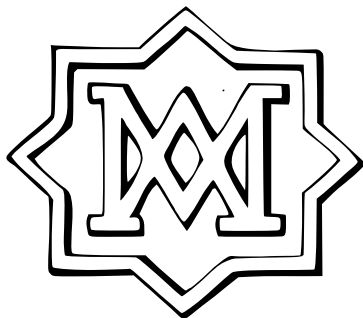


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## Pólya-Schur master theorems for circular domains and their boundaries

By JULIUS BORCEA and PETTER BRÄNDÉN



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## Abstract

We characterize all linear operators on finite or infinite-dimensional polynomial spaces that preserve the property of having the zero set inside a prescribed region  $\Omega \subseteq \mathbb{C}$  for arbitrary closed circular domains  $\Omega$  (i.e., images of the closed unit disk under a Möbius transformation) and their boundaries. This provides a natural framework for dealing with several long-standing fundamental problems, which we solve in a unified way. In particular, for  $\Omega = \mathbb{R}$  our results settle open questions that go back to Laguerre and Pólya-Schur.

## 1. Introduction

Some of the main challenges in the theory of the distribution of zeros of polynomials and transcendental entire functions concern the description of linear operators that preserve certain prescribed (“good”) properties. Notwithstanding their fundamental character, most of these problems are in fact still open as they turn out to be surprisingly difficult in full generality. Two outstanding questions among these are the following: Let  $\Omega \subseteq \mathbb{C}$  be an appropriate set of interest, and denote by  $\pi(\Omega)$  the class of all (complex or real) univariate polynomials whose zeros lie in  $\Omega$ .

PROBLEM 1. Characterize all linear transformations

$$T : \pi(\Omega) \rightarrow \pi(\Omega) \cup \{0\}.$$

Let  $\pi_n$  be the vector space (over  $\mathbb{C}$  or  $\mathbb{R}$ ) of all polynomials of degree at most  $n$ , and denote by  $\pi_n(\Omega)$  the subclass of  $\pi(\Omega)$  consisting of polynomials of degree at most  $n$ . The finite degree analogue of [Problem 1](#) is as follows.

PROBLEM 2. For  $n \in \mathbb{N}$ , describe all linear operators

$$T : \pi_n(\Omega) \rightarrow \pi_n(\Omega) \cup \{0\}.$$

These problems were stated in precisely this general form in [CC04], [Cso06] (see also [BBCV07], [RS02, pp. 182–183]), thereby encompassing essentially all similar questions or variations thereof scattered throughout the literature. Problems 1 and 2 originate from the works of Laguerre [Lag82] and Pólya and Schur [PS14] and have been open for all but trivial choices of  $\Omega$ , including such important cases as when  $\Omega = \mathbb{R}$  or  $\Omega$  is a half-plane. In this paper we completely solve Problems 1 and 2 in arguably the most relevant cases, namely all closed circular domains (iii)–(v) and their boundaries (i)–(ii):

- (i)  $\Omega$  is a line,
- (ii)  $\Omega$  is a circle,
- (iii)  $\Omega$  is a closed half-plane,
- (iv)  $\Omega$  is a closed disk,
- (v)  $\Omega$  is the complement of an open disk.

Despite their long history, relatively few results pertaining to Problems 1 and 2 are known. As we note in the following (very brief) survey, these deal almost exclusively with special types of linear transformations satisfying the required properties.

To prove the transcendental characterizations of linear preservers of polynomials whose zeros are located on a line or in a closed half-plane (Theorems 5 and 6), we first establish a result on uniform limits on compact sets of bivariate polynomials that are nonvanishing whenever both variables are in the upper half-plane (Theorem 12). Entire functions that are uniform limits on compact sets of sequences of univariate polynomials with only positive zeros were first described by Laguerre [Lag82]. In the process, he showed that if  $Q(z)$  is a real polynomial with all negative zeros, then  $T(\pi(\mathbb{R})) \subseteq \pi(\mathbb{R}) \cup \{0\}$ , where  $T : \mathbb{R}[z] \rightarrow \mathbb{R}[z]$  is the linear operator defined by  $T(z^k) = Q(k)z^k$  for  $k \in \mathbb{N}$ . Laguerre also stated without proof the correct result for uniform limits of polynomials with all real zeros. The class of entire functions thus obtained — the so-called Laguerre-Pólya class — was subsequently characterized by Pólya [Pól13]. A more complete investigation of sequences of such polynomials was carried out in [LP14]. This also led to the description of entire functions obtained as uniform limits on compact sets of sequences of univariate polynomials whose zeros all lie in a given closed half-plane [Lev80], [Obr41], [Sz43] as well as the description of entire functions in two variables obtained as limits, uniform on compact sets, of sequences of bivariate polynomials that are nonvanishing when both variables are in a given open half-plane [Lev80].

The Laguerre-Pólya class has ever since played a significant role in the theory of entire functions [CCS87], [Lev80]. It was for instance a key ingredient in Pólya and Schur's (transcendental) characterization of *multiplier sequences of the*

first kind [PS14]; see [Theorem 1](#) below. The latter are linear transformations  $T$  on  $\mathbb{R}[z]$  that are diagonal in the standard monomial basis of  $\mathbb{R}[z]$  and satisfy  $T(\pi(\mathbb{R})) \subseteq \pi(\mathbb{R}) \cup \{0\}$ . Pólya and Schur’s seminal paper generated a vast literature on this topic and related subjects at the interface between analysis, operator theory and algebra, but a solution to [Problem 1](#) in the case  $\Omega = \mathbb{R}$  has so far remained elusive (cf. [CC04]). Among the most noticeable progress in this direction we should mention [Theorem 17](#) of [Lev80, Ch. IX], where Levin describes a certain class of “regular” linear operators acting on the closure of the set of univariate polynomials with all zeros in the closed upper half-plane. However, Levin’s theorem actually uses rather restrictive assumptions and seems in fact to rely on additional (albeit not explicitly stated) nondegeneracy conditions for the transformations involved. Indeed, one can easily produce counterexamples to Levin’s result by considering linear operators such as the ones described in [Corollary 2\(a\)](#) of this paper. In [CC77], Craven and Csordas established an analogue of the Pólya-Schur theorem for multiplier sequences in finite degree, thus solving [Problem 2](#) for  $\Omega = \mathbb{R}$  in the special case of diagonal operators. Unipotent upper triangular linear operators  $T$  on  $\mathbb{R}[z]$  satisfying  $T(\pi(\mathbb{R})) \subseteq \pi(\mathbb{R}) \cup \{0\}$  were described in [CPP02a]. Quite recently, the authors in [BB06] solved [Problem 1](#) for  $\Omega = \mathbb{R}$  and obtained multivariate extensions for a large class of linear transformations, namely all finite order linear differential operators with polynomial coefficients. Further partial progress towards a solution to [Problem 1](#) for  $\Omega = \mathbb{R}$  is preliminarily reported in [Fis06], although the same kind of remarks as in the case of Levin’s theorem apply here. Namely, the results of [Fis06] are valid only in the presence of extra nondegeneracy or continuity assumptions for the operators under consideration. Various other special cases of [Problem 1](#) for  $\Omega = \mathbb{R}$  have been considered in [ABH04], [Brä06], [Bre89], [INS91], [IN87], [IN90]. Finally, we should mention that to the best of our knowledge [Problems 1](#) and [2](#) have so far been widely open in cases (ii)–(v).

To begin with, in [Section 2.1](#) and [Sections 3.1](#) and [3.2](#), we solve [Problems 1](#) and [2](#) for  $\Omega = \mathbb{R}$  and  $\Omega = \{z \in \mathbb{C} : \Im(z) \leq 0\}$  and thus obtain complete algebraic and transcendental characterizations of linear operators that preserve hyperbolicity and stability, respectively. In order to deal with [Problems 1](#) and [2](#) for *all* closed circular domains and their boundaries, we are naturally led to considering a third classification problem, namely the following more general version of [Problem 2](#):

**PROBLEM 3.** Let  $n \in \mathbb{N}$  and  $\Omega \subset \mathbb{C}$ . Describe all linear operators

$$T : \pi_n(\Omega) \setminus \pi_{n-1}(\Omega) \rightarrow \pi(\Omega) \cup \{0\}.$$

As we explain in [Section 2.2](#), [Problems 2](#) and [3](#) are equivalent for closed unbounded sets, but for closed bounded sets the latter problem is more natural and actually turns out to be a crucial step in solving [Problems 1](#) and [2](#) for closed discs. In [Sections 2.2](#) and [3.3](#), we fully answer [Problem 3](#) for any closed circular domain

or the boundary of such a domain. As a consequence, we get complete solutions to Problems 1 and 2 in all cases ((i)–(v)) listed above.

On the one hand, these results accomplish the classification program originating from the works of Laguerre and Pólya-Schur that we briefly outlined in this introduction. On the other hand, they seem to have numerous applications ranging from entire function theory and operator theory to real algebraic geometry, matrix theory and combinatorics. Some of these will be studied in forthcoming publications. Section 4 concludes this paper with several remarks on related open problems and potential further developments.

## 2. Main results

2.1. *Hyperbolicity and stability preservers.* To formulate the complete answers to Problems 1 and 2 for  $\mathbb{R}$  and the half-plane  $\{z \in \mathbb{C} : \Im(z) \leq 0\}$ , we need to introduce some notation. As in [BB06] — and following the commonly used terminology in e.g. the theory of partial differential equations [ABG70] — we call a nonzero univariate polynomial with real coefficients *hyperbolic* if all of its zeros are real. Such a polynomial is said to be *strictly hyperbolic* if in addition all of its zeros are distinct. A univariate polynomial  $f(z)$  with complex coefficients is called *stable* if  $f(z) \neq 0$  for all  $z \in \mathbb{C}$  with  $\Im(z) > 0$ , and it is called *strictly stable* if  $f(z) \neq 0$  for all  $z \in \mathbb{C}$  with  $\Im(z) \geq 0$ . Hence a univariate polynomial with real coefficients is stable if and only if it is hyperbolic. These classical concepts have several natural extensions to multivariate polynomials, the most general notion being as follows.

*Definition 1.* We say a polynomial  $f(z_1, \dots, z_n) \in \mathbb{C}[z_1, \dots, z_n]$  is *stable* if  $f(z_1, \dots, z_n) \neq 0$  for all  $n$ -tuples  $(z_1, \dots, z_n) \in \mathbb{C}^n$  with  $\Im(z_j) > 0$  for  $1 \leq j \leq n$ . If in addition  $f$  has real coefficients, it will be referred to as *real stable*. The sets of stable and real stable polynomials in  $n$  variables are denoted by  $\mathcal{H}_n(\mathbb{C})$  and  $\mathcal{H}_n(\mathbb{R})$ , respectively.

Note that  $f$  is stable (respectively, real stable) if and only if for all  $\alpha \in \mathbb{R}^n$  and  $v \in \mathbb{R}_+^n$  the univariate polynomial  $f(\alpha + vt) \in \mathbb{C}[t]$  is stable (respectively, hyperbolic). The connection between real stability and (Gårding) hyperbolicity for multivariate homogeneous polynomials is explained in e.g. [BB06, Prop. 1].

NOTATION 1. Henceforth it is understood that if  $T$  is a linear operator on some (real) linear subspace  $V \subseteq \mathbb{R}[z_1, \dots, z_n]$  then  $T$  extends in an obvious fashion to a linear operator — denoted again by  $T$  — on the complexification  $V \oplus iV$  of  $V$ .

