case first. In the DL case, the valence of a regular vertex is clearly $e^{B_{x}^{\prime} L^{\prime}}$ and we will see that irregular vertices have the same valence. For Sol, the valence of regular vertices can vary by a factor of 2 due to edge effects. This same factor of 2 occurs in the first step of the computation below.

Let $h_{\mathrm{top}}$ denote the height of the top of $B\left(L^{\prime}\right)$, and let $h_{\mathrm{bot}}=h_{\mathrm{top}}-L^{\prime}$ denote the height of the bottom of $B\left(L^{\prime}\right)$. Suppose $v$ is an irregular vertex in $K_{i}$. We can choose a horocycle $H^{\prime}$ so that $v \in \hat{\phi}_{i}\left(H^{\prime}\right)$, hence $q_{i}\left(h\left(H^{\prime}\right)\right)=h(v)$. Note that by definition, $\pi_{-}\left(H^{\prime}\right)$ contains a point in $E_{* * *}$. Then the number of paths going up from $v$ to the height $h_{\text {top }}$ is $\approx e^{B_{X}^{\prime}\left(h_{\text {top }}-h(v)\right)}$. Now the number of paths going down from $v$ to $\hat{W}(H)$ (at height $h_{0}$ ) is

$$
\begin{array}{ll}
\approx\left|\mathcal{C}_{q_{i}\left(h_{0}\right)}\left(f_{i}\left(\pi_{-}\left(H^{\prime}\right)\right)\right)\right| e^{-B_{X}^{\prime} q_{i}\left(h_{0}\right)} & \text { by }(2), \\
\approx\left|\mathcal{C}_{q_{i}\left(h_{0}\right)}\left(f_{i}\left(\pi_{-}\left(H^{\prime}\right)\right)\right)\right| e^{-B_{X} h_{0}} \frac{\left|\mathcal{C}_{q_{i}\left(h_{2}\right)}\left(g_{i}\left(S_{Y} \cap S\right)\right)\right|}{\left|S_{Y}\right|} & \text { by Proposition 4.6, } \\
\approx\left|\pi_{-}\left(H^{\prime}\right)\right| e^{-B_{X} h_{0}} & \text { by Corollary 4.4, } \\
\approx e^{B_{X}\left(h\left(H^{\prime}\right)-h_{0}\right)} & \text { by (2), } \\
=e^{B_{X}^{\prime}\left(h(v)-q_{i}\left(h_{0}\right)\right)} & \text { by Proposition 4.6. }
\end{array}
$$

Thus the total number of paths going down from $v$ to $h_{\mathrm{bot}}$ is $\approx e^{B_{X}^{\prime}\left(h(v)-h_{\mathrm{bot}}\right)}$, and thus the total number of paths incident to $v$ is $\approx e^{B_{X}^{\prime} L}$ as required.

The $H$-graph. An irregular $\widehat{S}$-vertex $v \in K_{i}$ is an $H$-vertex if and only if $q_{i}(h(H))=h(v)+O\left(\rho_{1}\right)$ and the $x$-coordinate of $H$ is $f_{i}^{-1}(v)+O\left(\rho_{1}\right)$. These vertices are called "good." (Note that for any good $H$-vertex $v \in K_{i}, \hat{\phi}_{i}^{-1}(v)$ is within $O\left(\rho_{1}\right)$ of $H$.)

We also declare the "bad" $H$-vertices to be the bad shadow vertices. These are always regular $\widehat{S}$-vertices. The "good" and "bad" vertices thus defined comprise all the vertices of the $H$-graph. An edge of the $H$-graph is a vertical path in the $\widehat{S}$-graph that either connects two $H$-vertices or connects an $H$-vertex to the top or bottom of the box $B\left(L^{\prime}\right)$. An edge with one endpoint at the top or bottom of the box is called an leaf edge.

We will count edges with multiplicity. An edge has multiplicity equal to the number of vertical paths in the $\widehat{S}$-graph that contain it.

Notation. We denote the $H$-graph by $\mathcal{G}(H)$. Let $\mathcal{V}$ denote the set of vertices of $\mathcal{G}(H)$, and let $\mathcal{E}$ denote the set of edges. Let $\mathcal{V}_{1} \subset \mathcal{V}$ denote the set of "good" vertices as defined above. We call an $H$ vertex $y$ oriented (resp.
$x$ oriented) if the horocycle segment containing it is a horocycle (resp. $x$ horocycle). We also refer to an orientation for $\widehat{S}$ vertices, which is just the orientation of $H$ vertices in the same box.

Lemma 5.4. The valence of $H$ vertices is bounded between two constants $M_{l}$ and $M_{u}$ depending only on $\kappa, C$ and the model geometries. Furthermore $\left|\mathcal{V}_{1}\right| \geq\left(1-c_{5}\right)|\mathcal{V}|$, where $c_{5}=c_{5}\left(\varepsilon^{\prime}, \delta_{0}\right)$ goes to zero with $\delta_{0} \rightarrow 0$ and $\varepsilon^{\prime} \rightarrow 0$.

Proof. The first statement of the lemma is immediate from Lemma 5.3. To show the final claim, let $F$ denote the set of vertical paths passing through the good shadow vertices. By definition, every such path is incident to a good $H$-vertex, and also every vertical path incident to a good $H$-vertex belongs to $F$. Thus $F$ is also equal to the set of vertical paths incident to good shadow vertices. Let $A$ denote the set of good shadow vertices. Since the valence of each $H$-vertex is between $M_{l}$ and $M_{u}$ times the valence of each good shadow vertex, we have $M_{l}|A| \leq|F| \leq M_{u}|A|$ and $M_{l}\left|\mathcal{V}_{1}\right| \leq|F| \leq M_{u}\left|\mathcal{V}_{1}\right|$. Thus, $\left|\mathcal{V}_{1}\right| \geq\left(M_{l} / M_{u}\right)^{2}|A|$. But by Lemma 5.2, $\left|\mathcal{V} \backslash \mathcal{V}_{1}\right| \leq c_{4}|A|$, where $c_{4}\left(\varepsilon^{\prime}, \delta_{0}\right) \rightarrow 0$ as $\varepsilon^{\prime} \rightarrow 0$ and $\delta_{0} \rightarrow 0$. Thus, $\left|\mathcal{V} \backslash \mathcal{V}_{1}\right| \leq\left(M_{l} / M_{u}\right)^{2} c_{4}\left|\mathcal{V}_{1}\right|$.
5.2. Averaging over the H-graph. In order to make our geometric arguments in the next section, we need to show that the paths and configurations we consider in the $H$ graph do not involve any bad shadow vertices; i.e., to show that these paths and configurations only come near the horocycle in the good set, at places where we have control over the map $\phi$. In this section we use multiple applications of the Vitali covering lemma in order to guarantee that "most" configurations in the $H$-graph avoid bad shadow vertices. A key fact is that while neither Sol nor $\mathrm{DL}(m, m)$ satisfy the sort of doubling condition needed for the Vitali covering lemma, the space of vertical geodesics does.

Choose $0<\theta_{3}<\theta_{4} \ll 1$. The $\theta$ 's will be functions of $\delta_{0}$ that go to 0 as $\delta_{0} \rightarrow 0$.

Definition 5.5 (Good Edges). The following defines sets of "good" edges. See also Definition 5.6.
$\mathcal{E}_{1}$ : Either connects two vertices in $\mathcal{V}_{1}$ or is a leaf edge based on a vertex of $\mathcal{V}_{1}$.
$\mathcal{E}_{3}$ : An $\mathcal{E}_{1}$ edge $e$ such that for for all $\widehat{S}$-vertices $x \in e, 1-\theta_{3}$ fraction of the edges (forward) branching at $x$ are in $\mathcal{E}_{1}$. (Note that $x$ is not supposed to be a vertex of the $H$-graph.)
$\mathcal{E}_{4}$ : An $\mathcal{E}_{3}$ edge such that for any $\widehat{S}$-vertex $x \in e, 1-\theta_{4}$ fraction of the edges reverse branching from $x$ are in $\mathcal{E}_{1}$.

Remark. There are $\mathcal{E}_{2}$ edges, they will be defined below in Section 5.3.
Choose $1 \gg \nu_{3}>\nu_{2}>0$. The $\nu$ 's will be functions of $\delta_{0}$ that tend to 0 as $\delta_{0} \rightarrow 0$.

