Prescribing symmetric functions 
of the eigenvalues of the Ricci tensor

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Abstract

We study the problem of conformally deforming a metric to a prescribed symmetric function of the eigenvalues of the Ricci tensor. We prove an existence theorem for a wide class of symmetric functions on manifolds with positive Ricci curvature, provided the conformal class admits an admissible metric.

1. Introduction

Let \((M^n, g)\) be a smooth, closed Riemannian manifold of dimension \(n\). We denote the Riemannian curvature tensor by \(\text{Riem}\), the Ricci tensor by \(\text{Ric}\), and the scalar curvature by \(R\). In addition, the Weyl-Schouten tensor is defined by

\[
A = \frac{1}{(n-2)} \left( \text{Ric} - \frac{1}{2(n-1)} R g \right).
\]

This tensor arises as the “remainder” in the standard decomposition of the curvature tensor

\[
\text{Riem} = W + A \odot g,
\]

where \(W\) denotes the Weyl curvature tensor and \(\odot\) is the natural extension of the exterior product to symmetric \((0,2)\)-tensors (usually referred to as the Kulkarni-Nomizu product, [Bes87]). Since the Weyl tensor is conformally invariant, an important consequence of the decomposition (1.2) is that the transformation of the Riemannian curvature tensor under conformal deformations of metric is completely determined by the transformation of the symmetric \((0,2)\)-tensor \(A\).

In [Via00a] the second author initiated the study of the fully nonlinear equations arising from the transformation of \(A\) under conformal deformations.

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More precisely, let $g_u = e^{-2u}g$ denote a conformal metric, and consider the equation

$$
\sigma^{1/k}_k(g_u^{-1}A_u) = f(x),
$$

(1.3)

where $\sigma_k : \mathbb{R}^n \rightarrow \mathbb{R}$ denotes the elementary symmetric polynomial of degree $k$, $A_u$ denotes the Weyl-Schouten tensor with respect to the metric $g_u$, and $\sigma^{1/k}_k(g_u^{-1}A_u)$ means $\sigma_k(\cdot)$ applied to the eigenvalues of the $(1,1)$-tensor $g_u^{-1}A_u$ obtained by “raising an index” of $A_u$. Following the conventions of our previous paper [GV04], we interpret $A_u$ as a bilinear form on the tangent space with inner product $g$ (instead of $g_u$). That is, once we fix a background metric $g$, $\sigma_k(A_u)$ means $\sigma_k(\cdot)$ applied to the eigenvalues of the $(1,1)$-tensor $g^{-1}A_u$. To understand the practical effect of this convention, recall that $A_u$ is related to $A$ by the formula

$$
A_u = A + \nabla^2 u + du \otimes du - \frac{1}{2} |\nabla u|^2 g
$$

(see [Via00a]). Consequently, (1.3) is equivalent to

$$
\sigma^{1/k}_k(A + \nabla^2 u + du \otimes du - \frac{1}{2} |\nabla u|^2 g) = f(x)e^{-2u}.
$$

(1.4)

(1.5)

Note that when $k = 1$, then $\sigma_1(g^{-1}A) = \trace(A) = \frac{1}{2(n-1)} R$. Therefore, (1.5) is the problem of prescribing scalar curvature.

To recall the ellipticity properties of (1.5), following [Gar59] and [CNS85] we let $\Gamma^+_k \subset \mathbb{R}^n$ denote the component of $\{x \in \mathbb{R}^n | \sigma_k(x) > 0\}$ containing the positive cone $\{x \in \mathbb{R}^n | x_1 > 0, ..., x_n > 0\}$. A solution $u \in C^2(M^n)$ of (1.5) is elliptic if the eigenvalues of $A_u$ are in $\Gamma^+_k$ at each point of $M^n$; we then say that $u$ is admissible (or $k$-admissible). By a result of the second author, if $u \in C^2(M^n)$ is a solution of (1.5) and the eigenvalues of $A = A_g$ are everywhere in $\Gamma^+_k$, then $u$ is admissible (see [Via00a, Prop. 2]). Therefore, we say that a metric $g$ is $k$-admissible if the eigenvalues of $A = A_g$ are in $\Gamma^+_k$, and we write $g \in \Gamma^+_k(M^n)$.