*Definition 2.* A linear operator  $T$  defined on a linear subspace  $V$  of  $\mathbb{C}[z_1, \dots, z_n]$  (respectively,  $\mathbb{R}[z_1, \dots, z_n]$ ) is called *stability preserving* (respectively, *real*

stability preserving) on a given subset  $M \subseteq V$  if

$$T(\mathcal{H}_n(\mathbb{C}) \cap M) \subseteq \mathcal{H}_n(\mathbb{C}) \cup \{0\} \text{ (respectively, } T(\mathcal{H}_n(\mathbb{R}) \cap M) \subseteq \mathcal{H}_n(\mathbb{R}) \cup \{0\} \text{)}.$$

A real stability preserver in the univariate case will alternatively be referred to as a *hyperbolicity preserver*. For  $m \in \mathbb{N}$ , let  $\mathbb{R}_m[z] = \{f \in \mathbb{R}[z] : \deg(f) \leq m\}$  and  $\mathbb{C}_m[z] = \mathbb{R}_m[z] \oplus i\mathbb{R}_m[z] = \{f \in \mathbb{C}[z] : \deg(f) \leq m\}$ . If  $T$  is a stability (respectively, hyperbolicity) preserving operator on  $\mathbb{C}_m[z]$  (respectively,  $\mathbb{R}_m[z]$ ), we will also say that  $T$  *preserves stability* (respectively, *hyperbolicity*) *up to degree*  $m$ .

Pólya and Schur’s characterization of multiplier sequences of the first kind, which we referred to in [Section 1](#), is given in the following theorem; see [\[CC04\]](#), [\[Lev80\]](#), [\[PS14\]](#).

**THEOREM 1 (Pólya-Schur).** *Let  $\lambda : \mathbb{N} \rightarrow \mathbb{R}$  be a sequence of real numbers, and let  $T : \mathbb{R}[z] \rightarrow \mathbb{R}[z]$  be the corresponding (diagonal) linear operator given by  $T(z^n) = \lambda(n)z^n$  for  $n \in \mathbb{N}$ . Define  $\Phi(z)$  to be the formal power series*

$$\Phi(z) = \sum_{k=0}^{\infty} \frac{\lambda(k)}{k!} z^k.$$

The following assertions are equivalent:

- (i)  $\lambda$  is a multiplier sequence.
- (ii)  $\Phi(z)$  defines an entire function which is the limit, uniform on compact sets, of polynomials with only real zeros of the same sign.
- (iii) Either  $\Phi(z)$  or  $\Phi(-z)$  is an entire function that can be written as

$$Cz^n e^{az} \prod_{k=1}^{\infty} (1 + \alpha_k z),$$

where  $n \in \mathbb{N}$ ,  $C \in \mathbb{R}$ ,  $a, \alpha_k \geq 0$  for all  $k \in \mathbb{N}$ , and  $\sum_{k=1}^{\infty} \alpha_k < \infty$ .

- (iv) For all nonnegative integers  $n$ , the polynomial  $T[(z + 1)^n]$  is hyperbolic with all zeros of the same sign.

As noted in e.g. [\[CC04, Th. 3.3\]](#), parts (ii) and (iii) in the Pólya-Schur theorem give a “transcendental” description of multiplier sequences, while part (iv) provides an “algebraic” characterization. We emphasize right away the fact that our main results actually yield algebraic and transcendental characterizations of *all* hyperbolicity and stability preservers, respectively, and are therefore natural generalizations of [Theorem 1](#). Moreover, they also display an intimate connection between [Problem 1](#) and its finite degree analogue ([Problem 2](#)) in the case of (real) stability preservers.

NOTATION 2. Given a linear operator  $T$  on  $\mathbb{C}[z]$ , we extend it to a linear operator—denoted again by  $T$ —on the space  $\mathbb{C}[z, w]$  of polynomials in the variables  $z$  and  $w$  by setting  $T(z^k w^\ell) = T(z^k)w^\ell$  for all  $k, \ell \in \mathbb{N}$ .

Definition 3. Let  $\alpha_1 \leq \alpha_2 \leq \dots \leq \alpha_n$  and  $\beta_1 \leq \beta_2 \leq \dots \leq \beta_m$  be the zeros of two hyperbolic polynomials  $f, g \in \mathcal{H}_1(\mathbb{R})$ . We say that these zeros *interlace* if they can be ordered so that either  $\alpha_1 \leq \beta_1 \leq \alpha_2 \leq \beta_2 \leq \dots$  or  $\beta_1 \leq \alpha_1 \leq \beta_2 \leq \alpha_2 \leq \dots$ . Note that in this case one has  $|m - n| \leq 1$ . By convention, the zeros of any two polynomials of degree 0 or 1 interlace.

Our first theorem characterizes linear operators preserving hyperbolicity up to some fixed degree  $n$ .

THEOREM 2. *Let  $n \in \mathbb{N}$ , and let  $T : \mathbb{R}_n[z] \rightarrow \mathbb{R}[z]$  be a linear operator. Then  $T$  preserves hyperbolicity if and only if either*

- (a)  *$T$  has range of dimension at most two and is of the form*

$$T(f) = \alpha(f)P + \beta(f)Q \quad \text{for } f \in \mathbb{R}_n[z],$$

where  $\alpha, \beta : \mathbb{R}_n[z] \rightarrow \mathbb{R}$  are linear functionals and  $P, Q \in \mathcal{H}_1(\mathbb{R})$  have interlacing zeros;

- (b)  $T[(z + w)^n] \in \mathcal{H}_2(\mathbb{R})$ ; or
- (c)  $T[(z - w)^n] \in \mathcal{H}_2(\mathbb{R})$ .

In [BB06], we recently characterized real stable polynomials in two variables as the polynomials  $f(z, w) \in \mathbb{R}[z, w]$  that can be expressed as

$$(2-1) \quad f(z, w) = \pm \det(zA + wB + C),$$

where  $A$  and  $B$  are positive semidefinite matrices and  $C$  is a symmetric matrix. Hence (b) and (c) in Theorem 2 can be reformulated as

$$T[(z + w)^n] = \pm \det(zA \pm wB + C),$$

where  $A$  and  $B$  are positive semidefinite matrices and  $C$  is a symmetric matrix.

We will also need to deal with the case when we allow complex coefficients.

THEOREM 3. *Let  $n \in \mathbb{N}$ , and let  $T : \mathbb{C}_n[z] \rightarrow \mathbb{C}[z]$  be a linear operator. Then  $T : \pi_n(\mathbb{R}) \rightarrow \pi(\mathbb{R})$  if and only if either*

- (a)  *$T$  has range of dimension at most one and is of the form*

$$T(f) = \alpha(f)P \quad \text{for } f \in \mathbb{C}_n[z],$$

where  $\alpha : \mathbb{C}_n[z] \rightarrow \mathbb{C}$  is a linear functional and  $P \in \mathcal{H}_1(\mathbb{R})$ ;

- (b)  *$T$  has range of dimension at most two and is of the form*

$$T(f) = \eta\alpha(f)P + \eta\beta(f)Q \quad \text{for } f \in \mathbb{C}_n[z],$$

where  $\eta \in \mathbb{C}$ ,  $\alpha, \beta : \mathbb{C}_n[z] \rightarrow \mathbb{C}$  are linear functionals with  $\alpha(\mathbb{R}_n[z]) \subseteq \mathbb{R}$  and  $\beta(\mathbb{R}_n[z]) \subseteq \mathbb{R}$ , and  $P, Q \in \mathcal{H}_1(\mathbb{R})$  have interlacing zeros;

- (c) there exists an  $\eta \in \mathbb{C}$  such that  $\eta T[(z + w)^n] \in \mathcal{H}_2(\mathbb{R})$ ; or
- (d) there exists an  $\eta \in \mathbb{C}$  such that  $\eta T[(z - w)^n] \in \mathcal{H}_2(\mathbb{R})$ .

The next theorem concerns stability preservers up to some fixed degree  $n$ .

**THEOREM 4.** *Let  $n \in \mathbb{N}$ , and let  $T : \mathbb{C}_n[z] \rightarrow \mathbb{C}[z]$  be a linear operator. Then  $T$  preserves stability if and only if either*

- (a)  $T$  has range of dimension at most one and is of the form

$$T(f) = \alpha(f)P \quad \text{for } f \in \mathbb{C}_n[z],$$

where  $\alpha : \mathbb{C}_n[z] \rightarrow \mathbb{C}$  is a linear functional and  $P \in \mathcal{H}_1(\mathbb{C})$ ; or

- (b)  $T[(z + w)^n] \in \mathcal{H}_2(\mathbb{C})$ .

From Theorems 2 and 4 we may deduce algebraic characterizations of hyperbolicity and stability preservers, respectively:

**COROLLARY 1** (algebraic characterization of hyperbolicity preservers). *A linear operator  $T : \mathbb{R}[z] \rightarrow \mathbb{R}[z]$  preserves hyperbolicity if and only if either*

- (a)  $T$  has range of dimension at most two and is of the form

$$T(f) = \alpha(f)P + \beta(f)Q \quad \text{for } f \in \mathbb{R}[z],$$

where  $\alpha, \beta : \mathbb{R}[z] \rightarrow \mathbb{R}$  are linear functionals and  $P, Q \in \mathcal{H}_1(\mathbb{R})$  have interlacing zeros;

- (b)  $T[(z + w)^n] \in \mathcal{H}_2(\mathbb{R}) \cup \{0\}$  for all  $n \in \mathbb{N}$ ; or
- (c)  $T[(z - w)^n] \in \mathcal{H}_2(\mathbb{R}) \cup \{0\}$  for all  $n \in \mathbb{N}$ .

**COROLLARY 2** (algebraic characterization of stability preservers). *A linear operator  $T : \mathbb{C}[z] \rightarrow \mathbb{C}[z]$  preserves stability if and only if either*

- (a)  $T$  has range of dimension at most one and is of the form

$$T(f) = \alpha(f)P \quad \text{for } f \in \mathbb{C}[z],$$

where  $\alpha : \mathbb{C}[z] \rightarrow \mathbb{C}$  is a linear functional and  $P \in \mathcal{H}_1(\mathbb{C})$ ; or

- (b)  $T[(z + w)^n] \in \mathcal{H}_2(\mathbb{C}) \cup \{0\}$  for all  $n \in \mathbb{N}$ .

**NOTATION 3.** To any linear operator  $T : \mathbb{C}[z] \rightarrow \mathbb{C}[z]$ , we associate a formal power series in  $w$  with polynomial coefficients in  $z$  given by

$$G_T(z, w) = \sum_{n=0}^{\infty} \frac{(-1)^n T(z^n)}{n!} w^n \in \mathbb{C}[z][[w]].$$



Let  $n$  be a positive integer, and denote by  $\overline{\mathcal{H}}_n(\mathbb{C})$  and  $\overline{\mathcal{H}}_n(\mathbb{R})$  the set of entire functions in  $n$  variables that are limits, uniform on compact sets, of polynomials in  $\mathcal{H}_n(\mathbb{C})$  and  $\mathcal{H}_n(\mathbb{R})$ , respectively. Hence in our notation,  $\overline{\mathcal{H}}_1(\mathbb{R})$  is the Laguerre-Pólya class of entire functions; this class is sometimes denoted  $\mathcal{L}\text{-}\mathcal{P}$  in the literature. For a description of  $\overline{\mathcal{H}}_1(\mathbb{C})$  and  $\overline{\mathcal{H}}_2(\mathbb{C})$ , see [Lev80, Chap. IX].

*Remark 1.* As noted in [BB06], any linear operator  $T$  on  $\mathbb{C}[z]$  may be uniquely represented as a formal linear differential operator with polynomial coefficients, i.e.,  $T = \sum_{k=0}^{\infty} Q_k(z) d^k/dz^k$ , where  $Q_k \in \mathbb{C}[z]$  and  $k \geq 0$ . In [BB06], we used the (formal) symbol  $F_T(z, w) := \sum_{k=0}^{\infty} Q_k(z)w^k \in \mathbb{C}[z][[w]]$  of  $T$ . One can easily check that the “modified symbol”  $G_T(z, w)$  introduced in Notation 3 satisfies  $G_T(z, w)e^{zw} = F_T(z, -w)$ .