Definition 5.6 (Good Vertices). The following defines sets of "good" vertices. See also Definition 5.5.
$\mathcal{V}_{1}$ : The set of "good" vertices as defined in the previous section.
$\mathcal{V}_{2}$ : In $\mathcal{V}_{1}$ and $1-\nu_{2}$ fraction of the outgoing edges are in $\mathcal{E}_{1}$.
$\mathcal{V}_{3}$ : In $\mathcal{V}_{2}$ and $1-\nu_{3}$ fraction of the outgoing edges are in $\mathcal{E}_{4}$.
$\mathcal{V}_{4}$ : In $\mathcal{V}_{3}$ and is not a strange vertex (see Definition 5.13).
Lemma 5.7. If $L^{\prime} \gg L$, we can choose a horocycle $H$ such that for the $H$-graph $\mathcal{G}(H), 1-\delta_{1}$ fraction of vertices are in $\mathcal{V}_{1}$. Here, $\delta_{1}$ is a function of $\delta_{0}$ that tends to 0 as $\delta_{0} \rightarrow 0$.

Proof. Note that $\phi^{-1}\left(B\left(L^{\prime}\right)\right)$ has small boundary area (compared to the volume). Now tile $\phi^{-1}\left(B\left(L^{\prime}\right)\right)$ by boxes $B(L)$. Since $L^{\prime} \gg L$, most boxes are completely in the interior of $\phi^{-1}\left(B\left(L^{\prime}\right)\right)$.

Let $\mathcal{U}$ denote the set where we know the map is locally standard (but could be right side up or upside down). Note that for every box $B(L),|\mathcal{U} \cap B(L)| \geq$ $0.999|B(L)|$.

This implies that for most $H$,

$$
\left|H \cap \phi^{-1}\left(B\left(L^{\prime}\right)\right) \cap \mathcal{U}\right| \geq 0.99\left|H \cap \phi^{-1}\left(B\left(L^{\prime}\right)\right)\right| .
$$

Then for such $H, \mathcal{V}_{1}$, which consists of vertices on $\phi(H) \cap B\left(L^{\prime}\right) \cap \phi(\mathcal{U})$, satisfies the conditions of the lemma.

We now fix $H$ such that Lemma 5.7 holds.
Lemma 5.8. At least $1-\varepsilon_{1}$ fraction of the edges of $\mathcal{G}(H)$ are in $\mathcal{E}_{1}$. Here, $\varepsilon_{1}$ is a function of $\delta_{0}$ that tends to 0 as $\delta_{0} \rightarrow 0$.

Proof. Recall that $m \leq M(v) \leq M$, where $M(v)$ is the degree of $v$. This implies that

$$
\frac{1}{m} \leq \frac{|\mathcal{V}(H)|}{|\mathcal{E}(H)|} \leq \frac{1}{M} .
$$

Since each edge not in $\mathcal{E}_{1}$ must be quasi-incident on a vertex not in $\mathcal{V}_{1}$ and each vertex is incident to at most $M$ edges, we have

$$
\left|\mathcal{E}_{1}^{c}\right| \leq 2 M\left|\mathcal{V}_{1}^{c}\right| .
$$

Combined with equation (5.2) this implies

$$
\frac{\left|\mathcal{E}_{1}^{c}\right|}{|\mathcal{E}(H)|} \leq 2 \frac{M}{m} \frac{\left|\mathcal{V}_{1}^{c}\right|}{|\mathcal{V}(H)|}
$$

Thus the lemma follows from Lemma 5.7.
Lemma 5.9. At least $1-\delta_{2}$ fraction of the vertices of $\mathcal{G}(H)$ are in $\mathcal{V}_{2}$. Here, $\delta_{2}$ is a function of $\delta_{0}$ that tends to 0 as $\delta_{0} \rightarrow 0$.

Proof. This follows immediately from Lemma 5.8.

Lemma 5.10. At least $1-\varepsilon_{3}$ fraction of the edges of $\mathcal{G}(H)$ are in $\mathcal{E}_{3}$. Here, $\varepsilon_{3}$ is a function of $\delta_{0}$ that tends to 0 as $\delta_{0} \rightarrow 0$.

Proof. In view of Lemma 5.9, it enough to prove that for any $v \in \mathcal{V}_{2}$, almost all the edges outgoing from $v$ belong to $\mathcal{E}_{3}$.

Suppose $v \in \mathcal{V}_{2}$. Let $\mathcal{E}(v)$ denote all the edges that are incident to $v$. We know that most edges in $\mathcal{E}(v)$ belong to $\mathcal{E}_{2}$; i.e.,

$$
\begin{equation*}
\left|\mathcal{E}_{2}^{c} \cap \mathcal{E}(v)\right| \leq \delta_{2}|\mathcal{E}(v)| . \tag{20}
\end{equation*}
$$

Let $A_{v}=\mathcal{E}(v) \cap \mathcal{E}_{3}^{c}$ denote the edges outgoing from $v$ that are not in $\mathcal{E}_{3}$. We know that for any $e \in A_{v}$, there exists $x \in e$ such that at least $\theta_{3}$ of the edges branching from $e$ at $x$ are not in $\mathcal{E}_{1}$. Thus there exists a neighborhood $U$ of $e$ such that

$$
\left|\mathcal{E}_{2}^{c} \cap U \cap \mathcal{E}(v)\right| \geq \theta_{3}|U \cap \mathcal{E}(v)|
$$

We thus get a cover of $A_{v}$ by $U$ 's. Then by Vitali's covering lemma, there exists disjoint $U_{j}$ such that

$$
\sum_{j=1}\left|U_{j}\right| \geq \frac{1}{2}\left|A_{v}\right| .
$$

Thus,

$$
\left|A_{v}\right| \leq 2 \sum\left|U_{j}\right| \leq \frac{2}{\theta_{3}} \sum\left|U_{j} \cap \mathcal{E}_{2}^{c} \cap \mathcal{E}(v)\right| \leq \frac{2}{\theta_{3}}\left|\mathcal{E}_{2}^{c} \cap \mathcal{E}(v)\right| .
$$

Then, by (20),

$$
\left|A_{v}\right| \leq \frac{2 \delta_{2}}{\theta_{3}}|\mathcal{E}(v)| .
$$

We now choose $\theta_{3}=\varepsilon_{3}=\sqrt{2 \delta_{2}}$.
Lemma 5.11. At least $1-\varepsilon_{4}$ fraction of the edges of $\mathcal{G}(H)$ are in $\mathcal{E}_{4}$. Here, $\varepsilon_{4}$ is a function of $\delta_{0}$ that tends to 0 as $\delta_{0} \rightarrow 0$.

Proof. It follows immediately from Lemma 5.10 that $1-2 \varepsilon_{3}$ proportion of the for nonleaf edges have the reverse branching property.

Let $\alpha=\varepsilon_{1}^{1 / 6}$. If the proportion of the leaf edges is at most $\alpha$, we are already done (with $\varepsilon_{4}=2 \varepsilon_{3}+\alpha$ ). Thus we may assume that the proportion of leaf edges is at least $\alpha$.

Let $Y$ be the set of all vertical paths in $B(L)$ going from top to bottom, and let $Y^{\prime} \subset Y$ be the subset consisting of paths that pass through a vertex not in $\mathcal{V}_{1}$. Let $D(\gamma)=1$ if $\gamma \in Y^{\prime}$ and $D(\gamma)=0$ otherwise. By Lemma 5.8, we have

$$
\begin{equation*}
\sum_{\gamma \in Y} D(\gamma) \leq 2 \varepsilon_{1}|\mathcal{E}(H)| \tag{21}
\end{equation*}
$$

From (21),

$$
\sum_{\gamma \in Y} D(\gamma) \leq \varepsilon_{1}|\mathcal{E}(H)| \leq \frac{\varepsilon_{1}}{\alpha}\left|\mathcal{E}_{\text {leaf }}\right|
$$

where $\mathcal{E}_{\text {leaf }} \subset \mathcal{E}(H)$ denotes the set of leaf edges. For a point $v \in \partial B(R)$, let $Y_{v}$ denote the set of geodesics emanating from $v$. We get

$$
\sum_{v \in \partial B(R)} \sum_{\gamma \in Y_{v}} D(\gamma) \leq \sum_{v \in \partial B(R)} \frac{\varepsilon_{1}}{\alpha}\left|\mathcal{E}_{\text {leaf }}(v)\right|
$$

where $\mathcal{E}_{\text {leaf }}(v)$ denotes the set of leaf edges emanating from $v$. Let $\theta^{\prime}=\varepsilon_{1}^{2 / 3}$, and let

$$
P=\left\{v \in \partial B(R) \quad: \quad \sum_{\gamma \in Y_{v}} D(\gamma)>\theta^{\prime}\left|\mathcal{E}_{\text {leaf }}(v)\right|\right\}
$$

Note that

$$
\sum_{v \in P}\left|\mathcal{E}_{\text {leaf }}(v)\right| \leq \sum_{v \in P} \frac{1}{\theta^{\prime}} \sum_{\gamma \in Y_{v}} D(\gamma) \leq \frac{1}{\theta^{\prime}} \sum_{v \in Y} D(\gamma) \leq \frac{\varepsilon_{1}}{\alpha \theta^{\prime}}\left|\mathcal{E}_{\text {leaf }}\right|
$$

Thus, since we choose $\alpha$ and $\theta^{\prime}$ so that $\frac{\varepsilon_{1}}{\alpha \theta^{\prime}} \ll 1$, it is enough to prove that for $v \notin P$, most of the edges in $\mathcal{E}_{\text {leaf }}(v)$ are in $\mathcal{E}_{4}$.