In this paper we are interested in the case $k > n/2$. According to a result of Guan-Viaclovsky-Wang [GVW03], a $k$-admissible metric with $k > n/2$ has positive Ricci curvature; this is the geometric significance of our assumption. Analytically, when $k > n/2$ we can establish an integral estimate for solutions of (1.5) (see Theorem 3.5). As we shall see, this estimate is used at just about every stage of our analysis. Our main result is a general existence theory for solutions of (1.5):

**Theorem 1.1.** Let $(M^n, g)$ be a closed $n$-dimensional Riemannian manifold, and assume

(i) $g$ is $k$-admissible with $k > n/2$,

(ii) $(M^n, g)$ is not conformally equivalent to the round $n$-dimensional sphere.
Then given any smooth positive function $f \in C^\infty(M^n)$ there exists a solution $u \in C^\infty(M^n)$ of (1.5), and the set of all such solutions is compact in the $C^m$-topology for any $m \geq 0$.

Remark. The second assumption above is of course necessary, since the set of solutions of (1.5) on the round sphere with $f(x) = \text{constant}$ is non-compact, while for variable $f$ there are obstructions to existence. In particular, there is a “Pohozaev identity” for solutions of (1.5) which holds in the conformally flat case; see [Via00b]. This identity yields non-trivial Kazdan-Warner-type obstructions to existence (see [KW74]) in the case $(M^n, g)$ is conformally equivalent to $(S^n, g_{\text{round}})$. It is an interesting problem to characterize the functions $f(x)$ which may arise as $\sigma_k$-curvature functions in the conformal class of the round sphere, but we do not address this problem here.

1.1. Prior results. Due to the amount of research activity it has become increasingly difficult to provide even a partial overview of results in the literature pertaining to (1.5). Therefore, we will limit ourselves to those which are the most relevant to our work here.

In [Via02], the second author established global a priori $C^1$- and $C^2$-estimates for $k$-admissible solutions of (1.5) that depend on $C^0$-estimates. Since (1.5) is a convex function of the eigenvalues of $A_u$, the work of Evans and Krylov ([Eva82], [Kry93]) give $C^2,\alpha$ bounds once $C^2$-bounds are known. Consequently, one can derive estimates of all orders from classical elliptic regularity, provided $C^0$-bounds are known. Subsequently, Guan and Wang ([GW03b]) proved local versions of these estimates which only depend on a lower bound for solutions on a ball. Their estimates have the added advantage of being scale-invariant, which is crucial in our analysis. For this reason, in Section 2 of the present paper we state the main estimate of Guan-Wang and prove some straightforward but very useful corollaries.

Given $(M^n, g)$ with $g \in \Gamma_k^+(M^n)$, finding a solution of (1.5) with $f(x) = \text{constant}$ is known as the $\sigma_k$-Yamabe problem. In [GV04] we described the connection between solving the $\sigma_k$-Yamabe problem when $k > n/2$ and a new conformal invariant called the maximal volume (see the introduction of [GV04]). On the basis of some delicate global volume comparison arguments, we were able to give sharp estimates for this invariant in dimensions three and four. Then, using the local estimates of Guan-Wang and the Liouville-type theorems of Li-Li [LL03], we proved the existence and compactness of solutions of the $\sigma_k$-Yamabe problem for any $k$-admissible four-manifold $(M^4, g)$ ($k \geq 2$), and any simply connected $k$-admissible three-manifold $(M^3, g)$ ($k \geq 2$). More generally, we proved the existence of a number $C(k, n) \geq 1$, such that if the fundamental group of $M^n$ satisfies $||\pi_1(M^n)|| > C(k, n)$ then the conformal class of any $k$-admissible metric with $k > n/2$ admits a solution of the $\sigma_k$-Yamabe problem. Moreover, the set of all such solutions is compact.
We note that the proof of Theorem 1.1 does not rely on the Liouville theorem of Li-Li. Indeed, other than the local estimates of Guan-Wang, the present paper is fairly self-contained.