**THEOREM 5** (transcendental characterization of hyperbolicity preservers). *A linear operator  $T : \mathbb{R}[z] \rightarrow \mathbb{R}[z]$  preserves hyperbolicity if and only if either*

- (a)  *$T$  has range of dimension at most two and is of the form*

$$T(f) = \alpha(f)P + \beta(f)Q \quad \text{for } f \in \mathbb{R}[z],$$

*where  $\alpha, \beta : \mathbb{R}[z] \rightarrow \mathbb{R}$  are linear functionals and  $P, Q \in \mathcal{H}_1(\mathbb{R})$  have interlacing zeros;*

- (b)  $G_T(z, w) \in \overline{\mathcal{H}}_2(\mathbb{R})$ ; or
- (c)  $G_T(z, -w) \in \overline{\mathcal{H}}_2(\mathbb{R})$ .

**THEOREM 6** (transcendental characterization of stability preservers). *A linear operator  $T : \mathbb{C}[z] \rightarrow \mathbb{C}[z]$  preserves stability if and only if either*

- (a)  *$T$  has range of dimension at most one and is of the form*

$$T(f) = \alpha(f)P \quad \text{for } f \in \mathbb{C}[z],$$

*where  $\alpha : \mathbb{C}[z] \rightarrow \mathbb{C}$  is a linear functional and  $P \in \mathcal{H}_1(\mathbb{C})$ ; or*

- (b)  $G_T(z, w) \in \overline{\mathcal{H}}_2(\mathbb{C})$ .

**2.2. Preservers of polynomials with zeros in a closed circular domain or its boundary.** Recall that a Möbius transformation is a bijective conformal map of the extended complex plane, i.e., a map  $\Phi : \mathbb{C} \cup \{\infty\} \rightarrow \mathbb{C} \cup \{\infty\}$  given by

$$(2-2) \quad \Phi(z) = \frac{az+b}{cz+d} \quad \text{for } a, b, c, d \in \mathbb{C} \text{ with } ad - bc \neq 0.$$

The inverse of  $\Phi$  is then given by

$$\Phi^{-1}(z) = \frac{dz-b}{-cz+a}.$$

*Definition 4.* Let

$$H = \{z \in \mathbb{C} : \Im(z) > 0\} \quad \text{and} \quad \bar{H} = \{z \in \mathbb{C} : \Im(z) \geq 0\}.$$

An *open circular domain* is the image of  $H$  under a Möbius transformation, i.e., an open disk, the (open) complement of a closed disk or an open affine half-plane. A *closed circular domain* is the image of  $\bar{H}$  under a Möbius transformation, that is, a closed disk, the (closed) complement of an open disk or a closed affine half-plane.

For technical reasons we will henceforth assume the following:

(2-3) *If  $C$  is a half-plane, then the corresponding Möbius transformation  $\Phi : C \rightarrow H$  is a translation composed with a rotation, i.e.,  $c = 0$  in (2-2).*

Let us also extend [Definition 1](#) to arbitrary sets  $\Omega \subseteq \mathbb{C}$ .

*Definition 5.* A polynomial  $f \in \mathbb{C}[z_1, \dots, z_n]$  is said to be  $\Omega$ -stable if it satisfies  $f(\zeta_1, \dots, \zeta_n) \neq 0$  whenever  $\zeta_j \in \Omega$  for all  $1 \leq j \leq n$ .

*Remark 2.* An  $H$ -stable polynomial is precisely a stable polynomial in the sense of [Definition 1](#).

When  $C_1$  is closed and unbounded and  $C_2$  is closed and bounded, a fundamental discrepancy between  $\pi_n(C_1)$  and  $\pi_n(C_2)$  is that  $\pi_n(C_1) \setminus \pi_{n-1}(C_1)$  is dense in  $\pi_n(C_1)$  while  $\pi_n(C_2) \setminus \pi_{n-1}(C_2)$  is not dense in  $\pi_n(C_2)$ , since constant nonzero polynomials do not belong to the closure of  $\pi_n(C_2) \setminus \pi_{n-1}(C_2)$ . In order for a linear transformation  $T : \mathbb{C}_n[z] \rightarrow \mathbb{C}[z]$  to map  $\pi_n(C_1) \cup \{0\}$  into  $\pi(C_1) \cup \{0\}$ , it is therefore enough (by Hurwitz’s theorem) for  $T$  to map  $\pi_n(C_1) \setminus \pi_{n-1}(C_1)$  into  $\pi(C_1) \cup \{0\}$ . However, this is not the case for  $C_2$ . Indeed, take for instance  $C_2$  to be the closed unit disk, and let  $T_n : \mathbb{C}_n[z] \rightarrow \mathbb{C}_{n-1}[z]$  be defined by

$$T(z^k) = (n - k)z^k + kz^{k-1} \quad \text{for } 0 \leq k \leq n.$$

An application of [Theorem 7](#) below shows that  $T : \pi_n(C_2) \setminus \pi_{n-1}(C_2) \rightarrow \pi(C_2) \cup \{0\}$  but  $T(z^{n-1}) = z^{n-2}(z + n - 1)$ , which does not belong to  $\pi(C_2)$  for  $n \geq 3$ . Therefore we need to solve a more general version of [Problem 2](#), namely [Problem 3](#). This is done in the next two theorems for all closed circular domains and their boundaries.

**NOTATION 4.** Given  $\Omega \subseteq \mathbb{C}$ , we denote its complement  $\mathbb{C} \setminus \Omega$  by  $\Omega'$  and its boundary  $\bar{\Omega} \setminus \overset{\circ}{\Omega}$  by  $\partial\Omega$ . We let  $\Omega^r$  be the interior of the complement of  $\Omega$ , that is,  $\Omega^r = \overset{\circ}{\Omega}'$ .

**THEOREM 7.** *Let  $n \in \mathbb{N}$ , and let  $T : \mathbb{C}_n[z] \rightarrow \mathbb{C}[z]$  be a linear operator. Let  $C$  be an open circular domain given by  $C = \Phi^{-1}(H)$ , where  $\Phi$  is a Möbius transformation as in (2-2). Then  $T : \pi_n(C') \setminus \pi_{n-1}(C') \rightarrow \pi(C') \cup \{0\}$  if and only if either*

(a)  $T$  has range of dimension at most one and is of the form

$$T(f) = \alpha(f)P \quad \text{for } f \in \mathbb{C}_n[z],$$

where  $\alpha : \mathbb{C}_n[z] \rightarrow \mathbb{C}$  is a linear functional and  $P \in \pi(C')$ ; or

(b) the polynomial  $T[((az + b)(cw + d) + (aw + b)(cz + d))^n]$  is  $C$ -stable.

*Remark 3.* In the case when  $C'$  is the closed unit disk then for

$$(2-4) \quad \Phi(z) = \frac{(i/2)(z+i)}{z-i}$$

the polynomial in (b) of [Theorem 7](#) reduces to  $i^n T[(1 + zw)^n]$ .

**NOTATION 5.** Given a Möbius transformation  $\Phi$  as in (2-2) and  $n \in \mathbb{N}$ , we define an invertible linear transformation  $\phi_n : \mathbb{C}_n[z] \rightarrow \mathbb{C}_n[z]$  by  $\phi_n(f)(z) = (cz + d)^n f(\Phi(z))$ .

**THEOREM 8.** Let  $n \in \mathbb{N}$ , and let  $T : \mathbb{C}_n[z] \rightarrow \mathbb{C}[z]$  be a linear operator. Let  $C = \Phi^{-1}(H)$  be an unbounded open circular domain, where  $\Phi$  is a Möbius transformation as in (2-2). Then  $T : \pi_n(\partial C) \setminus \pi_{n-1}(\partial C) \rightarrow \pi(\partial C) \cup \{0\}$  if and only if either

(a)  $T$  has range of dimension at most one and is of the form

$$T(f) = \alpha(f)P \quad \text{for } f \in \mathbb{C}_n[z],$$

where  $\alpha : \mathbb{C}_n[z] \rightarrow \mathbb{C}$  is a linear functional and  $P \in \pi(\partial C)$ ;

(b)  $T$  has range of dimension two, and the linear operator given by  $S = \phi_m^{-1} T \phi_n$  is a stability preserver as in (b) of [Theorem 3](#), where  $m = \max\{\deg T(f) : f \in \mathbb{C}_n[z]\}$ ;

(c) the polynomial  $T[((az + b)(cw + d) + (aw + b)(cz + d))^n]$  is both  $C$ -stable and  $C^r$ -stable; or

(d) the polynomial  $T[((az + b)(cw + d) - (aw + b)(cz + d))^n]$  is both  $C$ -stable and  $C^r$ -stable.

*Remark 4.* If  $\partial C$  is the unit circle, then for  $\Phi$  as in (2-4) the polynomials in (c) and (d) of [Theorem 8](#) simply become  $i^n T[(1 + zw)^n]$  and  $T[(z - w)^n]$ , respectively.

For completeness, we also formulate analogues of [Corollaries 1](#) and [2](#) providing algebraic characterizations in the case of closed circular domains and their boundaries.

**COROLLARY 3** (algebraic characterization: closed circular domain case). Let  $T : \mathbb{C}[z] \rightarrow \mathbb{C}[z]$  be a linear operator, and let  $C \subset \mathbb{C}$  be an open circular domain given by  $C = \Phi^{-1}(H)$ , where  $\Phi$  is a Möbius transformation as in (2-2). Then  $T : \pi(C') \rightarrow \pi(C') \cup \{0\}$  if and only if either

(a)  $T$  has range of dimension at most one and is of the form

$$T(f) = \alpha(f)P \quad \text{for } f \in \mathbb{C}[z],$$

where  $\alpha : \mathbb{C}[z] \rightarrow \mathbb{C}$  is a linear functional and  $P \in \pi(\mathbb{C}')$ ; or

(b) the polynomial  $T[((az + b)(cw + d) + (aw + b)(cz + d))^n]$  is  $C$ -stable for all  $n \in \mathbb{N}$ .

**COROLLARY 4** (algebraic characterization: circle and line case). *Suppose  $T : \mathbb{C}[z] \rightarrow \mathbb{C}[z]$  is a linear operator and  $C = \Phi^{-1}(H)$  is an unbounded open circular domain, where  $\Phi$  is a Möbius transformation as in (2-2). Then  $T : \pi(\partial C) \rightarrow \pi(\partial C) \cup \{0\}$  if and only if either*

(a)  $T$  has range of dimension at most one and is of the form

$$T(f) = \alpha(f)P \quad \text{for } f \in \mathbb{C}[z],$$

where  $\alpha : \mathbb{C}[z] \rightarrow \mathbb{C}$  is a linear functional and  $P \in \pi(\partial C)$ ;

(b)  $T$  has range of dimension two, and for all  $n \in \mathbb{N}$  the linear operator given by  $S_n = \phi_{m(n)}^{-1} T \phi_n$  is a stability preserver as in (b) of Theorem 3, where  $m(n) = \max\{\deg T(f) : f \in \mathbb{C}_n[z]\}$ ;

(c) the polynomial  $T[((az + b)(cw + d) + (aw + b)(cz + d))^n]$  is both  $C$ -stable and  $C^r$ -stable for all  $n \in \mathbb{N}$ ; or

(d) the polynomial  $T[((az + b)(cw + d) - (aw + b)(cz + d))^n]$  is both  $C$ -stable and  $C^r$ -stable for all  $n \in \mathbb{N}$ .

Similarly, we may characterize all linear maps that take polynomials with zeros in one closed circular domain  $\Omega_1$  to polynomials with zeros in another closed circular domain  $\Omega_2$ , or the boundary of one circular domain  $\Omega_1$  to the boundary of another circular domain  $\Omega_2$ . However, this only amounts to composing with linear operators of the type defined in Notation 5, namely  $\phi_n : \mathbb{C}_n[z] \rightarrow \mathbb{C}_n[z]$ , where  $\phi_n(f)(z) = (cz + d)^n f(\Phi(z))$  and  $\Phi$  is an appropriate Möbius transformation of the form (2-2).

### 3. Proofs of the main results

3.1. *Hyperbolic and stable polynomials.* Recall that if the zeros of two hyperbolic polynomials  $f, g \in \mathcal{H}_1(\mathbb{R})$  interlace, then the Wronskian  $W[f, g] := f'g - fg'$  is either nonnegative or nonpositive on the whole real axis  $\mathbb{R}$ .