Now assume $v \notin P$. Thus, we have

$$
\sum_{\gamma \in Y_{v}} D(\gamma)<\theta^{\prime}\left|\mathcal{E}_{\text {leaf }}(v)\right|
$$

Choose $\theta_{4}=\varepsilon_{1}^{1 / 12}$. Let $A_{v}=\mathcal{E}_{\text {leaf }}(v) \cap \mathcal{E}_{4}^{c}$ denote the leaf edges outgoing from $v$ that are not in $\mathcal{E}_{4}$. We know that for any $e \in A_{v}$, there exists $x \in e$ such that at least $\theta_{4}$ of the edges branching from $e$ at $x$ are not in $\mathcal{E}_{2}$. Thus there exists a neighborhood $U \subset Y_{v}$ with $e \in U$ such that

$$
\left|\mathcal{E}_{2}^{c} \cap U\right| \geq \theta_{4}|U|
$$

Hence, using the definition of $\mathcal{E}_{2}$,

$$
\sum_{\gamma \in U} D(\gamma) \geq \theta_{2} \theta_{4}|U|
$$

We thus get a cover of $A_{v}$ by $U^{\prime}$ s. Then by Vitali, there exists disjoint $U_{j}$ such that

$$
\sum_{j=1}\left|U_{j}\right| \geq \frac{1}{2}\left|A_{v}\right|
$$

Thus,

$$
\left|A_{v}\right| \leq 2 \sum_{j}\left|U_{j}\right| \leq \frac{2}{\theta_{2} \theta_{4}} \sum_{j} \sum_{\gamma \in U_{j}} D(\gamma) \leq \frac{2}{\theta_{2} \theta_{4}} \sum_{\gamma \in Y_{v}} D(\gamma) \leq \frac{2 \theta^{\prime}}{\theta_{2} \theta_{4}}\left|\mathcal{E}_{\text {leaf }}(v)\right|
$$

Since $\theta_{2}=\varepsilon_{1}^{1 / 2}, \frac{2 \theta^{\prime}}{\theta_{2} \theta_{4}}=\varepsilon_{1}^{\frac{1}{12}}$ and the lemma follows.

Lemma 5.12. At least $1-\delta_{4}$ fraction of the vertices of $\mathcal{G}(H)$ are in $\mathcal{V}_{3}$. Here, $\delta_{4}$ is a function of $\delta_{0}$ that tends to 0 as $\delta_{0} \rightarrow 0$.

Proof. This follows from Lemma 5.11.
Let $H_{*}$ be an horocycle intersecting $B\left(L^{\prime}\right)$. We say that an $S$-vertex on $w$ on $H_{*}$ is marked by a $\mathcal{V}_{1} H$-vertex $v$ if the cloud of $v$ contains a point of $H_{*}$, and also $h(v)=h\left(H_{*}\right)+O\left(\rho_{2}\right)$, and also the coordinates of $v$ and $w$ along $H_{*}$ must agree up to $O\left(\rho_{2}\right)$. (In particular the orientation of $v$ must be such that the coordinate of $v$ along $H_{*}$ is not "fuzzy.")

Definition 5.13 (Strange Vertex). An $H$-vertex $v \in \mathcal{V}_{3}$ is called strange if there is an horizontal segment (i.e., piece of horocycle) $K$ marked by $v$ such that more then $1-\nu_{4}$ fraction of the $S$-vertices on $K$ are marked by $H$-vertices that are $\mathcal{V}_{1}$ but not in $\mathcal{V}_{3}$.

Lemma 5.14. At least $1-\delta_{6}$ fraction of the vertices of $\mathcal{G}(H)$ are in $\mathcal{V}_{4}$ (i.e are in $\mathcal{V}_{3}$ and not strange). Here, $\delta_{6}$ is a function of $\delta_{0}$ that tends to 0 as $\delta_{0} \rightarrow 0$.

Proof. Let $v_{1}, \ldots, v_{m}$ be the strange vertices, and let $K_{1}, \ldots, K_{m}$ be horocycle segments marked by the strange vertices. The $K_{i}$ are not quite uniquely defined, but we address this issue below.

Note that the number of $H$-vertices that can mark a given $S$-vertex is $O\left(\rho_{2}\right)$. Indeed, any two such vertices must be within $O\left(\varepsilon^{\prime} R\right)$ of each other, which means that they must have come from the same good box, which implies that heights and their transverse coordinates must agree. (Recall that the vertices that come from near the edges of a good box are automatically not in $\mathcal{V}_{1}$.)

The same argument shows that one can choose the horocycle segments $K_{i}$ so that for $i \neq j, d\left(K_{i}, K_{j}\right)>3 D \varepsilon^{\prime} R$. Now we can apply the Vitali covering lemma to the $K_{i}$. This lemma applies since each $K_{i}$ is one-dimensional and the different $K_{i}$ do not interact with each other. Also, the density of the $\mathcal{V}_{1}$ vertices that are not in $\mathcal{V}_{3}$ is small by Lemma 5.12. This implies that the strange vertices are a small fraction of all the vertices.

### 5.3. Circuits.

The projection $\pi_{H}$ and the function $\rho_{H}(\cdot, \cdot)$. Let $H$ be a horocycle. Let $\pi_{H}: \mathrm{Sol} \rightarrow \mathbb{H}^{2}$ denote the orthogonal projection to the hyperplane orthogonal to $H$. We let $\rho_{H}(p, q)=\left(\pi_{H}(p) \mid \pi_{H}(q)\right)_{\pi_{H}(H)}$ be the Gromov product of $\pi_{H}(p)$ and $\pi_{H}(q)$ with respect to $\pi_{H}(H)$ in $\mathbb{H}^{2}$. Recall that for three points $x, y, z$ in a metric space $X$, the Gromov product is defined as

$$
(y \mid z)_{x}=\frac{1}{2}\left\{d_{X}(x, y)+d_{X}(x, z)-d_{X}(z, y)\right\} .
$$

Let $\gamma_{y z}$ be the geodesic joining $y$ to $z$. In a $\delta$-hyperbolic space, $X$ satisfies

$$
d_{X}\left(\gamma_{y z}, x\right)-\delta \leq(y \mid z)_{x} \leq d_{X}\left(\gamma_{y z}, x\right)
$$

see, e.g., [GdlH90, Lemma 2.17]. We note the following properties of $\rho_{H}$.
Lemma 5.15. (i) Suppose $d\left(p^{\prime}, p\right) \ll d(p, H), d\left(q^{\prime}, q\right) \ll d(q, H)$, and $\rho_{H}(p, q) \ll \min (d(p, H), d(q, H))$. Then,

$$
\rho_{H}(p, q) \approx \rho_{H}\left(p^{\prime}, q^{\prime}\right)
$$

(ii) Suppose $h\left(p^{\prime}\right)<h(p), h\left(q^{\prime}\right)<h(q)$, the points $p$ and $p^{\prime}$ can be connected by a vertical geodesic, and the same for the points $q$ and $q^{\prime}$. Suppose also $d(p, H) \gg \rho_{H}(p, q)$ and $d(q, H) \gg \rho_{H}(p, q)$. Then,

$$
\rho_{H}(p, q) \approx \rho_{H}\left(p^{\prime}, q^{\prime}\right)
$$

(iii) If $\rho_{H}(p, q)>s$ and $\rho_{H}\left(q, q^{\prime}\right)>s$, then $\rho_{H}\left(p, q^{\prime}\right)>s$ (up to a small error).

Proof. The statements (i), (ii), and (iii) are standard hyperbolic geometry. In particular, (iii) follows immediately from the "thin triangle" property.