There are several existence results for (1.5) when \((M^n, g)\) is assumed to be locally conformally flat and \(k\)-admissible. In [LL03], Li and Li solved the \(\sigma_k\)-Yamabe problem for any \(k \geq 1\), and established compactness of the solution space assuming the manifold is not conformally equivalent to the sphere. Guan and Wang ([GW03a]) used a parabolic version of (1.5) to prove global existence (in time) of solutions and convergence to a solution of the \(\sigma_k\)-Yamabe problem. However, as we observed above, if \((M^n, g)\) is \(k\)-admissible with \(k > n/2\) then \(g\) has positive Ricci curvature; by Myers' theorem the universal cover \(X^n\) of \(M^n\) must be compact, and Kuiper's theorem implies \(X^n\) is conformally equivalent to the round sphere. We conclude the manifold \((M^n, g)\) must be conformal to a spherical space form. Consequently, there is no significant overlap between our existence result and those of Li-Li or Guan-Wang.

For global estimates the aforementioned result of Viaclovsky ([Via02]) is optimal: since (1.3) is invariant under the action of the conformal group, \(a \text{ priori} \ C^0\)-bounds may fail for the usual reason (i.e., the conformal group of the round sphere). Some results have managed to distinguish the case of the sphere, thereby giving bounds when the manifold is not conformally equivalent to \(S^n\). For example, [CGY02a] proved the existence of solutions to (1.5) when \(k = 2\) and \(g\) is 2-admissible, for any function \(f(x)\), provided \((M^4, g)\) is not conformally equivalent to the sphere. In [Via02] the second author studied the case \(k = n\), and defined another conformal invariant associated to admissible metrics. When this invariant is below a certain value, one can establish \(C^0\)-estimates, giving existence and compactness for the determinant case on a large class of conformal manifolds.

1.2. Outline of proof. In this paper our strategy is quite different from the results just described. We begin by defining a 1-parameter family of equations that amounts to a deformation of (1.5). When the parameter \(t = 1\), the resulting equation is exactly (1.5), while for \(t = 0\) the ‘initial’ equation is much easier to analyze. This artifice appears in our previous paper [GV04], except that here we are attempting to solve (1.5) for general \(f\) and not just \(f(x) = \text{constant}\). In both instances the key observation is that the Leray-Schauder degree, as defined in the paper of Li [Li89], is non-zero. By homotopy-invariance of the degree the question of existence reduces to establishing \(a \text{ priori}\) bounds for solutions for \(t \in [0, 1]\).

To prove such bounds we argue by contradiction. That is, we assume the existence of a sequence of solutions \(\{u_i\}\) for which a \(C^0\)-bound fails, and undertake a careful study of the blow-up. On this level our analysis parallels
the blow-up theory for solutions of the Yamabe problem as described, for
eexample, in [Sch89].

The first step is to prove a kind of weak compactness result for a se-
sequence of solutions \(\{u_i\}\), which says that there is a finite set of points \(\Sigma = \{x_1, \ldots, x_\ell\} \subset M^n\) with the property that the \(u_i\)'s are bounded from below
and the derivatives up to order two are uniformly bounded on compact sub-
sets of \(M^n \setminus \Sigma\) (see Proposition 4.4). This leads to two possibilities: either a
subsequence of \(\{u_i\}\) converges to a limiting solution on \(M^n \setminus \Sigma\), or \(u_i \to +\infty\)
on \(M^n \setminus \Sigma\). Using our integral gradient estimate, we are able to rule out the
former possibility.

The next step is to normalize the sequence \(\{u_i\}\) by choosing a “regular”
point \(x_0 \notin \Sigma\) and defining \(w_i(x) = u_i(x) - u_i(x_0)\). By our preceding observa-
tions, a subsequence of \(\{w_i\}\) converges on compact subsets of \(M^n \setminus \Sigma\) in \(C^{1,\alpha}\)
to a limit \(w \in C^{1,1}_{\text{loc}}(M^n \setminus \Sigma)\). At this point, the analysis becomes technically
quite different from that of the Yamabe problem, where a divergent sequence
(after normalizing in a similar way) is known to converge off the singular set to
a solution of \(L \Gamma = 0\), where \(\Gamma\) is a linear combination of fundamental solutions
of the conformal laplacian \(L = \Delta - \frac{(n-2)}{4(n-1)} R\). By contrast, in our case the limit
is only a viscosity solution of

\[
\sigma^{1/k}_k (A + \nabla^2 w + dw \otimes dw - \frac{1}{2} |\nabla w|^2 g) \geq 0.
\]

In addition, we have no a priori knowledge of the behavior of singular solutions
of (1.6). For example, it is unclear what is meant by a fundamental solution
in this context.