*Definition 6.* Given  $f, g \in \mathcal{H}_1(\mathbb{R})$  we say that  $f$  and  $g$  are in *proper position*, and write  $f \ll g$ , if the zeros of  $f$  and  $g$  interlace and  $W[f, g] \leq 0$ .

For technical reasons we also say that the zeros of the polynomial 0 interlace the zeros of any (nonzero) hyperbolic polynomial and write  $0 \ll f$  and  $f \ll 0$ .

Note that if  $f \ll g$  and  $g \ll f$ , then  $f$  and  $g$  must be constant multiples of each other, that is,  $W[f, g] \equiv 0$ .

The following is a version of the classical Hermite-Biehler theorem [RS02].

**THEOREM 9 (Hermite-Biehler).** *Let  $h := f + ig \in \mathbb{C}[z]$ , where  $f, g \in \mathbb{R}[z]$ . Then  $h \in \mathcal{H}_1(\mathbb{C})$  if and only if  $f, g \in \mathcal{H}_1(\mathbb{R})$  and  $g \ll f$ . Moreover,  $h$  is strictly stable if and only if  $f$  and  $g$  are strictly hyperbolic polynomials with no common zeros and  $g \ll f$ .*

The next theorem is often attributed to Obreschkoff [Obr63].

**THEOREM 10 (Obreschkoff).** *Let  $f, g \in \mathbb{R}[z]$ . Then  $\alpha f + \beta g \in \mathcal{H}_1(\mathbb{R}) \cup \{0\}$  for all  $\alpha, \beta \in \mathbb{R}$  if and only if either  $f \ll g$ ,  $g \ll f$ , or  $f = g \equiv 0$ . Moreover,  $\alpha f + \beta g$  is strictly hyperbolic for all  $\alpha, \beta \in \mathbb{R}$  with  $\alpha^2 + \beta^2 \neq 0$  if and only if  $f$  and  $g$  are strictly hyperbolic polynomials with no common zeros and either  $f \ll g$  or  $g \ll f$ .*

*Remark 5.* Note that if  $T : \pi_n(\mathbb{R}) \rightarrow \pi(\mathbb{R})$  is an  $\mathbb{R}$ -linear operator then by Obreschkoff's theorem  $T$  also preserves interlacing, as follows: if  $f$  and  $g$  are hyperbolic polynomials of degree at most  $n$  whose zeros interlace, then the zeros of  $T(f)$  and  $T(g)$  interlace provided that  $T(f)T(g) \neq 0$ .

**LEMMA 1.** *Let  $n \in \mathbb{N}$ . Suppose  $T : \mathbb{R}_{n+1}[z] \rightarrow \mathbb{R}[z]$  preserves hyperbolicity and  $f \in \mathbb{R}[z]$  is a strictly hyperbolic polynomial of degree  $n$  or  $n + 1$  for which  $T(f) = 0$ . Then  $T(g)$  is hyperbolic for all  $g \in \mathbb{R}[z]$  with  $\deg g \leq n + 1$ .*

*Let  $T : \mathbb{C}_n[z] \rightarrow \mathbb{C}[z]$  be a stability preserver, and suppose that  $f \in \mathbb{C}[z]$  is a strictly stable polynomial of degree  $n$  for which  $T(f) = 0$ . Then  $T(g)$  is stable for all  $g \in \mathbb{C}[z]$  with  $\deg g \leq n$ .*

*Proof.* Let  $f$  be a strictly hyperbolic polynomial of degree  $n$  or  $n + 1$  for which  $T(f) = 0$ , and let  $g \in \mathbb{R}[z]$  be a polynomial with  $\deg g \leq n + 1$ . From Hurwitz's theorem it follows that for  $\epsilon \in \mathbb{R}$  with  $|\epsilon|$  small enough the polynomial  $f + \epsilon g$  is strictly hyperbolic. Since  $\deg(f + \epsilon g) \leq n + 1$  and  $T$  preserves hyperbolicity up to degree  $n + 1$ , we get that  $T(g) = \epsilon^{-1}T(f + \epsilon g)$  is hyperbolic.

Suppose  $f \in \mathbb{C}[z]$  is a strictly stable polynomial of degree  $n$  such that  $T(f) = 0$ , and suppose the degree of  $g \in \mathbb{C}[z]$  does not exceed  $n$ . By Hurwitz's theorem,  $f + \epsilon g$  is strictly stable for all sufficiently small  $|\epsilon|$ . Then because  $\deg(f + \epsilon g) \leq n$  and because  $T$  preserves stability up to degree  $n$ , it follows that  $T(g) = \epsilon^{-1}T(f + \epsilon g)$  is stable.  $\square$

**LEMMA 2.** *Suppose  $V \subseteq \mathbb{R}[z]$  is an  $\mathbb{R}$ -linear space whose nonzero elements are all hyperbolic. Then  $\dim V \leq 2$ .*

*Suppose  $V \subseteq \mathbb{C}[z]$  is a  $\mathbb{C}$ -linear space whose nonzero elements are all stable. Then  $\dim V \leq 1$ .*

*Proof.* We first deal with the real case. Suppose there are three linearly independent polynomials  $f_1, f_2$  and  $f_3$  in  $V$ . By Obreschkoff’s theorem, the zeros of these polynomials mutually interlace. Without loss of generality, we may assume that  $f_1 \ll f_2$  and  $f_1 \gg f_3$ . Consider the line segment  $\ell_\theta = \theta f_3 + (1 - \theta) f_2$  for  $0 \leq \theta \leq 1$ . Since  $f_1 \ll \ell_0$  and  $f_1 \gg \ell_1$  by Hurwitz’s theorem, there is a real number  $\eta$  between 0 and 1 such that  $f_1 \ll \ell_\eta$  and  $f_1 \gg \ell_\eta$ . This means that  $f_1$  and  $\ell_\eta$  are constant multiples of each other, which contradicts the assumption that  $f_1, f_2$  and  $f_3$  are linearly independent.

For the complex case, let  $V_R = \{p : p + iq \in V \text{ with } p, q \in \mathbb{R}[z]\}$  be the “real component” of  $V$ . By the Hermite-Biehler theorem, all polynomials in  $V_R$  are hyperbolic, so by the above we have  $\dim_{\mathbb{R}} V_R \leq 2$ . Clearly  $V$  is the complex span of  $V_R$ . If  $\dim_{\mathbb{R}} V_R \leq 1$ , we are done, so we may assume that  $\{p, q\}$  is a basis for  $V_R$  with  $f := p + iq \in V$ . By definition  $W[p, q] \geq 0$  on the whole of  $\mathbb{R}$ , and the Wronskian is not identically zero. Assume now that  $g$  is another polynomial in  $V$ . Then  $g = ap + bq + i(cp + dq)$  for some  $a, b, c, d \in \mathbb{R}$ . We must show that  $g$  is a (complex) constant multiple of  $f$ . Since  $g \in V$ , we have

$$W[ap + bq, cp + dq] = (ad - bc)W[p, q] \geq 0,$$

so that  $ad - bc \geq 0$ . Now by linearity we have

$$g + (u + iv)f = (a + u)p + (b - v)q + i((c + v)p + (d + u)q) \in V$$

for all  $u, v \in \mathbb{R}$ , which, as above, gives

$$H(u, v) := (a + u)(d + u) - (b - v)(c + v) \geq 0$$

for all  $u, v \in \mathbb{R}$ . But

$$4H(u, v) = (2u + a + d)^2 + (2v + c - b)^2 - (a - d)^2 - (b + c)^2,$$

so  $H(u, v) \geq 0$  for all  $u, v \in \mathbb{R}$  if and only if  $a = d$  and  $b = -c$ . This gives

$$g = ap - cq + i(cp + aq) = (a + ic)(p + iq) = (a + ic)f. \quad \square$$

NOTATION 6. Let  $\mathcal{H}_1^-(\mathbb{C}) = \{f \in \mathbb{C}[z] : f(z) \neq 0 \text{ if } \Im(z) < 0\}$ . By the Hermite-Biehler theorem and Definition 6, if  $f, g \in \mathbb{R}[z]$  then  $f + ig \in \mathcal{H}_1^-(\mathbb{C})$  if and only if  $f, g \in \mathcal{H}_1(\mathbb{R})$  and  $f \ll g$ . Given a linear subspace  $V$  of  $\mathbb{C}[z]$  and  $M \subseteq V$ , we say that a linear operator  $T$  on  $V$  is *stability reversing* on  $M$  if  $T(\mathcal{H}_1(\mathbb{C}) \cap M) \subseteq \mathcal{H}_1^-(\mathbb{C}) \cup \{0\}$ . Note that if  $S : \mathbb{C}[z] \rightarrow \mathbb{C}[z]$  is the linear involution defined by  $S(f)(z) = f(-z)$ , then  $T$  is stability reversing if and only if  $S \circ T$  is stability preserving.

LEMMA 3. *Suppose  $T : \mathbb{R}_n[z] \rightarrow \mathbb{R}[z]$  maps all hyperbolic polynomials of degree at most  $n$  to hyperbolic polynomials. Then  $T$  is either stability preserving, stability reversing, or the range of  $T$  has dimension at most two. In the latter case*

$T$  is given by

$$(3-1) \quad T(f) = \alpha(f)P + \beta(f)Q \quad \text{for } f \in \mathbb{R}_n[z],$$

where  $P$  and  $Q$  are hyperbolic polynomials whose zeros interlace and  $\alpha$  and  $\beta$  are real-valued linear functionals on  $\mathbb{R}_n[z]$ .

*Proof.* The lemma is obvious for  $n = 0$ , so we may and do assume  $n$  is a positive integer. By Remark 5 and the Hermite-Biehler theorem, we know  $T$  maps all stable polynomials of degree  $n$  into the set  $\mathcal{H}_1(\mathbb{C}) \cup \mathcal{H}_1^-(\mathbb{C}) \cup \{0\}$ . We now distinguish two cases. Suppose first there are two strictly stable polynomials  $f$  and  $g$  of degree  $n$  such that  $T(f) \in \mathcal{H}_1(\mathbb{C})$  and  $T(g) \in \mathcal{H}_1^-(\mathbb{C})$ .

CLAIM. *If the above conditions are satisfied, then the kernel of  $T$  must contain a strictly hyperbolic polynomial of degree at least  $n - 1$ .*

From Lemma 1 and the claim, we deduce that  $T : \mathbb{R}_n[z] \rightarrow \pi(\mathbb{R}) \cup \{0\}$ . Hence all nonzero polynomials in the image of  $T$  are hyperbolic, which by Lemma 2 gives that  $\dim T(\mathbb{R}_n[z]) \leq 2$ . Thus  $T$  must be of the form (3-1).

*Proof of the claim.* Suppose  $f_1$  and  $f_2$  are two strictly stable polynomials of degree  $n$  for which  $T(f_1) \in \mathcal{H}_1(\mathbb{C})$  and  $T(f_2) \in \mathcal{H}_1^-(\mathbb{C})$ , respectively. By a homotopy argument, invoking again Hurwitz’s theorem, there is a strictly stable polynomial  $h$  of degree  $n$  for which  $T(h) \in \mathcal{H}_1(\mathbb{C}) \cap \mathcal{H}_1^-(\mathbb{C}) \cup \{0\}$ . Writing  $h$  as  $h = p + iq$ , where  $p$  and  $q$  are strictly hyperbolic polynomials (by the Hermite-Biehler theorem) gives that  $T(p)$  and  $T(q)$  are constant multiples of each other. Suppose  $\deg p = n$ . Then  $\deg q \geq n - 1$  since the zeros of  $p$  and  $q$  interlace. If  $T(q) = 0$ , the claim is obviously true, so suppose  $T(q) \neq 0$ . Then  $T(p) = \lambda T(q)$  for some  $\lambda \in \mathbb{R}$ . By the Obreschkoff theorem,  $p - \lambda q$  is strictly hyperbolic and of degree at least  $n - 1$ . Clearly,  $T(p - \lambda q) = 0$ , which proves the claim.  $\square$

Now suppose  $T$  maps all strictly stable polynomials of degree  $n$  into the set  $\mathcal{H}_1(\mathbb{C}) \cup \{0\}$  (the case when  $T$  maps all such polynomials into  $\mathcal{H}_1^-(\mathbb{C}) \cup \{0\}$  is treated similarly). Let  $f$  be a strictly stable polynomial with  $\deg f < n$ , and set  $f_\epsilon(z) = (1 - \epsilon iz)^{n - \deg f} f(z)$ . Then  $f_\epsilon$  is strictly stable whenever  $\epsilon > 0$  and  $T(f_\epsilon) \in \mathcal{H}_1(\mathbb{C}) \cup \{0\}$ , since  $\deg f_\epsilon = n$ . Letting  $\epsilon \rightarrow 0$ , we get  $T(f) \in \mathcal{H}_1(\mathbb{C}) \cup \{0\}$ , and since strictly stable polynomials are dense in  $\mathcal{H}_1(\mathbb{C})$ , it follows that  $T$  is stability preserving.  $\square$

As a final tool we will need the Grace-Walsh-Szegö coincidence theorem [Gra02], [Sze22], [Wal22]. Recall that a multivariate polynomial is *multi-affine* if it has degree at most one in each variable.