In the following lemma, the horocycle $H$ is assumed to be a $y$ horocycle. An analogous lemma, with a few sign changes, holds for $x$ horocycles.

Lemma 5.16. Suppose $p, q \in X(n)$ are connected by a path $\hat{\gamma}$ such that

$$
\begin{equation*}
h(x) \leq h(H)-\rho_{4} \text { for all } x \in \gamma . \tag{22}
\end{equation*}
$$

Further, assume the initial segments of $\gamma$ at both $p$ and $q$ are vertical geodesics going down for length at least $\varepsilon^{\prime} R$, that $\gamma$ stays below $h(H)-R^{\prime}$ except on these initial segments, and that the length of $\gamma$ is less than $e^{\varepsilon^{\prime} R}$. Then, $\rho_{H}(p, q)$ $>\Omega\left(\rho_{4}\right)$.

Proof. This is standard hyperbolic geometry applied to $\pi_{H}(\gamma)$.
Notation. An $\mathcal{E}_{2}$ edge is a monotone vertical path in the $\widehat{S}$-graph that is a subset of an $\mathcal{E}_{1}$ edge (or possibly a subset the extension of an $\mathcal{E}_{1}$ edge by at most $\rho_{4}$ at each end).

Lemma 5.17. Suppose $\gamma=\overline{p_{0} q_{0}}$ is an $\mathcal{E}_{2}$ edge going up from an $x$-oriented irregular $\widehat{S}$-vertex (or going down from a $y$-oriented irregular $\widehat{S}$-vertex). Suppose $p \in \gamma$ is within the same $B_{i}(R)$ as $p_{0}$, and $q \in \gamma$ is within the same $B_{i^{\prime}}(R)$ as $q_{0}$ and $d\left(p, p_{0}\right)$ and $d\left(q, q_{0}\right)$ is at least $10 \varepsilon^{\prime} R$. Then the following hold.
(i) Except near its endpoints, $\gamma$ never passes through any irregular $\widehat{S}$-vertices.

In other words, in its interior, $\gamma$ never comes within $R^{\prime}$ of a good $H$ vertex.
(ii) We have $\rho_{H}\left(\hat{\phi}^{-1}(p), \hat{\phi}^{-1}(q)\right)>\Omega\left(\rho_{4}\right)$.

Remark. In the above, $\rho_{H}\left(\hat{\phi}^{-1}(p), \hat{\phi}^{-1}(q)\right)$ is well defined since for an $\widehat{S}$-vertex $v, \pi_{H}\left(\hat{\phi}^{-1}(v)\right)$ is well defined (even though $\hat{\phi}^{-1}(v)$ may not be).

Informal outline of proof. We first outline the proof. We then give the full argument. Consider $\phi^{-1}(\gamma)$. Note that below height $h(H)-R^{\prime}, \phi^{-1}(\gamma)$ cannot move transverse to $H$ because it is of length at most $O(L)$. Because of this, whenever $\gamma$ attempts to cross above height $h(H)-R^{\prime}$ it must does so in the image of $W(H)$. Consider the point $q^{\prime}$ where it does so. Since $\gamma$ cannot hit a bad shadow vertex, $q^{\prime}$ must be essentially in $U \cap B_{i}(R) \cap W(H)$. But then, by the definition of the $\widehat{S}$-graph, $\gamma$ must hit an $H$-vertex. Thus, $q^{\prime}$ is near the endpoint of $\gamma$, and thus (i) holds. Now (ii) follows from Lemma 5.16 since we know that $\phi^{-1}(\gamma)$ has not passed above height $h(H)-R^{\prime}$ except near the endpoints.

Proof. Let $p_{1}$ be the first place where $\gamma$ hits $\hat{W}(H)$. Then, since $\gamma$ cannot hit a bad shadow vertex, there exists $p_{1}^{\prime} \in U_{*} \cap W(H)$ such that $\hat{\phi}\left(p_{1}^{\prime}\right)=p_{1}$ and $d\left(\phi^{-1}\left(p_{1}\right), \hat{\phi}^{-1}\left(p_{1}\right)\right)=O\left(\varepsilon^{\prime} R\right)$. Note that $p_{1}^{\prime}$ and $\phi^{-1}\left(p_{1}\right)$ are both $\Omega\left(\varepsilon^{\prime} R\right)$ from the sides of $W(H)$.

Let $p_{2}^{\prime}$ be the next point after $p_{1}^{\prime}$ when $\phi^{-1}(\gamma)$ intersects $\tilde{B} \cap\{x: h(x)=$ $\left.h(H)-R^{\prime}\right\}$ at $\phi^{-1}\left(p_{2}\right)$. Since $\gamma$ is an $\mathcal{E}_{2}$ edge and, in particular, a vertical geodesic, we know $d\left(p_{1}^{\prime}, p_{2}^{\prime}\right)$ is $\Omega(\beta R)$. By the choice of $p_{2}^{\prime}$ and the definition of $\mathcal{E}_{2}$ edge, $\phi^{-1} \gamma$ never hits a shadow vertex between $p_{1}^{\prime}$ and $p_{2}^{\prime}$. This fact and the fact that $\left|\phi^{-1}(\gamma)\right|<O(L)$ imply that $p_{2}^{\prime}$ must be in $W(H)$. Since $\gamma$ is $\mathcal{E}_{2}, p_{2}^{\prime}$ is not a bad shadow vertex and, in particular, is away from the edge of $W(H)$. Together, this implies that $p_{2}^{\prime}$ is in $W(H) \cap \tilde{B}$ and that the continuation of $\gamma$ past $p_{2}=\hat{\phi}\left(p_{2}^{\prime}\right)$ must, by the definition of the $\widehat{S}$ and $H$ graphs, hit an $H$-vertex. Since $\gamma$ is an $\mathcal{E}_{2}$ edge and does not contain good vertices in its interior, this implies that $p_{2}$ and $q_{0}$ are in the same box and that the segment from $p_{2}$ to $q_{0}$ contains $q$. Now by Lemma 5.15,

$$
\rho_{H}\left(\hat{\phi}^{-1}(p), \hat{\phi}^{-1}(q)\right)=\rho_{H}\left(\hat{\phi}^{-1}\left(p_{1}\right), \hat{\phi}^{-1}\left(p_{2}\right)\right) \approx \rho_{H}\left(\phi^{-1}\left(p_{1}\right), \phi^{-1}\left(p_{2}\right)\right) \geq \Omega\left(\rho_{4}\right) .
$$

Lemma 5.18. Suppose $\overline{p_{0} q_{0}}$ is an $\mathcal{E}_{2}$ edge (which goes up from an $x$ oriented vertex and down from a y-oriented vertex), $\rho_{3} \gg s \gg \rho_{1}$, and $p$ (resp. $q$ ) is on $\gamma$ distance $s$ away from $p_{0}$ (resp. from $q_{0}$ ). Then there exists a horocycle $H^{\prime}$ such that $p$ and $q$ are within $O\left(\rho_{1}\right)$ of $\hat{\phi}\left(H^{\prime}\right)$.

Proof. Choose points $p^{\prime}$ and $q^{\prime}$ on $\overline{p_{0} q_{0}}$ close to where $\overline{p_{0} q_{0}}$ enters the respective good boxes. Applying Lemma 5.17 we see that $\rho_{H}\left(\hat{\phi}^{-1}\left(p^{\prime}\right), \hat{\phi}^{-1}\left(q^{\prime}\right)\right)>$ $\Omega\left(\rho_{4}\right)$. By the usual $\delta$-thin triangle properties, this implies that the geodesic segments $\pi_{H}\left(\hat{\phi}^{-1}(p)\right) \pi_{H}(H)$ and $\pi_{H}\left(\hat{\phi}^{-1}(q)\right) \pi_{H}(H)$ stay close for roughly $\rho_{4}$ units from $\pi_{H}(H)$. Since $d\left(\hat{\phi}^{-1}(p), H\right) \ll \rho_{3}<\rho_{4}$ and similarly for $\hat{\phi}^{-1}(q)$, this implies that $\pi_{H}\left(\hat{\phi}^{-1}(p)\right)$ and $\pi_{H}\left(\hat{\phi}^{-1}(q)\right)$ are within $2 \delta$ of the same vertical geodesic through the point $\pi_{H}(H)$. But since they are at the same height, this implies that $\pi_{H}\left(\hat{\phi}^{-1}(p)\right)=\pi_{H}\left(\hat{\phi}^{-1}(q)\right)$.