Keeping in mind the goal, if not the means of [Sch89], we remind the reader
that Schoen applied the Pohozaev identity to the singular limit \(\Gamma\) to show
that the constant term in the asymptotic expansion of the Green’s function
has a sign, thus reducing the problem to the resolution of the Positive Mass
Theorem. In other words, analysis of the sequence is reduced to analysis of
the asymptotically flat metric \(\Gamma_{(n-2)}^4 g\). For example, if \((M^n, g)\) is the round
sphere then the singular metric defined by the Green’s function \(\Gamma_p\) with pole
at \(p\) is flat; in fact, \((M^n \setminus \{p\}, \Gamma_p^{4/(n-2)} g)\) is isometric to \((\mathbb{R}^n, g_{\text{Euc}})\).

Our approach is to also study the manifold \((M^n \setminus \Sigma, e^{-2w} g)\) defined by the
singular limit. However, the metric \(g_w = e^{-2w} g\) is only \(C^{1,1}\), and owing to our
lack of knowledge about the behavior of \(w\) near the singular set \(\Sigma\), initially we
do not know if \(g_w\) is complete. Therefore in Section 6 we analyze the behavior
of \(w\), once again relying on the integral gradient estimate and a kind of weak
maximum principle for singular solutions of (1.6). Eventually we are able to
show that near any point \(x_k \in \Sigma\),

\[
2 \log d_g(x, x_k) - C \leq w(x) \leq 2 \log d_g(x, x_k) + C
\]
for some constant $C$, where $d_g$ is the distance function with respect to $g$. If $\Gamma$ denotes the Green’s function for $L$ with singularity at $x_k$, then (1.7) is equivalent to

$$e^{-1}\Gamma(x)^{4/(n-2)} \leq e^{-2w(x)} \leq e\Gamma(x)^{4/(n-2)}$$

for some constant $c > 1$. Thus, the asymptotic behavior of the metric $g_w$ at infinity is the same— at least to first order—as the behavior of $\Gamma^{4/(n-2)}$. Consequently, $g_w$ is complete (see Proposition 7.4).

The estimate (1.7) can be slightly refined; if $\Psi(x) = w(x) - 2\log d_g(x, x_k)$ then (1.7) says $\Psi(x) = O(1)$ near $x_k$. In fact, we can show that

$$\int_{U_k} |\nabla\Psi|^2_{g_w} \, dvol_{g_w} < \infty$$

for some neighborhood $U_k$ of $x_k$ (see Theorem 7.16). Using this bound we proceed to analyze the manifold $(M^n, g_w)$ near infinity. First, we observe that since $g_w$ is the limit of smooth metrics with positive Ricci curvature, by Bishop’s theorem the volume growth of large balls is sub-Euclidean:

$$\text{Vol}_{g_w}(B(p_0, r)) \leq \frac{\omega_n}{r^n},$$

where $p_0 \in M \setminus \Sigma$ is a basepoint. Moreover, the ratio in (1.9) is non-increasing as a function of $r$. Also, using (1.8) and a tangent cone analysis, we find that

$$\lim_{r \to \infty} \frac{\text{Vol}_{g_w}(B(p_0, r))}{r^n} = \omega_n.$$ 

Therefore, equality holds in (1.9), which by Bishop’s theorem implies that $g_w$ is isometric to the Euclidean metric. We emphasize that since the limiting metric $g_w$ is only $C^{1,1}$, we cannot directly apply the standard version of Bishop’s theorem; this problem makes our arguments technically more difficult. However, once equality holds in (1.9), it follows that $w$ is regular, $e^{-2w} = \Gamma^{4/(n-2)}$, and $(M^n, g)$ is conformal to the round sphere.