THEOREM 11 (Grace-Walsh-Szegö coincidence theorem). *Suppose that  $f \in \mathbb{C}[z_1, \dots, z_n]$  is symmetric and multi-affine, and let  $C$  be a circular domain containing the points  $\zeta_1, \dots, \zeta_n$ . Assume further that either the total degree of  $f$*

equals  $n$  or  $C$  is convex (or both). Then there exists a point  $\zeta \in C$  such that  $f(\zeta_1, \dots, \zeta_n) = f(\zeta, \dots, \zeta)$ .

This theorem has an immediate corollary:

**COROLLARY 5.** Let  $f \in \mathbb{C}[z_1, \dots, z_n]$  be of degree at most  $d$  in  $z_1$ , and consider the expansion of  $f$  in powers of  $z_1$  given by

$$f(z_1, \dots, z_n) = \sum_{k=0}^d Q_k(z_2, \dots, z_n) z_1^k \quad \text{for } Q_k \in \mathbb{C}[z_2, \dots, z_n] \text{ and } 0 \leq k \leq d.$$

Then  $f$  is stable if and only if the polynomial

$$\sum_{k=0}^d Q_k(z_2, \dots, z_n) e_k(x_1, \dots, x_d) / \binom{d}{k}$$

is stable in the variables  $z_2, \dots, z_n, x_1, \dots, x_d$ , where the  $e_k(x_1, \dots, x_d)$  for  $0 \leq k \leq d$  are the elementary symmetric functions in the variables  $x_1, \dots, x_d$  given by  $e_0 = 1$  and  $e_k = \sum_{1 \leq j_1 < j_2 < \dots < j_k \leq d} x_{j_1} \cdots x_{j_k}$  for  $1 \leq k \leq d$ .

**LEMMA 4.** Suppose  $T : \mathbb{C}_n[z_1] \rightarrow \mathbb{C}[z_1]$  is a linear operator such that

$$T[(z_1 + w)^n] \in \mathfrak{H}_2(\mathbb{C}).$$

If  $f \in \mathfrak{H}_m(\mathbb{C})$  is of degree at most  $n$  in  $z_1$  then  $T(f) \in \mathfrak{H}_m(\mathbb{C}) \cup \{0\}$ , where  $T$  is extended to a linear operator on  $\mathbb{C}[z_1, \dots, z_m]$  by setting  $T(z_1^{\alpha_1} \cdots z_m^{\alpha_m}) = T(z_1^{\alpha_1}) z_2^{\alpha_2} \cdots z_m^{\alpha_m}$  for all  $\alpha \in \mathbb{N}^m$  with  $\alpha_1 \leq n$  (compare with [Notation 2](#)).

*Proof.* Let  $f \in \mathfrak{H}_m(\mathbb{C})$  be of degree  $n$  in  $z_1$ . For  $\epsilon > 0$ , set

$$f_\epsilon(z_1, \dots, z_m) = f(z_1 + \epsilon i, z_2, \dots, z_m).$$

Fixing  $\zeta_2, \dots, \zeta_m$  in the open upper half-plane, we may write

$$\begin{aligned} f_\epsilon(z_1, \zeta_2, \dots, \zeta_m) &= C(z_1 - \xi_1)(z_1 - \xi_2) \cdots (z_1 - \xi_n) \\ &= C \sum_{k=0}^n (-1)^k e_k(\xi_1, \dots, \xi_n) z_1^{n-k}, \end{aligned}$$

where  $C \neq 0$  and  $\Im m(\xi_j) < 0$  for  $1 \leq j \leq n$ . Note that  $z_1 \mapsto f_\epsilon(z_1, \zeta_2, \dots, \zeta_m)$  is indeed a polynomial of degree  $n$  in  $z_1$ . This is because

$$f_\epsilon(z_1, z_2, \dots, z_m) = z_1^n Q_n(z_2, \dots, z_m) + \text{terms of lower degree in } z_1$$

and  $Q_n(z_2, \dots, z_n) := \lim_{r \rightarrow \infty} r^{-n} f(r, z_2, \dots, z_m)$  is stable by Hurwitz's theorem; hence  $Q_n(\zeta_2, \dots, \zeta_n) \neq 0$ . Let us now write

$$T[(z_1 + w)^n] = \sum_{k=0}^n \binom{n}{k} T(z_1^{n-k}) w^k \in \mathfrak{H}_2(\mathbb{C}).$$



By [Corollary 5](#) we know that

$$\sum_{k=0}^n T(z_1^{n-k})e_k(w_1, \dots, w_n) \in \mathcal{H}_{n+1}(\mathbb{C}).$$

But then

$$T(f_\epsilon)(z_1, \zeta_2, \dots, \zeta_m) = C \sum_{k=0}^n T(z_1^{n-k})e_k(-\xi_1, \dots, -\xi_n) \in \mathcal{H}_1(\mathbb{C}),$$

which gives  $T(f_\epsilon) \in \mathcal{H}_m(\mathbb{C})$ . Letting  $\epsilon \rightarrow 0$  we have  $T(f) \in \mathcal{H}_m(\mathbb{C}) \cup \{0\}$ . If  $f \in \mathcal{H}_m(\mathbb{C})$  is of degree less than  $n$  in  $z_1$ , we consider  $f^\epsilon = (1 - \epsilon i z_1)^{n - \deg f} f \in \mathcal{H}_m(\mathbb{C})$ . Then by the above we have  $T(f^\epsilon) \in \mathcal{H}_m(\mathbb{C}) \cup \{0\}$  for all  $\epsilon > 0$ . The lemma now follows from Hurwitz’s theorem by letting  $\epsilon \rightarrow 0$ .  $\square$

*Proof of Theorem 4.* If  $T[(z + w)^n] \in \mathcal{H}_2(\mathbb{C})$  then by applying [Lemma 4](#) with  $m = 1$ , it follows that  $T$  is stability preserving.

Suppose now that  $T$  preserves stability. Assume first that there exists a  $w_0 \in \mathbb{C}$  with  $\Im(w_0) > 0$  such that  $(z + w_0)^n$  is in the kernel of  $T$ . Then since  $(z + w_0)^n$  is strictly stable, it follows from [Lemma 1](#) and [Lemma 2](#) that  $\dim_{\mathbb{C}} T(\mathbb{C}_n[z]) \leq 1$ . Hence  $T$  is given by  $T(f) = \alpha(f)P$ , where  $P$  is a fixed stable polynomial and  $\alpha : \mathbb{C}_n[z] \rightarrow \mathbb{C}$  is a linear functional. Otherwise, we assume  $T[(z + w_0)^n] \in \mathcal{H}_1(\mathbb{C})$  for all  $w_0 \in \mathbb{C}$  with  $\Im(w_0) > 0$  and conclude that  $T[(z + w)^n] \in \mathcal{H}_2(\mathbb{C})$ .  $\square$

*Proof of Theorem 2.* Recall [Notation 6](#), and note that by [Lemma 3](#) we may assume that  $\dim_{\mathbb{R}} T(\mathbb{R}_n[z]) > 2$ , so that  $T$  is either stability reversing or stability preserving. [Theorem 4](#) says  $T$  is stability reversing or stability preserving if and only if  $T[(z + w)^n] \in \mathcal{H}_2(\mathbb{C})$  or  $T[(z - w)^n] \in \mathcal{H}_2(\mathbb{C})$ , respectively, which proves the theorem.  $\square$

*Proof of Theorem 3.* By [Theorem 2](#), it suffices to prove that if a linear operator  $T : \mathbb{C}_n[z] \rightarrow \mathbb{C}[z]$  satisfies  $T : \pi_n(\mathbb{R}) \rightarrow \pi(\mathbb{R})$  then either

- (a) there exists a  $\theta \in \mathbb{R}$  such that  $T = e^{i\theta} \tilde{T}$ , where  $\tilde{T} : \mathbb{R}_n[z] \rightarrow \mathbb{R}[z]$  is a hyperbolicity preserver when restricted to  $\mathbb{R}_n[z]$ , or
- (b)  $T$  is given by  $T(f) = \alpha(f)P$ , where  $\alpha : \mathbb{C}_n[z] \rightarrow \mathbb{C}$  is a linear functional and  $P$  is a hyperbolic polynomial.

We prove this by induction on  $n \in \mathbb{N}$ . If  $n = 0$  there is nothing to prove, so we may assume that  $n$  is a positive integer. Note that  $T$  restricts to a linear operator  $T' : \pi_{n-1}(\mathbb{R}) \rightarrow \pi(\mathbb{R})$  and that by induction  $T'$  must be of the form (a) or (b) above. Suppose  $T' = e^{i\theta} \tilde{T}'$ , where  $\tilde{T}'$  is a hyperbolicity preserver up to degree  $n - 1$ . If  $T(z^n) = e^{i\theta} f_n$ , where  $f_n \in \mathbb{R}[z]$  (actually,  $f_n \in \mathcal{H}_1(\mathbb{R}) \cup \{0\}$ ), then  $T$  is of the form (a). Hence we may assume that  $T(z^n) = e^{i\gamma} f_n$ , where  $0 \leq \gamma < 2\pi$ . We may also assume that  $\gamma - \theta$  is not an integer multiple of  $\pi$  and that  $f_n$  is a hyperbolic

polynomial. Suppose there is an integer  $k < n$  such that  $T(z^k)$  is not a constant multiple of  $f_n$ . Let  $M$  be the largest such  $k$  and set  $R(z) = e^{-i\theta}T(z^M)$ . Then

$$e^{-i\theta}T[z^M(1+z)^{n-M}] = R(z) + (r + e^{i(\gamma-\theta)})f_n(z) \quad \text{for some } r \in \mathbb{R}.$$

But this polynomial is supposed to be a complex constant multiple of a hyperbolic polynomial, which can only happen if  $R$  and thus  $T(z^M)$  is a constant multiple of  $f_n$ . This contradiction means that  $T$  must be as in (b) above with  $P = f_n$ .