Suppose $H^{\prime}$ is a horocycle obtained by moving up less than $\rho_{3}$ from $H$. Recall that the set $\hat{\phi}\left(H^{\prime}\right)$ is a well-defined subset of the $\widehat{S}$-graph (see Section 5.1). We always assume that $\hat{\phi}\left(H^{\prime}\right)$ runs along vertices in the $\widehat{S}$-graph (or else project it). By Lemma 5.18, given any collection of $\mathcal{E}_{2}$ edges with (some) endpoints on $H$, we may replace them with $\mathcal{E}_{2}$ edges with (some) endpoints on $H^{\prime}$.

Lemma 5.19 (Illegal Circuit). Suppose $n$ is some finite even integer that is not too large (we will use $n=4$ and $n=6$ ), and for $0 \leq i \leq n-1, p_{i}$ are $\widehat{S}$-vertices. Also suppose that for $0 \leq i \leq n-1, \overline{p_{i-1} p_{i}}$ are subsets of $\mathcal{E}_{2}$ edges, where $i-1$ is considered $\bmod n$. For $1 \leq i \leq n$, let $r^{ \pm}\left(p_{i}\right)$ denote the maximum distance the geodesic $\overline{p_{i \pm 1} p_{i}}$ can be continued beyond $p_{i}$ while remaining a subset of an $\mathcal{E}_{2}$ edge, and let $r\left(p_{i}\right)=\max \left(r^{+}\left(p_{i}\right), r^{-}\left(p_{i}\right)\right)$.

Suppose there is an index $k$ such that $r\left(p_{k}\right) \ll \rho_{4}$, and for all $i \neq k$, $r\left(p_{i}\right)>r\left(p_{k}\right)+2 \rho_{1}$. Then $\overline{p_{k-1} p_{k}}$ and $\overline{p_{k} p_{k+1}}$ cannot have only the point $p_{k}$ in common.

Remark. Roughly, the point of the lemma is that one cannot find a loop of length $O(L)$ through a point on the horocycle that begins by going up in two distinct directions unless the loop comes back to the original horocycle.

Proof. Without loss of generality, $k=0$. Let $H^{\prime}$ be the horocycle passing thorough $\hat{\phi}^{-1}\left(p_{0}\right)$. By Lemma 5.18 and the discussion following, we can consider $H^{\prime}$ in place of $H$; namely, we can replace all $H$ vertices that occur in our arguments with vertices in $H^{\prime}$. Let $p_{i-1}^{+}$be the first time when $\overline{p_{i-1} p_{i}}$ leaves $\hat{\phi}(\tilde{B} \cap W(H))$, and let $p_{i-1}^{-}$be the last time when $\overline{p_{i-1} p_{i}}$ enters $\hat{\phi}(\tilde{B} \cap W(H))$ (so $d\left(p_{i-1}, p_{i-1}^{+}\right) \approx R^{\prime} \leq R$ and $d\left(p_{i}^{-}, p_{i}\right) \approx R^{\prime} \leq R$ ). By applying Lemma 5.17 to each segment $\overline{p_{i-1}^{+}, p_{i}^{-}}$, we see that $\rho_{H^{\prime}}\left(\hat{\phi}^{-1}\left(p_{i-1}^{+}\right), \hat{\phi}^{-1}\left(p_{i}^{-}\right)\right) \geq \Omega\left(\rho_{4}\right)$.

Now, by assumption, for all $i \in[0, n-1]$ except $k=0$,

$$
\rho_{H^{\prime}}\left(\hat{\phi}^{-1}\left(p_{i}^{-}\right), \hat{\phi}^{-1}\left(p_{i}^{+}\right)\right) \geq 2 \rho_{1},
$$

but for $i=0$,

$$
\rho_{H^{\prime}}\left(\hat{\phi}^{-1}\left(p_{0}^{-}\right), \hat{\phi}^{-1}\left(p_{0}^{+}\right)\right) \leq \rho_{1} .
$$

This is a contradiction to Lemma 5.15(iii).
5.4. Families of geodesics. Let $B[\lambda]$ be a box in $X\left(n^{\prime}\right)$ of combinatorial size $\lambda$; i.e., the number of edges from the top to the bottom is $\lambda$, and the distance from the top to the bottom is $\rho_{1} \lambda$. Let $\mathfrak{b}$ be the branching number of each vertex; i.e., the valence of each vertex counting both up and down branching is $2 \mathfrak{b}$. Note that $\mathfrak{b}$ is related to the the constant $B_{X}^{\prime}$ of Section 3.3 by $\mathfrak{b}^{2 \lambda}=e^{B_{X}^{\prime} \rho_{1} \lambda}$, so $\log \mathfrak{b}=B_{X}^{\prime} \rho_{1} / 2$.

Thus the number of $\widehat{S}$-vertices on the top edge of $B[\lambda]$ is $\mathfrak{b}^{\lambda}$, and so is the number of $\widehat{S}$-vertices on the bottom edge. The total number of vertical geodesics in $B[\lambda]$ is $\mathfrak{b}^{2 \lambda}$.

Lemma 5.20. The number of vertices of the $H$-graph in $B[\lambda]$ is at most $c_{9}\left(\rho_{1}\right) \mathfrak{b}^{\lambda}$.

Proof. Apply Lemma 3.8 with $Q$ the union of the top edge and the bottom edge of the box.

Given a box $B(D)$ and a vertical geodesic segment $\gamma$ of length $D$ in $B$, we say $\gamma$ is through if $\gamma$ does not hit any $H$ vertex in $B$. The following lemma applies to families of geodesics in a box. Note that the geodesics are not assumed to be part of the $H$-graph. The point of the lemma is that if too many paths through the box are blocked by good vertices, then some good vertex must block many paths. This really only depends on the fact that there are not too many good vertices in the box.

Lemma 5.21. Let $B[\lambda]$ be a box of combinatorial size $\lambda$. Suppose $\mathcal{F}$ is a family of vertical geodesics (actually monotone paths in the modified $\widehat{S}$-graph going from the top of $B[\lambda]$ to the bottom) with the following properties:
(a) Each geodesic in $\mathcal{F}$ does not hit any bad vertices.
(b) $|\mathcal{F}|$ (i.e., the number of geodesics in $\mathcal{F}$ ) is at least $\sigma \mathfrak{b}^{2 \lambda}$, where $0<\sigma<1$.
(c) For some $\rho \in \mathbb{N}$ (we will always use $\rho=\rho_{2}$ ), fewer than $1-\frac{c 9\left(\rho_{1}\right)}{\mathfrak{b} \rho} \mathfrak{b}^{2 \lambda}$ of the geodesics in $\mathcal{F}$ are through (i.e., do not contain any $H$-vertices in their interior).

Then there exist a vertex $v \in \mathcal{V}_{1}$ not on the bottom edge or within $\rho$ of the top edge of $B[\lambda]$, and two geodesics in $\mathcal{F}$ that pass through $v$ and stay together for fewer than $\rho \widehat{S}$-edges.

Thus, if $\sigma \gg \frac{c 9\left(\rho_{1}\right)}{b^{\rho}}$, almost all of the geodesics in $\mathcal{F}$ are through unless we have a configuration as described in the conclusion of the lemma.

Proof. Let $\mathcal{F}_{0}$ denote the family of all vertical geodesics on the unmodified $\widehat{S}$-graph, passing from the top of $B[\lambda]$ to the bottom. Clearly $\left|\mathcal{F}_{0}\right|=\mathfrak{b}^{2 \lambda}$. Note that $B[\lambda]$ has $\lambda \mathfrak{b}^{\lambda} \widehat{S}$-vertices, and each geodesic contains $\lambda \widehat{S}$-vertices. This implies that each $\widehat{S}$-vertex lies on $M=\mathfrak{b}^{\lambda}$ geodesics in $\mathcal{F}_{0}$.

Now suppose $v$ is an $H$-vertex in $\mathcal{V}_{1}$ and $v$ is not on the bottom edge or within $\rho$ of the top edge. Assuming the conclusion of the lemma fails, then $v$ can belong to at most $M \mathfrak{b}^{-\rho}$ geodesics in $\mathcal{F}$. Thus, using Lemma 5.20, we see that the total number of geodesics in $\mathcal{F}$ that pass through a vertex in $\mathcal{V}_{1}$ in $B$ is at most

$$
M \mathfrak{b}^{-\rho} c_{9}\left(\rho_{1}\right) \mathfrak{b}^{\lambda}=\frac{c_{9}\left(\rho_{1}\right)}{\mathfrak{b}^{\rho}} \mathfrak{b}^{2 \lambda}
$$

which implies that all but $\frac{c_{9}\left(\rho_{1}\right)}{\mathfrak{b}^{\rho}} \mathfrak{b}^{2 \lambda}$ of the geodesics are through, contradicting (c).