Because much of the technical work of this paper is reduced to understanding singular solutions which arise as limits of sequences, we are optimistic that our techniques can be used to study more general singular solutions of (1.5), as in the recent work of María del Mar González [dMG04], [dMG05]. Also, the importance of the integral estimate, Theorem 3.5, indicates that it should be of independent interest in the study of other conformally invariant, fully nonlinear equations.

1.3. Other symmetric functions. Our method of analyzing the blow-up for sequences of solutions to (1.5) can be applied to more general examples of symmetric functions, provided the Ricci curvature is strictly positive and the appropriate local estimates are satisfied. To make this precise, let

$$F : \Gamma \subset \mathbb{R}^n \to \mathbb{R}$$

with $F \in C^\infty(\Gamma) \cap C^0(\overline{\Gamma})$, where $\Gamma \subset \mathbb{R}^n$ is an open, symmetric, convex cone.
We impose the following conditions on the operator $F$:

(i) $F$ is symmetric, concave, and homogenous of degree one.

(ii) $F > 0$ in $\Gamma$, and $F = 0$ on $\partial \Gamma$.

(iii) $F$ is elliptic: $F_{\lambda_i}(\lambda) > 0$ for each $1 \leq i \leq n$, $\lambda \in \Gamma$.

(iv) $\Gamma \supset \Gamma^+_n$, and there exists a constant $\delta > 0$ such that any $\lambda = (\lambda_1, \ldots, \lambda_n) \in \Gamma$ satisfies

\begin{equation}
\lambda_i > \frac{(1 - 2\delta)}{(n - 2)}(\lambda_1 + \cdots + \lambda_n) \quad \forall \ 1 \leq i \leq n.
\end{equation}

To explain the significance of (1.11), suppose the eigenvalues of the Schouten tensor $A_g$ are in $\Gamma$ at each point of $M^n$. Then $(M^n, g)$ has positive Ricci curvature: in fact,

\begin{equation}
\text{Ric}_g - 2\delta \sigma_1(A_g) g \geq 0.
\end{equation}

For $F$ satisfying (i)–(iv), consider the equation

\begin{equation}
F(A_u) = f(x)e^{-2u},
\end{equation}

where we assume $A_u \in \Gamma$ (i.e., $u$ is $\Gamma$-admissible). Some examples of interest are

**Example 1.** $F(A_u) = \sigma^{1/k}_{\Lambda}(A_u)$ with $\Gamma = \Gamma^+_k$, $k > n/2$. Thus, (1.5) is an example of (1.13).

**Example 2.** Let $1 \leq l < k$ and $k > n/2$, and consider

\begin{equation}
F(A_u) = \left(\frac{\sigma_k(A_u)}{\sigma_l(A_u)}\right)^{\frac{1}{k-l}}.
\end{equation}

In this case we also take $\Gamma = \Gamma^+_k$.

**Example 3.** For $\tau \leq 1$ let

\begin{equation}
A^\tau = \frac{1}{(n - 2)} \left(\text{Ric} - \frac{\tau}{2(n - 1)} Rg\right)
\end{equation}

and consider the equation

\begin{equation}
F(A_u) = \sigma^{1/k}_{\Lambda}(A^\tau_u) = f(x)e^{-2u}.
\end{equation}

By (1.4), this is equivalent to the fully nonlinear equation

\begin{equation}
\sigma^{1/k}_{\Lambda}\left(A^\tau + \nabla^2 u + \frac{1 - \tau}{n - 2}(\Delta u)g + du \otimes du - \frac{2 - \tau}{2} |\nabla u|^2 g\right) = f(x)e^{-2u}.
\end{equation}