Assume now that  $T'$  is as in (b). If  $T(z^n)$  is a constant multiple of  $P$  there is nothing to prove, so we may assume  $T(z^n) = e^{i\theta}f_n$ , where  $0 \leq \theta < 2\pi$  and  $f_n$  is a hyperbolic polynomial that is not a constant multiple of  $P$ . Suppose there is an integer  $k < n$  such that  $\alpha(z^k)e^{-i\theta} \notin \mathbb{R}$ , and let  $M$  be the largest such integer. Then

$$e^{-i\theta}T[z^M(1+z)^{n-M}] = (\alpha(z^M)e^{-i\theta} + r)P(z) + f_n(z) \quad \text{for some } r \in \mathbb{R}.$$

However, the latter polynomial should be a complex constant multiple of a hyperbolic polynomial, and this can happen only if  $\alpha(z^M)e^{-i\theta} \in \mathbb{R}$ , which contradicts the above assumption. This means that  $T$  must be as in (a). □

*Proof of Corollary 1.* Note first that if  $T : \mathbb{R}[z] \rightarrow \mathbb{R}[z]$  is as in (a), (b) or (c) of Corollary 1 then by Theorem 2, we have that  $T$  preserves hyperbolicity up to any degree  $n \in \mathbb{N}$ . Conversely, if  $T : \mathbb{R}[z] \rightarrow \mathbb{R}[z]$  preserves hyperbolicity then for any  $n \in \mathbb{N}$ , the restriction  $T : \mathbb{R}_n[z] \rightarrow \mathbb{R}[z]$  preserves hyperbolicity (up to degree  $n$ ). The case when  $\dim_{\mathbb{R}} T(\mathbb{R}[z]) \leq 2$  is clear. Suppose now that  $\dim_{\mathbb{R}} T(\mathbb{R}[z]) > 2$  and that  $T[(z+w)^n] \in \mathcal{H}_2(\mathbb{R})$  for some  $n \in \mathbb{N}$ . Then by Lemma 4 we have  $T[(z+w)^m] \in \mathcal{H}_2(\mathbb{C}) \cup \{0\}$  for all  $m \leq n$ , and since the latter polynomial has real coefficients, we get  $T[(z+w)^m] \in \mathcal{H}_2(\mathbb{R}) \cup \{0\}$  for all  $m \leq n$ . Similarly, if  $T[(z-w)^n] \in \mathcal{H}_2(\mathbb{R})$ , then  $T[(z-w)^m] \in \mathcal{H}_2(\mathbb{R}) \cup \{0\}$  for all  $m \leq n$ . It follows that if  $\dim_{\mathbb{R}} T(\mathbb{R}[z]) > 2$  then either  $T[(z+w)^n] \in \mathcal{H}_2(\mathbb{R}) \cup \{0\}$  for all  $n \in \mathbb{N}$  or  $T[(z-w)^n] \in \mathcal{H}_2(\mathbb{R}) \cup \{0\}$  for all  $n \in \mathbb{N}$ . □

By appropriately modifying the arguments in the proof of Corollary 1, one can easily check that Corollary 2 follows readily from Theorem 4.

3.2. *The transcendental characterization.* We will need a lemma due to Szász; see [Sz43, Lem. 3].

LEMMA 5 (Szász). *Let  $m, n \in \mathbb{N}$  with  $m \leq n$ , and suppose that  $f(z) = \sum_{k=m}^n c_k z^k \in \mathbb{C}[z]$ . If  $f(z) \in \mathcal{H}_1(\mathbb{C})$  and  $c_m c_n \neq 0$  then, for any  $r \geq 0$ ,*

$$|f(z)| \leq |c_m| r^m \exp\left(r \frac{|c_{m+1}|}{|c_m|} + 3r^2 \frac{|c_{m+1}|^2}{|c_m|^2} + 3r^2 \frac{|c_{m+2}|}{|c_m|}\right)$$

whenever  $|z| \leq r$ .

For  $k, n \in \mathbb{N}$ , let  $(n)_k = k! \binom{n}{k} = n(n-1) \cdots (n-k+1)$  if  $k \leq n$  and  $(n)_k = 0$  if  $n < k$  denote as usual the Pochhammer symbol.

**THEOREM 12.** *Let  $F(z, w) = \sum_{k=0}^{\infty} P_k(z)w^k$  be a formal power series in  $w$  with polynomial coefficients. Then  $F(z, w) \in \mathcal{H}_2(\mathbb{C})$  if and only if*

$$\sum_{k=0}^n (n)_k P_k(z)w^k \in \mathcal{H}_2(\mathbb{C}) \cup \{0\}$$

for all  $n \in \mathbb{N}$ .

*Proof.* Suppose that  $F(z, w) = \sum_{k=0}^{\infty} P_k(z)w^k \in \overline{\mathcal{H}}_2(\mathbb{C})$  has polynomial coefficients. Given  $n \in \mathbb{N}$ , the sequence  $\{(n)_k\}_{k=0}^n$  is a multiplier sequence, and since it is nonnegative, it is a stability preserver by [Lemma 3](#). By [Corollary 2](#) and [Lemma 4](#), this multiplier extends to a map  $\Lambda : \mathcal{H}_2(\mathbb{C}) \rightarrow \mathcal{H}_2(\mathbb{C}) \cup \{0\}$ . If  $\tilde{F}_m(z, w) = \sum_{k=0}^{N_m} P_{m,k}(z)w^k$  is a sequence of polynomials in  $\mathcal{H}_2(\mathbb{C})$  converging to  $F(z, w)$ , uniformly on compacts, then  $P_{m,k}(z) \rightarrow P_k(z)$  as  $m \rightarrow \infty$  uniformly on compacts for fixed  $k \in \mathbb{N}$ . But then  $\Lambda[\tilde{F}_m(z, w)] \rightarrow \Lambda[F(z, w)]$  uniformly on compacts, which gives  $\sum_{k=0}^n (n)_k P_k(z)w^k \in \mathcal{H}_2(\mathbb{C}) \cup \{0\}$ .

Conversely, suppose that  $\sum_{k=0}^n (n)_k P_k(z)w^k \in \mathcal{H}_2(\mathbb{C}) \cup \{0\}$  for all  $n \in \mathbb{N}$ , and let  $F_n(z, w) = \sum_{k=0}^n (n)_k n^{-k} P_k(z)w^k$ .

**CLAIM.** *Given  $r > 0$ , there is a constant  $C_r$  such that*

$$|F_n(z, w)| \leq C_r \quad \text{for } |z| \leq r, |w| \leq r \text{ and all } n \in \mathbb{N}.$$

This [claim](#) proves the theorem since  $\{F_n(z, w)\}_{n=0}^{\infty}$  is then a normal family whose convergent subsequences converge to  $F(z, w)$  (due to the fact that  $n^{-k}(n)_k \rightarrow 1$  for all  $k \in \mathbb{N}$  as  $n \rightarrow \infty$ ).

We first prove the [claim](#) in the special case when  $P_k(z) \in \mathbb{R}[z]$  for all  $k \in \mathbb{N}$  and  $P_K(z)$  is a nonzero constant, where  $K$  is the first index for which  $P_K(z) \neq 0$ .

*Proof of the claim in the special case.* Let  $|P_K(z)| = A$ ,

$$B_r = \max\{|P_{K+1}(z)| : |z| \leq r\} \quad \text{and} \quad D_r = \max\{|P_{K+2}(z)| : |z| \leq r\}.$$

Then, if we fix  $\zeta \in \mathbb{C}$  with  $\Im(\zeta) > 0$ , we have  $F_n(\zeta, w) \in \mathcal{H}_1(\mathbb{C}) \cup \{0\}$ , and by [Lemma 5](#)

$$(3-2) \quad |F_n(\zeta, w)| \leq Ar^K \exp\left(r \frac{B_r}{A} + 3r^2 \frac{B_r^2}{A^2} + 3r^2 \frac{D_r}{A}\right)$$

whenever  $\Im(\zeta) > 0$ ,  $|\zeta| \leq r$  and  $|w| \leq r$ . If  $\zeta \in \mathbb{C}$  is fixed with  $\Im(\zeta) < 0$ , then  $F_n(\zeta, -w) \in \mathcal{H}_1(\mathbb{C})$  (since  $F_n(z, w)$  has real coefficients and  $\overline{F_n(z, w)} = F_n(\bar{z}, \bar{w})$ ). By [Lemma 5](#), this means that (3-2) holds also for  $\Im(\zeta) < 0$  and by continuity also for  $\zeta \in \mathbb{R}$ , which proves the [claim](#).  $\square$

Next we assume  $\deg(P_K(z)) = d \geq 1$ . An application of [Theorem 4](#) verifies that  $T = d/dz$  preserves stability, and [Lemma 4](#) shows  $T = \partial/\partial z$  preserves stability in two variables. Hence  $\partial F_n(z, w)/\partial z \in \mathcal{H}_2(\mathbb{R}) \cup \{0\}$  if  $F_n(z, w) \in \mathcal{H}_2(\mathbb{R}) \cup \{0\}$ . To

deal with this case, it is therefore enough to prove that if  $|\partial F_n(z, w)/\partial z| \leq C_r$  for  $|z| \leq r, |w| \leq r$  and all  $n \in \mathbb{N}$ , then there is a constant  $D_r$  such that  $|F_n(z, w)| \leq D_r$  for  $|z| \leq r, |w| \leq r$  and all  $n \in \mathbb{N}$ . Clearly,  $F_n(0, w) \in \mathcal{H}_1(\mathbb{R}) \cup \{0\}$  for all  $n \in \mathbb{N}$ . Moreover, if  $m$  is the first index such that  $P_m(0) \neq 0$ , then for  $n \geq m$  we have

$$F_n(0, w) = (n)_{m,n} n^{-m} P_m(0) w^m + (n)_{m+1,n} n^{-m-1} P_{m+1}(0) w^{m+1} + \dots \in \mathcal{H}_1(\mathbb{R}),$$

which by [Lemma 5](#) gives

$$|F_n(0, w)| \leq |P_m(0)| r^m \exp\left(r \frac{|P_{m+1}(0)|}{|P_m(0)|} + 3r^2 \frac{|P_{m+1}(0)|^2}{|P_m(0)|^2} + 3r^2 \frac{|P_{m+2}(0)|}{|P_m(0)|}\right)$$

for  $|z| \leq r$ . Here we have used  $(n)_k n^{-k} \leq 1$  and  $(n)_{k+1} n^{-k-1} / (n)_k n^{-k} \leq 1$  for  $0 \leq k \leq n$ . Denote by  $E_r$  the right side of the inequality above. Suppose

$$\left| \frac{\partial F_n(z, w)}{\partial z} \right| \leq C_r \quad \text{for } |z| \leq r, |w| \leq r \text{ and all } n \in \mathbb{N}.$$

Then

$$F_n(z, w) = F_n(0, w) + z \int_0^1 \frac{\partial F_n}{\partial z}(zt, w) dt,$$

so

$$|F_n(z, w)| \leq E_r + r C_r \quad \text{for } |z| \leq r, |w| \leq r \text{ and all } n \in \mathbb{N}.$$

Next we prove the above [claim](#) in the general case. We will need a property of multivariate stable polynomials established in [\[BB06, Cor. 1\]](#):

FACT. *If  $h = g + if \in \mathcal{H}_n(\mathbb{C})$ , then  $f, g \in \mathcal{H}_n(\mathbb{R})$ .*

Now this means that if we let  $P_k(z) = R_k(z) + iI_k(z)$  then we may write

$$F_n(z, w) = F_n^{\Re}(z, w) + iF_n^{\Im}(z, w),$$

with  $F_n^{\Re}(z, w), F_n^{\Im}(z, w) \in \mathcal{H}_2(\mathbb{R}) \cup \{0\}$ , where

$$F_n^{\Re}(z, w) = \sum_{k=0}^n (n)_k n^{-k} R_k(z) w^k \quad \text{and} \quad F_n^{\Im}(z, w) = \sum_{k=0}^n (n)_k n^{-k} I_k(z) w^k.$$

By the above, there are constants  $A_r$  and  $B_r$  such that

$$|F_n^{\Re}(z, w)| \leq A_r \text{ and } |F_n^{\Im}(z, w)| \leq B_r \quad \text{for } |z| \leq r, |w| \leq r \text{ and all } n \in \mathbb{N}.$$

Hence  $|F_n(z, w)| \leq \sqrt{A_r^2 + B_r^2}$  for  $|z| \leq r, |w| \leq r$  and all  $n \in \mathbb{N}$ , which proves the [claim](#) in the general case. □

We can now prove the transcendental characterizations of hyperbolicity and stability preservers.