Convention. For the remainder of this subsection, we assume that we have an $x$ horocycle $H$ whose image (at least in some initial box) is $x$-oriented. The proof proceeds by extending the set on which the image is horocycle, and so all points in the $H$ graph we consider will be $x$-oriented.

The intervals $I_{\lambda}(v)$ and $I_{\lambda}^{\prime}(v)$. For any $\widehat{S}$-vertex $v$, let $I_{\lambda}(v)$ denote the set of vertices on the same $x$-horocycle as $v$ that are within combinatorial distance $2 \lambda$. Let $I_{\lambda}^{\prime}(v)$ denote the set of vertices that can be reached from $v$ by a monotone path going up for exactly $\lambda$ steps (so $I_{\lambda}^{\prime}(v)$ is a piece of $y$-horocycle). Note that for DL graphs, each point of $I_{\lambda}(v)$ is connected to each point of $I_{\lambda}^{\prime}(v)$ by a monotone path of length $\lambda$ and for any $w \in I_{\lambda}(v)$, $I_{\lambda}(w)=I_{\lambda}(v)$ and $I_{\lambda}^{\prime}(w)=I_{\lambda}^{\prime}(v)$. For Sol slightly more complicated, variants of these statements hold. For instance, for any $w \in I_{\lambda}(v), I_{\lambda}(w)$ and $I_{\lambda}(v)$ intersect in a set that contains more than half the measure of each, and the the relative measure of this intersection in each set is close to one, unless $w$ is close to an edge of $I_{\lambda}(v)$.

Let $v$ be any $\widehat{S}$-vertex. Let $\mathcal{U}(v, \lambda)$ denote the set of distinct monotone geodesic segments in the $\widehat{S}$ graph going up from $v$ for distance exactly $\lambda$. Then $U(v, \lambda)$ is the is the set of geodesics joining $v$ to $I_{\lambda}^{\prime}(v)$. Similarly, we let $\mathcal{D}(w, \lambda)$ be the set of distinct monotone geodesics segments in the $\widehat{S}$-graph going down distance $\lambda$ from $w$. If $w \in I_{\lambda}^{\prime}(v)$, then $\mathcal{D}(w, \lambda)$ is the set of monotone geodesics joining $w$ to points in $I_{\lambda}(v)$

Proposition 5.22 (Extension of Horocycles I). Suppose $v \in \mathcal{V}_{3}$. Suppose $\sigma \gg \eta \gg c_{9}\left(\rho_{1}\right) / \mathfrak{b}^{\rho_{2}}$, and suppose $\lambda$ is such that at least $\sigma$-fraction of the edges going up from $v$ are $\mathcal{E}_{4}$ edges of length at least $\lambda+\rho_{2}$. Then at least $1-O(\eta)$ fraction of the $\widehat{S}$-vertices in $I_{\lambda}(v)$ are in fact $H$-vertices.

Proof. We assume that $v \in \mathcal{V}_{3}$ and that $\hat{\phi}(H)$ is oriented as an $x$-horocycle near $v$. Let $E$ denote the set of $\mathcal{E}_{4}$ edges coming out of $v$ that have length at least $\lambda+\rho_{2}$. Let $E_{\lambda}$ be the set of vertices in $I_{\lambda}^{\prime}(v)$ that are on of $\lambda+\rho_{2}$ unobstructed geodesics leaving $v$. By assumption, we have

$$
\begin{equation*}
\left|E_{\lambda}\right| \geq \sigma \mathfrak{b}^{\lambda} . \tag{23}
\end{equation*}
$$

We now let $\mathcal{F}_{0}^{\prime}=\bigcup_{w \in E_{\lambda}} \mathcal{D}_{\lambda}(v)$ and let $\mathcal{F}^{\prime}$ be all the geodesics segments in $\mathcal{F}_{0}^{\prime}$ that do not contain a bad vertex. Assume for a contradiction that many geodesics in $\mathcal{F}^{\prime}$ are not through, i.e., that (c) of Lemma 5.21 holds for $\mathcal{F}^{\prime}$. We verify that Lemma $5.21(\mathrm{a})$ and (b) hold for $\mathcal{F}^{\prime}$. Since $v \in \mathcal{V}_{3}$,

$$
\begin{equation*}
\left(1-\theta_{4}\right)\left|E_{\lambda}\right| \mathfrak{b}^{\lambda} \leq\left|\mathcal{F}^{\prime}\right| \leq\left|E_{\lambda}\right| \mathfrak{b}^{\lambda} . \tag{24}
\end{equation*}
$$

Note that by (23) and (24), we have $\left|\mathcal{F}^{\prime}\right| \geq \sigma \mathfrak{b}^{2(\lambda)}$. Hence Lemma 5.21(b) holds. Note that all the geodesics in $\mathcal{F}^{\prime}$ end at points of $I_{\lambda}(v)$.

Now by Lemma 5.21 there exist $w \in \mathcal{V}_{1}$ with $h(w)>h(v)$ and an $\widehat{S}$-vertex $w_{1}$ with $h\left(w_{1}\right)>h(w)$ and $d\left(w, w_{1}\right)<\rho_{2}$ so that at least two geodesics in $\mathcal{F}^{\prime}$ meet at $w_{1}$ and continue to $w$ (see Figure 2). Let $x \in I_{\lambda}^{\prime}(v)$ and $y \in I_{\lambda}^{\prime}(v)$ be the starting points of these two geodesics.


Figure 2. Proof of Proposition 5.22. The filled boxes denote $H$-vertices.

Let $z$ be the last common point of the geodesics $\overline{v x}$ and $\overline{v y}$. We now apply Lemma 5.19 to the points $\left\langle w_{1}, x, z, y\right\rangle$. Note that $r\left(w_{1}\right)<\rho_{2}$ (because of $w$ ). Also by assumption, $r(x) \geq \rho_{2}>r\left(w_{1}\right)$ and $r(y) \geq \rho_{2}>r\left(w_{1}\right)$. Note that $h(z)=h\left(w_{1}\right)$, hence $r(z)=h(z)-h(v)=h\left(w_{1}\right)-h(v)>h\left(w_{1}\right)-h(w)=$ $r\left(w_{1}\right)$. Hence we get a contradiction by Lemma 5.19. Hence we cannot have condition (c) of Lemma 5.21; therefore all but $O(\eta)$ of the geodesics in $\mathcal{F}^{\prime}$ are unobstructed. Thus the number of unobstructed geodesics in $\mathcal{F}^{\prime}$ is at least

$$
\begin{equation*}
(1-O(\eta))\left|\mathcal{F}^{\prime}\right| \geq(1-O(\eta))\left(1-\theta_{4}\right)\left|E_{\lambda}\right| \mathfrak{b}^{\lambda} \tag{25}
\end{equation*}
$$

where we have used (24) to get the second estimate.
Now, let $U^{\prime} \subset I_{\lambda}(v)$ be the set of $\widehat{S}$-vertices (at height $h(v)$ ) that are the endpoints of at least two geodesics in $\mathcal{F}^{\prime}$. Since every vertex can be reached by at most $\left|E_{\lambda}\right|$ geodesics, we have by (25),

$$
\begin{equation*}
\left|U^{\prime}\right| \geq(1-O(\eta))\left(1-\theta_{4}\right) \mathfrak{b}^{\lambda} \tag{26}
\end{equation*}
$$

i.e., then $U^{\prime}$ has almost full measure in $I_{\lambda}(v)$.

Now suppose $w \in I_{\lambda}(v)$ is such that two unobstructed geodesics in $\mathcal{F}^{\prime}$ end at $w$. Let us denote these geodesics by $\overline{w x}$ and $\overline{w y}$ where $x, y \in I_{\lambda}^{\prime}(v)$. By definition of $\mathcal{F}^{\prime}, \overline{x v}$ and $\overline{y v}$ are unobstructed. We now apply Lemma 5.19 to the points $\langle w, x, v, y\rangle$. Note that $r(v)=0$ (since $v$ is an $H$-vertex), and also that $r(x) \geq \rho_{2}$, and $r(y) \geq \rho_{2}$. Thus, by Lemma 5.19, we get a contradiction unless $r(w)=0$; i.e., $w$ is an $H$-vertex.