In the appendix we show that the results of [GVW03] imply the existence of $\tau_0 = \tau_0(n, k) > 0$ and $\delta_0 = \delta(k, n) > 0$ so that if $1 \geq \tau > \tau_0(n, k)$ and $A^\tau_g \in \Gamma_k$ with $k > n/2$, then $g$ satisfies (1.11) with $\delta = \delta_0$. 
For the existence part of our proof we use a degree-theory argument which requires us to introduce a 1-parameter family of auxiliary equations. For this reason, we need to consider the following slightly more general equation:

\[(1.18) \quad F(Au + G(x)) = f(x)e^{-2u} + c,\]

where \(G(x)\) is a symmetric \((0,2)\)-tensor with eigenvalues in \(\Gamma\), and \(c \geq 0\) is a constant. To extend our compactness theory to equations like \((1.18)\), we need to verify that solutions satisfy local estimates like those proved by Guan-Wang. Such estimates were recently proved by S. Chen [Che05]:

**Theorem 1.2** (See [Che05, Cor. 1]). Let \(F\) satisfy the properties (i)--(iv) above. If \(u \in C^4(B(x_0, \rho))\) is a solution of \((1.18)\), then there is a constant

\[C_0 = C_0(n, \rho, \|g\|_{C^1(B(x_0, \rho))}, \|f\|_{C^2(B(x_0, \rho))}, \|G\|_{C^2(B(x_0, \rho))}, c),\]

such that

\[(1.19) \quad |\nabla^2 u(x)| + |\nabla u|^2(x) \leq C_0(1 + e^{-2\inf_{B(x_0, \rho)} u})\]

for all \(x \in B(x_0, \rho/2)\).

An important feature of \((1.19)\) is that both sides of the inequality have the same homogeneity under the natural dilation structure of equation \((1.18)\); see the proof of Lemma 3.1 and the remark following Proposition 3.2.

We note that higher order regularity for solutions of \((1.18)\) will follow from pointwise bounds on the solution and its derivatives up to order two, by the aforementioned results of Evans [Eva82] and Krylov [Kry93]. The point here is that \(C^2\)-bounds, along with the properties (i)--(iv), imply that equation \((1.18)\) is *uniformly* elliptic. Since this is not completely obvious we provide a proof in the Appendix.

For the examples enumerated above, local estimates have already appeared in the literature. As noted, Guan and Wang established local estimates for solutions of \((1.5)\) in [GW03b]. In subsequent papers ([GW04a], [GW04b]) they proved a similar estimate for solutions of \((1.14)\). In [LL03], Li and Li proved local estimates for solutions of \((1.17)\) (see also [GV03]). In both cases, the estimates can be adapted to the modified equation \((1.18)\) with very little difficulty. The work of S. Chen, in addition to giving a unified proof of these results, also applies to other fully nonlinear equations in geometry. Applying her result, our method gives
Theorem 1.3. Suppose $F : \Gamma \to \mathbb{R}$ satisfies (i)–(iv). Let $(M^n, g)$ be closed $n$-dimensional Riemannian manifold, and assume

(i) $g$ is $\Gamma$-admissible, and

(ii) $(M^n, g)$ is not conformally equivalent to the round $n$-dimensional sphere.

Then given any smooth positive function $f \in C^\infty(M^n)$ there exists a solution $u \in C^\infty(M^n)$ of

$$F(A_u) = f(x)e^{-2u},$$

and the set of all such solutions is compact in the $C^m$-topology for any $m \geq 0$.

Note that, in particular, the symmetric functions arising in Examples 2 and 3 above fall under the umbrella of Theorem 1.3. To simplify the exposition in the paper we give the proof of Theorem 1.1, while providing some remarks along the way to point out where modifications are needed for proving Theorem 1.3 (in fact, there are very few).

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2. The deformation

Let $f \in C^\infty(M^n)$ be a positive function, and for $0 \leq t \leq 1$ consider the family of equations

$$\sigma_k^{1/k}(\lambda_k(1 - \psi(t))g + \psi(t)A + \nabla^2 u + du \otimes du - \frac{1}{2}|\nabla u|^2 g) = (1 - t)\left(\int e^{-(n+1)u}d\text{vol}_g\right)^{\frac{n}{n+1}} + \psi(t)f(x)e^{-2u},$$