*Proof of Theorems 5 and 6.* We only prove [Theorem 6](#) since the proof of [Theorem 5](#) is almost identical. [Theorem 6](#) follows quite easily from [Theorem 12](#)

and [Corollary 2](#). Indeed, note that  $T[(1-zw)^n] \in \mathcal{H}_2(\mathbb{C})$  if and only if  $T[(z+w)^n] \in \mathcal{H}_2(\mathbb{C})$ . Since

$$T[(1-zw)^n] = \sum_{k=0}^n \binom{n}{k} \frac{(-1)^k T(z^k)}{k!} w^k$$

for all  $n \in \mathbb{N}$ , we deduce the desired conclusion by comparing the above expression with the modified symbol  $G_T(z, w)$  introduced in [Notation 3](#). □

Finally, we show how Pólya and Schur’s algebraic and transcendental characterizations of multiplier sequences ([Theorem 1](#)) follow from our results.

*Proof of Theorem 1.* We may assume that  $\lambda(0) = 1$ . Statements (i)–(iv) are all true if  $\dim_{\mathbb{R}} T(\mathbb{R}[z]) \leq 2$ , since then  $\lambda(j) = 0$  for all  $j \geq 2$ . Hence we may assume that  $\dim_{\mathbb{R}} T(\mathbb{R}[z]) > 2$ . [Corollary 1](#) implies that either

$$T[(1-zw)^n] = \sum_{k=0}^n (-1)^k \binom{n}{k} \lambda(k) (zw)^k \in \mathcal{H}_2(\mathbb{R}) \quad \text{for all } n \in \mathbb{N}$$

or  $T[(1+zw)^n] = \sum_{k=0}^n \binom{n}{k} \lambda(k) (zw)^k \in \mathcal{H}_2(\mathbb{R}) \quad \text{for all } n \in \mathbb{N}.$

We claim that if  $f(z) \in \mathbb{R}[z]$ , then  $f(zw) \in \mathcal{H}_2(\mathbb{R})$  if and only if all the zeros of  $f$  are real and nonnegative. Suppose first that  $f(zw)$  is real stable. Letting  $z = w = t$ , we see that  $f(t^2)$  is hyperbolic, which can only happen if all the zeros of  $f$  are nonnegative (since  $a + t^2$  is hyperbolic if and only if  $a \leq 0$ ). On the other hand, if  $f$  has only real nonpositive zeros, then  $f(zw)$  factors as  $f(zw) = C \prod_{j=0}^n (zw + \alpha_j)$ , where  $\alpha_j \in \mathbb{R}$  for  $1 \leq j \leq n$ . Now  $zw + \alpha_j \in \mathcal{H}_2(\mathbb{R})$  if and only if  $\alpha_j \leq 0$ . Hence (i) is equivalent to (iv), and by [Theorem 5](#), we also have that (ii) is equivalent to (iv). The equivalence of (ii) and (iii) is Laguerre’s classical result. □

3.3. *Closed circular domains and their boundaries.* Recall [Definitions 1](#) and [4](#), [Notation 4](#) and the linear operators  $\phi_n$  introduced in [Notation 5](#). In particular, an  $H$ -stable polynomial in the sense of [Definition 4](#) is precisely a stable polynomial in the sense of [Definition 1](#).

LEMMA 6. *Let  $T : \mathbb{C}_n[z] \rightarrow \mathbb{C}_m[z]$  be a linear operator, and suppose  $m$  is minimal, i.e.,  $m = \max\{\deg T(f) : f \in \mathbb{C}_n[z]\}$ . Let  $C = \Phi^{-1}(H)$  be an open circular domain, where  $\Phi$  is a Möbius transformation as in (2-2), and let  $S : \mathbb{C}_n[z] \rightarrow \mathbb{C}_m[z]$  be the linear operator defined by  $S = \phi_m^{-1} T \phi_n$ . The following are equivalent:*

- (i)  $T(f)$  is  $C$ -stable or zero whenever  $f$  is of degree  $n$  and  $C$ -stable;
- (ii)  $S(f)$  is  $H$ -stable or zero whenever  $f$  is of degree  $n$  and  $H$ -stable;
- (iii)  $S(f)$  is  $H$ -stable or zero whenever  $f$  is of degree at most  $n$  and  $H$ -stable.

The following are also equivalent:

- (i)  $T(f)$  is  $\partial C$ -stable or zero whenever  $f$  is of degree  $n$  and  $\partial C$ -stable;
- (ii)  $S(f)$  is  $\mathbb{R}$ -stable or zero whenever  $f$  is of degree  $n$  and  $\mathbb{R}$ -stable;
- (iii)  $S(f)$  is  $\mathbb{R}$ -stable or zero whenever  $f$  is of degree at most  $n$  and  $\mathbb{R}$ -stable.

*Proof.* Note first that the equivalences of (ii) and (iii) and of (ii) and (iii) are simple consequences of the density argument used in Section 2.2. Let us now show that (i) and (ii) are equivalent. This is obvious if  $C$  is an open half-plane, i.e., if  $c = 0$  (cf. (2-3)). Therefore we assume that  $c \neq 0$  and that the boundary of  $C$  is a circle. If  $C$  is an open disk, then  $a/c$  is in the open lower half-plane, so that  $-cz + a$  is  $H$ -stable. Moreover,  $-d/c \in \partial C$ , and thus  $cz + d$  is  $C$ -stable. Hence  $f$  is  $H$ -stable if and only if  $\phi_n(f)$  is  $C$ -stable, so the assertion follows in this case as well.

It remains to prove that (i) and (ii) are equivalent in the case when  $C$  is the open complement of a (closed) disk.

*Proof that (i) implies (ii).* Clearly, we may assume that  $T$  is not the trivial (identically zero) operator. Let  $p(z) = \sum_{k=0}^n a_k z^k$  be an  $H$ -stable polynomial of degree  $n$  and suppose first that  $\sum_{k=0}^n a_k a^k c^{n-k} \neq 0$ . Then  $\phi_n(p)$  is a  $C$ -stable polynomial of degree  $n$  so that by assumption  $T(\phi_n(p))$  is  $C$ -stable or zero. If  $S(p) \neq 0$ , it follows that we can express  $S(p)$  uniquely as  $S(p) = (-cz + a)^{r(p)} S_0(p)$ , where  $S_0(p)$  is  $H$ -stable and  $r(p)$  is a nonnegative integer. By a continuity argument and an application of Hurwitz’s theorem, a factorization as above holds for any  $H$ -stable polynomial of degree  $n$ . Since the set of  $H$ -stable polynomials of degree  $n$  is dense in  $\pi_n(H') \cup \{0\}$  — that is, the set of  $H$ -stable polynomials of degree at most  $n$  union the zero polynomial — we deduce that such a factorization holds for the image under  $S$  of any  $H$ -stable polynomial  $p$  of degree at most  $n$ , namely  $S(p) = (-cz + a)^{r(p)} S_0(p)$ , where  $S_0(p)$  is  $H$ -stable or zero and  $r(p)$  is a nonnegative integer.

Fix a basis  $\{p_j(z)\}_{j=0}^n$  of  $\mathbb{C}_n[z]$  consisting of strictly  $H$ -stable (that is,  $\overline{H}$ -stable) polynomials of degree  $n$ . We distinguish two cases:

First suppose  $S(f) \neq 0$  for all strictly  $H$ -stable polynomials  $f$  of degree  $n$ . Since the topological space of strictly stable polynomials of degree  $n$  is (path-) connected, we have by Hurwitz’s theorem that  $r(f)$  is constant on the set of strictly  $H$ -stable polynomials of degree  $n$ . Thus, by the minimality assumption on  $m$  and the fact that  $\phi_n$  is invertible, we must have  $\deg(T(\phi_n(p_k))) = m$  for some  $k$ . It follows that  $r(p_k) = 0$ ; hence  $S(f) = S_0(f)$  for any strictly  $H$ -stable polynomial  $f$  of degree  $n$ . Using again a standard density argument and Hurwitz’s theorem, we deduce that  $S$  preserves ( $H$ -)stability up to degree  $n$ .

Suppose now that  $S(f) = 0$  for some strictly  $H$ -stable polynomial  $f$  of degree  $n$ , and let  $g \in \mathbb{C}_n[z]$ . Clearly,  $f + \epsilon g$  is strictly  $H$ -stable for all  $\epsilon > 0$  small enough.

By the above,

$$S(g) = \epsilon^{-1}S(f + \epsilon g) = (-cz + a)^{r(g)}S_0(g),$$

where  $S_0(g)$  is  $H$ -stable or zero. It follows that  $V := S(\mathbb{C}_n[z])$  is a  $\mathbb{C}$ -linear space such that every nonzero polynomial in  $V$  is a  $(-cz + a)^r$ -multiple of an  $H$ -stable polynomial. We know that  $r(p_k) = 0$  for the strictly  $H$ -stable polynomial  $p_k$  above. Assume that  $h \in \mathbb{C}_n[z]$  is such that  $r(h) \neq 0$ . Since  $r(p_k) = 0$  and

$$S(h) + \delta S(p_k) = S(h + \delta p_k) = (-cz + a)^{r(h+\delta p_k)}S_0(h + \delta p_k) \in V,$$

where  $S_0(h + \delta p_k)$  is  $H$ -stable or zero, we conclude that  $S(h) + \delta S(p_k)$  is  $H$ -stable or zero for all  $\delta \neq 0$ . Letting  $\delta \rightarrow 0$ , we have by Hurwitz’s theorem that either  $S(h) = 0$  or  $S(h)$  is  $H$ -stable. However, this contradicts the fact that  $a/c \in H$  and  $S(h)(a/c) = 0$ , which follows from the assumption that  $r(h) \neq 0$ . Hence all nonzero polynomials in  $V$  are  $H$ -stable. Thus we deduce that  $S$  preserves  $(H)$ -stability up to degree  $n$  in this case as well.  $\square$

*Proof that (ii) implies (i).* Since the set of  $H$ -stable polynomials of degree  $n$  is dense in the set of  $H$ -stable polynomials of degree at most  $n$ , it follows that  $S$  preserves  $H$ -stability on the latter set (i.e.,  $S$  preserves  $H$ -stability up to degree  $n$ ). Let  $f$  be a  $C$ -stable polynomial of degree  $n$ . Then  $\phi_n^{-1}(f)$  is  $H$ -stable. Hence so is  $S(\phi_n^{-1}(f))$ , and thus  $T(f) = \phi_m(S(\phi_n^{-1}(f)))$  is a  $C$ -stable polynomial (note that  $-d/c \in \partial C$ ).  $\square$

The equivalence of (i) and (ii) follows just as above by replacing “strictly  $H$ -stable” with “strictly hyperbolic”, that is, real- and simple-rooted.  $\square$

NOTATION 7. Given a polynomial  $f \in \mathbb{C}[z, w]$  of degree at most  $m$  in  $z$  and at most  $n$  in  $w$  and a Möbius transformation  $\Phi$  as in (2-2), we let

$$\begin{aligned} \phi_{m,z}(f)(z, w) &= (cz + d)^m f(\Phi(z), w), \\ \phi_{n,w}(f)(z, w) &= (cw + d)^n f(z, \Phi(w)). \end{aligned}$$

LEMMA 7. Let  $f(z, w) \in \mathbb{C}[z, w]$  be of degree at most  $m$  in  $z$  and at most  $n$  in  $w$ , and let  $\Phi : C \rightarrow H$  be a Möbius transformation as in (2-2). If either

- (a)  $C$  is not the exterior of a disk, or
- (b)  $C$  is the exterior of a disk and
  - (b1) the degree in  $z$  of  $\phi_{m,z}(f)(z, w)$  is  $m$ , and
  - (b2) the degree in  $w$  of  $\phi_{n,w}\phi_{m,z}(f)(z, w)$  is  $n$ ,

then  $f$  is  $H$ -stable if and only if  $\phi_{n,w}\phi_{m,z}(f)$  is  $C$ -stable.

*Proof.* The equivalence is clear when  $C$  is a disk or a half-plane since in these cases  $-cz + a$  is  $H$ -stable and  $cz + d$  is  $C$ -stable (cf. (2-3)). Hence we may assume that  $C$  is the exterior of a disk. Note that if  $g(z)$  is a polynomial of

degree  $k$ , then  $a/c$  is not a zero of  $\phi_k^{-1}(g)(z)$ . In particular, if  $g(z)$  is a  $C$ -stable polynomial of degree  $k$ , then  $\phi_k^{-1}(g)(z)$  is an  $H$ -stable polynomial of degree  $k$ . Now since  $-d/c \in \partial C$ , we have that  $cz + d$  is  $C$ -stable, and therefore  $\phi_{n,w}\phi_{m,z}(f)$  is  $C$ -stable if  $f$  is  $H$ -stable, which proves one of the implications.