If $v \in \mathcal{V}_{4}$, then the conclusion is strengthened automatically to imply that most vertices in $I_{\lambda}(v)$ are in $\mathcal{V}_{3}$. This is used in the following proposition.

Proposition 5.23 (Zero-One Law). Suppose $v \in \mathcal{V}_{4}$. Suppose $\lambda$ is such that the fraction of the edges in $\mathcal{U}(v, \lambda)$ that are in $\mathcal{E}_{4}$ and are unobstructed for at least length $\lambda+\rho_{2}$ is at least $\sigma \gg c_{9}\left(\rho_{1}\right) / \mathfrak{b}^{\rho_{2}}$. Let $\mathcal{F}=\bigcup_{w \in I_{\lambda}(v)} \mathcal{U}(w)$. Then at least $1-O(\eta)$ fraction of the edges in $\mathcal{F}$ are unobstructed for length $\lambda+\rho_{2}$.

Proof. As in the previous proposition, let $E_{\lambda}$ be the set of vertices in $I_{\lambda}^{\prime}(v)$ that are on of $\lambda+\rho_{2}$ unobstructed geodesics leaving $v$. Also let $U^{\prime} \subset I_{\lambda}(v)$ and $\mathcal{F}^{\prime}$ be as in Proposition 5.22.

Now since $v$ is not a strange vertex, the subset $U^{\prime \prime}$ of $I_{\lambda}(v)$ consisting of $\mathcal{V}_{3}$ vertices in $U^{\prime}$ is of almost full measure in $I_{\lambda}(v)$. Let

$$
\mathcal{F}^{\prime \prime}=\bigcup_{w \in U^{\prime \prime}} \mathcal{U}(w) \cap \mathcal{E}_{2} .
$$

(Thus $\mathcal{F}^{\prime \prime}$ consists of all the $\mathcal{E}_{2}$ edges coming out of all the "good" $H$-vertices on $I_{\lambda}(v)$.) We cut off all the geodesics in $\mathcal{F}^{\prime \prime}$ after they cross $I_{\lambda}^{\prime}(v)$.

We want to apply Lemma 5.21 to $\mathcal{F}^{\prime \prime}$ in the box of size $\lambda$, but there are technical difficulties here in verifying Lemma 5.21. To overcome these difficulties, we look at a horocircle $H^{\prime}$ that is $\rho_{4}$ units below $H$ with the same orientation. By a discussion similar to Lemma 5.18 and following and the fact that $\mathcal{F}^{\prime \prime}$ consists of edges in $\mathcal{E}_{2}$, we can extend every geodesic segment in $\mathcal{F}^{\prime \prime}$ by $\rho_{4}$ on top and bottom in all possible ways to obtain a family $\mathcal{F}_{\text {long }}^{\prime}$. We will apply Lemma 5.21 to $\mathcal{F}_{\text {long }}^{\prime \prime}$ instead. If almost all segments in $\mathcal{F}_{\text {long }}^{\prime \prime}$ are unobstructed by $H^{\prime}$, it is immediate that almost all segments in $\mathcal{F}^{\prime \prime}$ are unobstructed by $H^{\prime}$. We let $U_{\text {long }}^{\prime}$ be the set of $H^{\prime}$ vertices within $\rho_{4}$ of $U^{\prime}$.

We have that $\left|\mathcal{F}_{\text {long }}^{\prime \prime}\right| \geq(1-O(\eta)) \mathfrak{b}^{2\left(\lambda+\rho_{4}\right)}$, so (b) is satisfied. Also, (a) is satisfied since the relevant edges are in $\mathcal{E}_{2}$. If (c) does not hold, we are done, so we assume (c) holds. This implies that the conclusion of the lemma is true, and we show this yields an illegal circuit (see Figure 3).


Figure 3. Proof of Proposition 5.23. The filled boxes denote $H^{\prime}$-vertices.

By Lemma 5.21, there exist an $H^{\prime}$-vertex $q$ with $h(q)<h(v)+\lambda+2 \rho_{4}$ and an $\widehat{S}$-vertex $q_{*}$ with $h(q)-\rho_{2}<h\left(q_{*}\right) \leq h(q)$ such that at least two geodesics in $\mathcal{F}_{\text {long }}^{\prime \prime}$ come together at $q_{*}$. Let these geodesics be $\overline{u_{1} q_{*}}$ and $\overline{u_{2} q_{*}}$ where for $i=1,2, u_{i} \in U_{\text {long }}^{\prime}$. Let $w_{i}=\overline{u_{1} q_{*} \cap U^{\prime}}$ denote the corresponding point in $U^{\prime}$. Since $w_{i} \in U^{\prime}$, there exists $x_{i} \in I_{\lambda+\rho_{4}}^{\prime}(v)$ such that $\overline{w_{i} x_{i}}$ and $\overline{x_{i} v}$ are both $\mathcal{E}_{2}$ and unobstructed. Let $v^{\prime}$ denote any point on $U_{\text {long }}^{\prime}$ that is $\rho_{4}$ units below $v$. We now apply Lemma 5.19 to the points $\left\langle q_{*}, w_{1}, x_{1}, v, x_{2}, w_{2}\right\rangle$. Note that by construction, $r\left(q_{*}\right)<\rho_{2} \ll \rho_{3}, r(v)=\rho_{4}$, and for $i=1,2, r\left(w_{i}\right)=\rho_{4}$, $r\left(x_{i}\right) \geq \rho_{2}$. Thus by Lemma 5.19, $q_{*} w_{1}$ and $q_{*} w_{2}$ do not diverge at $q_{*}$, which is a contradiction.

Theorem 5.24 (Extension of Horocycles II). Suppose $v \in \mathcal{V}_{4}$ is $x$-oriented. Let $s$ denote the height difference between $v$ and the top of $B\left(L^{\prime}\right)$, and assume $s>4 \kappa^{2} \beta^{\prime \prime} R$. Then, the density of $x$-oriented $\mathcal{V}_{3} H$-vertices along $I_{s}(v)$ is $1-O(\eta)$.

Remark. The proof of this theorem is considerably simpler in the case of DL-graphs as boxes in DL graphs have "no sides." We give the proof first in this case. The Sol case is complicated by needing to avoid having paths "escape off the sides of the box."

Proof for DL graphs. For an $x$-oriented $\mathcal{V}_{4}$ vertex $w$, let $f(w, \lambda)$ denote the proportion of edges in $\mathcal{U}(w)$ which are $\mathcal{E}_{4}$ and unobstructed for length $\lambda+\rho_{2}$. Let

$$
f^{*}(v, \lambda)=\sup _{w \in I_{\lambda}(v) \cap \mathcal{V}_{4}} f(w, \lambda) .
$$

In view of Proposition 5.23, for any $\lambda$ for which $f^{*}(v, \lambda) \geq O(\eta)$, we have $f^{*}(v, \lambda)>1-O(\eta)$.

Thus, either for all $1 \leq \lambda \leq s, f_{j}^{*}(v, \lambda) \geq 1-O(\eta)$, in which case Theorem 5.24 holds in view of Proposition 5.22 and 5.23 , or else there exists minimal $\lambda$ such that $f^{*}(v, \lambda)>1-O(\eta)$, and also $f^{*}(v, \lambda+1)<O(\eta)$. Note that $\lambda>\Omega\left(\beta^{\prime \prime} R\right)$ by the definition of good vertices and the $\widehat{S}$ and $H$-graphs. Let $w \in I_{\lambda}(v) \cap \mathcal{V}_{4}$ be such that the sup in the definition of $f^{*}(v, \lambda)$ is realized at $w$. Hence, by Proposition 5.22(i), all but $O(\eta)$ fractions of the $\widehat{S}$-vertices in $I_{\lambda}(w)=I_{\lambda}(v)$ are $H$-vertices. By the choice of $w$, at least $1-O(\eta)$ fraction of the geodesics in $\mathcal{U}(w)$ are in $\mathcal{E}_{4}$, unobstructed for length $\lambda+\rho_{2}$, and hit an $H$-vertex (in $\mathcal{V}_{1}$ ) at length $\lambda+\rho_{2}+1$. Thus, in particular, the density of $H$-vertices on $I_{\lambda+\rho_{2}+1}^{\prime}(w)$ is at least $1-O(\eta)$.