(2.1)

where $\psi \in C^1[0,1]$ satisfies $0 \leq \psi(t) \leq 1, \psi(0) = 0$, and $\psi(t) \equiv 1$ for $t \leq \frac{1}{2}$; now, $\lambda_k$ is given by

$$\lambda_k = \left(\frac{n}{k}\right)^{-1/k}.$$  

Note that when $t = 1$, equation (2.1) is just equation (1.5). Thus, we have constructed a deformation of (1.5) by connecting it to a “less nonlinear” equation at $t = 0$:

$$\sigma_k^{1/k}(\lambda_k g + \nabla^2 u + du \otimes du - \frac{1}{2}|\nabla u|^2 g) = \left(\int e^{-(n+1)u}d\text{vol}_g\right)^{\frac{n}{n+1}}.$$

(2.2)

This ‘initial’ equation turns out to be much easier to analyze. Indeed, if we assume that $g$ has been normalized to have unit volume, then $u_0 \equiv 0$ is the
unique solution of (2.2). Since the initial equation admits a solution, one might hope to use topological methods to establish the existence of a solution to (2.1) when \( t = 1 \).

In a previous paper ([GV04]) we studied (2.1) with \( f(x) = \text{constant} > 0 \). Note that when \( t = 0 \), equation (2.1) is identical to the initial equation in [GV04]; for this reason we will only provide an outline of the degree theory argument, and refer the reader to Section 4 of [GV04] for many of the details.

To begin, define the operator

\[
\Psi_t[u] = \sigma_k^{1/k} \left( \lambda_k (1 - \psi(t))g + \psi(t)A + \nabla^2 u + du \otimes du - \frac{1}{2} |\nabla u|^2 g \right) - (1 - t) \left( \int e^{-(n+1)u} d\text{vol}_g \right)^{\frac{2}{n+1}} - \psi(t)f(x)e^{-2u}.
\]

As we observed above, when \( t = 0 \)

\[
\Psi_0[u_0] = 0.
\]

In fact, \( u_0 \) is the unique solution, and the linearization of \( \Psi_0 \) at \( u_0 \) is invertible. It follows that the Leray-Schauder degree \( \text{deg}(\Psi_0, \mathcal{O}_0, 0) \) defined by Li [Li89] is non-zero, where \( \mathcal{O}_0 \subseteq C^{4,\alpha} \) is a neighborhood of the zero solution. Of course, we would like to use the homotopy-invariance of the degree to conclude that \( \text{deg}(\Psi_t, \mathcal{O}, 0) \) is non-zero for some open set \( \mathcal{O} \subseteq C^{4,\alpha} \); to do so we need to establish \textit{a priori} bounds for solutions of (2.1) which are independent of \( t \) (in order to define \( \mathcal{O} \)). Using the \( \varepsilon \)-regularity result of Guan-Wang [GW03b], one can easily obtain bounds when \( t < 1 \):

**Theorem 2.1 ([GV04, Th. 2.1]).** For any fixed \( 0 < \delta < 1 \), there is a constant \( C = C(\delta, g) \) such that any solution of (2.1) with \( t \in [0, 1 - \delta] \) satisfies

\[
\|u\|_{C^{4,\alpha}} \leq C.
\]

The question that remains—and that we ultimately address in this article for \( k > n/2 \)—is the behavior of a sequence of solutions \( \{u_t\} \) as \( t \to 1 \). We will prove

**Theorem 2.2.** Let \((M^n, g)\) be a closed, compact Riemannian manifold that is not conformally equivalent to the round \( n \)-dimensional sphere. Then there is a constant \( C = C(g) \) such that any solution \( u \) of (2.1) satisfies

\[
\|u\|_{C^{4,\alpha}} \leq C.
\]

Theorem 2.2 allows us to define properly the degree of the map \( \Psi_t[\cdot] \), and by homotopy invariance we conclude the existence of a solution of (2.1) for \( t = 1 \).

To prove Theorem 2.2 we argue by contradiction. Thus, we assume \((M^n, g)\) is not conformally equivalent to the round sphere, and let \( u_i = u_{t_i} \).
be a sequence of solutions to (2.1) with $t_i \to 1$ and such that $\|u_i\|_{L^\infty} \to \infty$. In the next section we derive various estimates used to analyze the behavior of this sequence.