Conversely, suppose that  $G(z, w) := \phi_{n,w}\phi_{m,z}(f)(z, w) = \sum_{k=0}^n Q_k(z)w^k$  is  $C$ -stable. Then so is  $\lambda^{-n}G(z, \zeta + \lambda(w - \zeta))$  whenever  $\lambda \geq 1$ , where  $\zeta$  is the center of  $C'$ . Letting  $\lambda \rightarrow \infty$ , we see by Hurwitz's theorem that  $(w - \zeta)^n Q_n(z)$  is  $C$ -stable. Hence, so is  $Q_n(z)$ . For every  $z_0 \in C$  the degree of  $G(z_0, w)$  is  $n$ , from which it follows that  $\phi_{n,w}^{-1}(G)(z, w) = \phi_{m,z}(f)(z, w) \neq 0$  whenever  $z \in C$  and  $w \in H$ . Similarly, if  $\phi_{m,z}(f)(z, w) = \sum_{k=0}^m P_k(w)z^k$ , then  $P_m(w)$  is  $H$ -stable so that  $\phi_{m,z}(f)(z, w_0)$  has degree  $m$  for every  $w_0 \in H$ . We conclude that  $f(z, w) = \phi_{m,z}^{-1}\phi_{n,w}^{-1}(G)(z, w)$  is  $H$ -stable, as claimed.  $\square$

The following lemma is a simple consequence of Hurwitz's theorem, since boundedness prevents zeros from escaping to infinity.

LEMMA 8. *Let  $\Omega_1$  be a path-connected subset of  $\mathbb{C}$ , and let  $\Omega_2$  be a bounded subset of  $\mathbb{C}$ . If  $T : \mathbb{C}_n[z] \rightarrow \mathbb{C}[z]$  is a linear operator such that*

$$T : \pi_n(\Omega_1) \setminus \pi_{n-1}(\Omega_1) \rightarrow \pi(\Omega_2),$$

*then all the polynomials in the image of  $\pi_n(\Omega_1) \setminus \pi_{n-1}(\Omega_1)$  have the same degree.*

Note that in the hypothesis of Lemma 8, we do not allow the identically zero polynomial to be in the image of  $\pi_n(\Omega_1) \setminus \pi_{n-1}(\Omega_1)$ .

*Proof of Theorem 7.* Suppose  $T : \mathbb{C}_n[z] \rightarrow \mathbb{C}_m[z]$ , where as before  $m$  is minimal in the sense that  $m = \max\{\deg T(f) : f \in \mathbb{C}_n[z]\}$ . By combining Lemma 6 with Hurwitz's theorem we see  $T : \pi_n(C') \setminus \pi_{n-1}(C') \rightarrow \pi(C') \cup \{0\}$  if and only if  $\phi_m^{-1}T\phi_n : \pi_n(H') \rightarrow \pi(H') \cup \{0\}$ . The case  $\dim_{\mathbb{C}} T(\mathbb{C}_n[z]) \leq 1$  is clear. If  $\dim_{\mathbb{C}} T(\mathbb{C}_n[z]) > 1$  then by Theorem 4, we have

$$\phi_m^{-1}T\phi_n : \pi_n(H') \rightarrow \pi(H') \cup \{0\}$$

if and only if  $f(z, w) := \phi_m^{-1}T\phi_n [(z + w)^n]$  is  $H$ -stable. Now the polynomial in (b) of Theorem 7 is precisely  $\phi_{n,w}\phi_{m,z}(f)$ . Moreover, by Lemma 7(a) we may assume that  $C$  is the exterior of a disk. Therefore, in order to complete the proof it only remains to show that conditions (b1) and (b2) of Lemma 7 are satisfied.

If there were two different  $\bar{C}$ -stable polynomials of degree  $n$  that were mapped by  $T$  on polynomials of different degrees, then by Lemma 8 there would be a  $\bar{C}$ -stable polynomial  $g$  of degree  $n$  in the kernel of  $T$ . However, since  $\phi_n^{-1}(g)$  is strictly  $H$ -stable it would then follow from Lemmas 1 and 2 that  $\phi_m^{-1}T\phi_n$  and hence also that  $T$  has range of dimension at most one, which is not the case. We infer that  $\deg T(h) = m$  for any  $\bar{C}$ -stable polynomial  $h$  of degree  $n$ .



Clearly,  $\phi_{m,z}(f)(z, w) = T[\phi_{n,z}((z + w)^n)]$ . Let  $w_0 \in H \setminus \{-a/c\}$ . The only zero of the degree  $n$  polynomial

$$p_{w_0}(z) := \phi_{n,z}((z + w_0)^n) = ((a + w_0c)z + b + w_0d)^n$$

is  $\Phi^{-1}(-w_0) \in \bar{C}'$ , so  $p_{w_0}(z)$  is  $\bar{C}$ -stable. By the previous paragraph we then have  $\deg(\phi_{m,z}(f)(z, w_0)) = \deg(T[p_{w_0}(z)]) = m$ , which verifies condition (b1) of Lemma 7.

Note next that the coefficient of  $w^n$  in the polynomial defined in (b) of Theorem 7 is  $T[(2acz + bc + ad)^n]$ . We claim the polynomial  $(2acz + bc + ad)^n$  is  $\bar{C}$ -stable and of degree  $n$ . Since the image of any  $\bar{C}$ -stable polynomial of degree  $n$  is of degree  $m$ , this would verify condition (b2) of Lemma 7. To prove the claim, note first that since  $C$  is the exterior of a disk we have that  $ac \neq 0$ , so  $\deg(2acz + bc + ad)^n = n$ . Let  $\zeta = -b/a$  and  $\eta = -d/c$ . Since  $\Phi(\zeta) = 0$  and  $\Phi(\eta) = \infty$ , we have that  $\zeta, \eta \in \partial C$ , which implies — again by the assumption that  $C$  is the exterior of a disk — that the zero of  $(2acz + bc + ad)^n$ , namely

$$-\frac{bc+ad}{2ac} = \frac{\zeta+\eta}{2},$$

is in  $\bar{C}'$ . Thus  $(2acz + bc + ad)^n$  is  $\bar{C}$ -stable and of degree  $n$ , as required.  $\square$

*Proof of Theorem 8.* Let  $m = \max\{\deg T(f) : f \in \mathbb{C}_n[z]\}$ . Lemma 6 says that  $T : \pi_n(\partial C) \rightarrow \pi(\partial C) \cup \{0\}$  if and only if  $\phi_m^{-1}T\phi_n : \pi_n(\mathbb{R}) \rightarrow \pi(\mathbb{R}) \cup \{0\}$ . Using this and Theorem 3, it is not difficult to verify the theorem in the case  $\dim_{\mathbb{C}} T(\mathbb{C}_n[z]) \leq 2$ . Let  $f(z, w) = \phi_m^{-1}T\phi_n[(z + w)^n]$ . To settle the remaining cases, note first that by Theorem 3(c) and (d), we have that

$$T : \pi_n(\partial C) \rightarrow \pi(\partial C) \cup \{0\}$$

if and only if  $f(z, w)$  or  $f(z, -w)$  is a complex multiple of a real stable polynomial. Now the condition that  $f(z, w)$  is a complex multiple of a real stable polynomial is equivalent to saying that  $f(z, w)$  is both  $H$ -stable and  $H^r$ -stable; see [BB06, Prop. 3] (note that  $H^r = -H$ ). By Theorem 7, we know that  $f(z, w)$  is  $H$ -stable if and only if the polynomial in (c) of Theorem 8, that is,  $\phi_{n,w}\phi_{m,z}(f)(z, w)$ , is  $C$ -stable. On the other hand, since  $-cz + a$  is  $H^r$ -stable and  $cz + d$  is  $C^r$ -stable (since  $C^r$  is not the exterior of a disk), we also have that  $f(z, w)$  is  $H^r$ -stable if and only if  $\phi_{n,w}\phi_{m,z}(f)$  is  $C^r$ -stable. It follows in similar fashion that condition (d) in Theorem 8 is equivalent to saying that  $f(z, -w)$  is a complex multiple of a real stable polynomial.  $\square$

Corollaries 3 and 4 are immediate consequences of Theorems 7 and 8, respectively.

#### 4. Open problems

As we already noted in [Section 1](#), [Problems 1](#) and [2](#) have a long and distinguished history. In this paper we completely solved them for a particularly relevant type of sets, namely all closed circular domains and their boundaries. Among the most interesting remaining cases that are currently under investigation are (a)  $\Omega$  is an open circular domain, (b)  $\Omega$  is a sector or a double sector, (c)  $\Omega$  is a strip, (d)  $\Omega$  is a half-line, and (e)  $\Omega$  is an interval.

Let us briefly comment on the importance of the above cases.

Case (a). The classical notion of Hurwitz (or continuous-time) stability refers to univariate polynomials whose roots all lie in the open left half-plane. Its well-known discrete-time version — often called Schur or Schur-Cohn stability — is when all the roots of a polynomial lie in the open unit disk. Both these notions are fundamental and widely used in e.g. control theory and engineering sciences. (The authors easily found several hundred publications in both purely mathematical and applied areas devoted to the study of Hurwitz and Schur stability for various classes of polynomials as well as continuous or discrete-time systems.)

Case (b). Polynomials and transcendental entire functions whose zeros are all confined to a (double) sector often appear as solutions to, for example, Schrödinger-type equations with polynomial potential or, more generally, any linear ordinary differential equation with polynomial coefficients and constant leading coefficient; see for instance [\[HR89\]](#), [\[Hil69\]](#). Concrete information about linear transformations preserving this class of polynomials and entire functions turns out to be very useful for asymptotic integration of linear differential equations.

Case (c). Specific examples of linear transformations preserving the class of polynomials whose roots all lie in the strip  $|\Im(z)| \leq \alpha$  for  $\alpha > 0$  can be found in the famous articles by Pólya [\[Pól126\]](#), Lee and Yang [\[LY52\]](#) and de Bruijn [\[dB50\]](#). A complete characterization of all such linear transformations would shed light on a great many problems in the theory of Fourier transforms and operator theory [\[BB08\]](#), [\[BBCV07\]](#).

Case (d). Polynomials whose roots all lie on either the positive or negative half-axis appeared already in Laguerre's works and in Pólya and Schur's fundamental paper [\[PS14\]](#) and have been frequently used in various contexts ever since. In addition to their description of multiplier sequences of the first kind in [\[PS14\]](#), Pólya and Schur also classified multiplier sequences of the second kind, i.e., diagonal linear operators mapping polynomials with all real roots and of the same sign to polynomials with all real roots. A natural extension of these results would be to characterize all linear transformations with this property. Solving case (d) would answer this question and thus complete the program initiated by Pólya and Schur over 90 years ago.

Case (e). Numerous papers have been devoted to this case of Problems 1 and 2 and its connections with Pólya frequency functions, integral equations with totally positive or sign regular kernels, Laplace transforms, the theory of orthogonal polynomials, etc. A complete description of all linear transformations preserving the set of polynomials whose zeros all lie in a given interval would therefore have many interesting applications and would also answer several of the questions raised in e.g. [CPP02b], [INS91], [IN87], [IN90], [IS89], [Pin02], [PS76] on these and related subjects.

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*E-mail address:* [julius@math.su.se](mailto:julius@math.su.se)

DEPARTMENT OF MATHEMATICS, STOCKHOLM UNIVERSITY, SE-106 91 STOCKHOLM, SWEDEN

*E-mail address:* [pbranden@math.kth.se](mailto:pbranden@math.kth.se)

DEPARTMENT OF MATHEMATICS, ROYAL INSTITUTE OF TECHNOLOGY, SE-100 44 STOCKHOLM, SWEDEN