Let $\widetilde{H}=I_{\lambda}(w) \cap \mathcal{V}_{1}$. We consider the family $\mathcal{E}(w)$ of monotone geodesic segments "going up" length $L^{\prime}$ from points at height $h_{1}$ in

$$
\operatorname{Sh}\left(N\left(\phi^{-1}(\tilde{H}), O\left(\varepsilon^{\prime} R\right)\right) \cap H, \rho_{1}\right)
$$

and use the behavior of this family to derive a contradiction. We first modify $\mathcal{E}(w)$ by throwing away some bad parts of the set. This modification is unnecessary if we are assuming that $\left.\phi\right|_{U_{i}}$ is within $O\left(\varepsilon^{\prime} R\right)$ of a $b$-standard map. We throw out any geodesic $\gamma$ in $\mathcal{E}(w)$ whose intersection with $\mathrm{SL}_{2}^{1}(H)$ has more than $100 c_{2}^{\frac{1}{2}}$ of its measure outside $\mathrm{SL}_{2}^{1}(H) \cap U_{*}$. By Lemma 4.1, this throws away at most $O\left(c^{\frac{1}{2}}\right)$ of the geodesics in $\mathcal{E}(w)$. After this modifications, it follows that each geodesic in $\mathcal{E}(w)$ has $\varepsilon^{\prime}$-monotone image on an initial segment of length at least $\Omega\left(\beta^{\prime} R\right)$.

Note that $N\left(\phi^{-1}(\widetilde{H}), O\left(\varepsilon^{\prime} R\right)\right) \cap H$ contains a set of large measure in $H$ and that $\left(I_{\lambda}(w) \cup I_{\lambda+\rho_{2}+1}^{\prime}(w)\right) \cap \mathcal{V}_{1}$ is contained in the $O\left(\varepsilon^{\prime} R\right)$ neighborhood of $\phi(H)$.

Since every geodesic in $\mathcal{E}(w)$ diverges linearly from $H$ and the initial segments of all $\mathcal{E}(w)$ of length $\Omega\left(\beta^{\prime} R\right)>\Omega\left(\varepsilon^{\prime} R\right)$ have $\varepsilon^{\prime}$-monotone image for $\phi$, we have that any quasi-geodesic in $\phi(\mathcal{E}(w))$ diverges linearly from $\phi(H)$ and, in particular, never comes within $\Omega\left(\beta^{\prime} R\right)$ of $\phi(H)$.

Let $Q_{u} \subset I_{\lambda}^{\prime}(w)$ be the subset of vertices $v$ such that all vertices on $I_{\lambda+\rho_{2}+1}^{\prime}$ within $\frac{R}{100 \kappa^{3}}-\rho_{2}-1$ are not in $\mathcal{V}_{1}$. Since $\ell\left(\mathcal{V}_{1}^{c} \cap I_{\lambda+\rho_{2}+1}^{\prime}\right)<O(\eta) \ell\left(I_{\lambda+\rho_{2}+1}^{\prime}\right)$, we have $\ell\left(Q_{u}\right) \ll O(\eta) \ell\left(I_{\lambda}^{\prime}(w)\right)=O(\eta) \mathfrak{b}^{\lambda}$. Any quasi-geodesic in $\phi(\mathcal{E}(w))$ crossing $I_{\lambda}^{\prime}(w)$ does so on $Q_{u}$.

Similarly, let $Q_{d}=I_{\lambda}(w) \cap \mathcal{V}_{1}^{c}$. Note that $\ell\left(Q_{d}\right) \ll O(\eta) \ell\left(I_{\lambda}(w)\right)=O(\eta) \mathfrak{b}^{\lambda}$ and that any quasi-geodesic in $\phi(\mathcal{E}(w))$ crossing $I_{\lambda}(w)$ must cross it on $Q_{d}$.

Now as all quasi-geodesics in $\phi(\mathcal{E}(w))$ diverge linearly from $\phi(H)$, they must all eventually leave the box of size $\lambda$ bounded by $I_{\lambda}(w)$ and $I_{\lambda}^{\prime}(w)$. This implies that every quasi-geodesic in $\phi(\mathcal{E}(w))$ eventually crosses $Q_{u} \cup Q_{d}$ or that every geodesic in $\mathcal{E}(w)$ eventually crosses $\phi^{-1}\left(Q_{u} \cup Q_{d}\right)$. This is impossible by Lemma 3.7, since

$$
\begin{equation*}
\ell\left(\phi^{-1}\left(Q_{u} \cup Q_{d}\right)\right) \leq O(\eta) \ell(H) \tag{27}
\end{equation*}
$$

and $c\left(\rho_{1}\right) O(\eta) \ll 1$.
Before reading the proof for Sol, the reader should be sure to read Section 3.5.

Proof for Sol. We need to modify the proof given above in two ways in order to avoid "escape off the sides" of the box of size $\lambda$. As this is a modification of the previous proof, we only sketch the necessary changes.

We choose $w$ as in the proof for DL graphs. We remark that it is easy to see that $w$ can be chosen away from the edge of $B[\lambda]$. This can be deduced from Proposition 5.23. We will assume that we have chosen such a $w$. It is also possible to work with $w$ near the edge of the box but that one use a more complicated definition of points deep in the shadow of horocycles.

As above we consider $\widetilde{H}=I_{\lambda}(w) \cap \mathcal{V}_{1}$. We consider the family $\mathcal{E}(w)$ of monotone geodesics "going up" length $L^{\prime}$ from points at height

$$
h_{1} \in \operatorname{Sh}\left(N\left(\phi^{-1}(\widetilde{H}), O\left(\varepsilon^{\prime} R\right)\right) \cap H, \rho_{1}\right)
$$

and use the behavior of this family to derive a contradiction. We first modify $\mathcal{E}(w)$ exactly as before. We now further modify $\mathcal{E}(w)$ to only include those geodesics whose images at the end of the initial segment are $\beta^{\prime} R$-deep in $B[\lambda]$. By this we mean that they are $\beta^{\prime} R$ deep in the shadows of the top and bottom of $B(R)$. This subset still contains a large proportion of the original elements of $\mathcal{E}(w)$. Let $Q=Q_{u} \cup Q_{d}$. Then as before, we see that paths in $\mathcal{E}(w)$ can only come near the top and bottom of $B[\lambda]$ in $N\left(Q^{c}, \frac{\beta^{\prime} R}{2 \kappa}\right)$.

We now apply the results of Section 3.5 with $\rho=\rho_{1}, D_{1}=\varepsilon^{\prime} R, D_{2}=\frac{\beta^{\prime} R}{2 \kappa}$, and $D_{3}=\lambda$. By Lemma 3.12, if a path $\gamma \in \phi(\mathcal{E}(w))$ leaves the box, it must tangle with the union of the top and the bottom of the box. Since $\left.\gamma \in N\left(Q^{c}, \frac{\beta^{\prime} R}{2 \kappa}\right)\right)$, Lemma 3.13 implies

$$
\ell\left(Q_{u} \cup Q_{d}\right)=\ell(Q) \geq \omega\|\mathcal{E}(w)\|,
$$

where $\omega$ depends only on $\kappa$ and $C$. But we have $\|\mathcal{E}(w)\| \geq \omega^{\prime} \ell(H)$, where $\omega^{\prime}$ depends only on $\kappa$ and $C$. This is a contradiction to (27) if $\eta$ is sufficiently small. As before, $\eta$ can be made arbitrarily small by taking $\varepsilon^{\prime}$ and $\delta_{0}$ sufficiently small.

### 5.5. Completing the proof of Theorem 2.1.

Proof. By Theorem 1.3, $\phi^{-1}$ of any very favorable horocycle in $B\left(L^{\prime}\right)$ is within $O\left(\varepsilon^{\prime} R\right)$ error of a horocycle. Given $\hat{\theta}>0$, Lemma 5.1 implies, by choosing $\beta^{\prime \prime}$ and $\delta_{0}$ small enough, that $1-\hat{\theta}$ of the measure of $B\left(L^{\prime}\right)$ consists of points in the image of both a very favorable $x$-horocycle and a very favorable $y$-horocycle. By an argument from the proof of [EFW12, Lemma 4.11], this implies that $\phi^{-1}$ respects level sets of height to within $O\left(\varepsilon^{\prime} R\right)$ error.

From this, it is not hard to show that $\phi^{-1}$ of most vertical geodesics are weakly monotone. This is very similar to the proof of [EFW12, Lemma 6.5]. There are some additional difficulties due to the fact that we only control the map on most of the measure, but these can be handled in a manner similar to the proofs of [EFW12, Lemma 5.10 and Cor. 5.12].

Once we know $\phi^{-1}$ of most vertical geodesics are weakly monotone, the conclusion of the theorem follows as in the proof of [EFW12, Th. 5.1].

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