2.1. Degree theory for other symmetric functions. As in the above case, we define

$$\tilde{\Psi}_t[u] = F\left(\lambda_k'(1 - \psi(t))g + \psi(t)A + \nabla^2 u + du \otimes du - \frac{1}{2}|\nabla u|^2 g\right)$$

$$- (1-t)\left(\int e^{-(n+1)u} \, d\text{vol}_g\right)^{\frac{n}{n+1}} - \psi(t)f(x)e^{-2u},$$

where $\lambda_k'$ is chosen so that $F(\lambda_k' \cdot g) = 1$.

It is straightforward to adapt the construction above in order to define the Leray-Schauder degree of solutions to (2.7). The analog of Theorem 2.1 is proved in a similar fashion using the local estimates of S. Chen (Theorem 1.2). In the course of proving Theorem 2.2, in this paper we will also prove

**Theorem 2.3.** Let $(M^n, g)$ be a closed, compact Riemannian manifold that is not conformally equivalent to the round $n$-dimensional sphere. Then there is a constant $C = C(g)$ such that any solution $u$ of $\tilde{\Psi}_t[u] = 0$ satisfies $\|u\|_{C^{1,\alpha}} \leq C$.

3. Local estimates

In this section we state some local results for solutions of

$$\sigma_k^{1/k}((1-s)g + sA + \nabla^2 u + du \otimes du - \frac{1}{2}|\nabla u|^2 g) = \mu + f(x)e^{-2u},$$

where $u$ is assumed to be $k$-admissible, and $s \in [0, 1], \mu \geq 0$ are constants. Of course, equation (2.1) is of this form; in particular each function $\{u_i\}$ in the sequence defined above satisfies an equation like (3.1).

The results of this section are of two types: the pointwise $C^{1}$- and $C^{2}$-estimates of Guan-Wang ([GW03b]), and various integral estimates. The first integral estimate (Proposition 3.3) already appeared—albeit in a slightly different form—in [CGY02b] and [Gur93].

The main integral result is Theorem 3.5. It is a kind of weighted $L^p$-gradient estimate that holds for $k$-admissible metrics when $k > n/2$, and has the advantage of assuming only minimal regularity for the metric. This flexibility can be important when studying limits of sequences of solutions to (3.1), which may only be in $C^{1,1}$.

3.1. Pointwise estimates. Before recalling the results of Guan and Wang we should point out that they studied equation (1.3) for $s = 1$ and $\mu = 0$. However, as explained in Section 2 of [GV04], there is only one line in Guan
and Wang’s argument that needs to be modified, and then only slightly (see the paragraph following Lemma 2.4 in [GV04] for details).

**Lemma 3.1** (Theorem 1.1 of [GW03b]). Let $u \in C^4(M^n)$ be a $k$-admissible solution of (3.1) in $B(x_0, \rho)$, where $x_0 \in M^n$ and $\rho > 0$. Then there is a constant
\[
C_1 = C_1(k, n, \mu, \|g\|_{C^3(B(x_0, \rho))}, \|f\|_{C^2(B(x_0, \rho))}),
\]
such that
\[
|\nabla^2 u|(x) + |\nabla u|^2(x) \leq C_1(\rho^{-2} + e^{-2\inf_{B(x_0, \rho)} u})
\]
for all $x \in B(x_0, \rho/2)$.

**Remark.** Guan-Wang did not include the explicit dependence of their estimates on the radius of the ball. Since it will be important in certain applications, we have done so here. The dependence is easy to establish using a typical dilation argument.

An immediate corollary of this estimate is an $\epsilon$-regularity result:

**Proposition 3.2** (Proposition 3.6 of [GW03b]). There exist constants $\epsilon_0 > 0$ and $C = C(g, \epsilon_0)$ such that any solution $u \in C^2(B(x_0, \rho))$ of (3.1) with
\[
\int_{B(x_0, \rho)} e^{-nu} \, d\text{vol}_g \leq \epsilon_0,
\]
satisfies
\[
\inf_{B(x_0, \rho/2)} u \geq -C + \log \rho.
\]
Consequently, there is a constant
\[
C_2 = C_2(k, n, \mu, \epsilon_0, \|g\|_{C^3(B(x_0, \rho))}),
\]
such that
\[
|\nabla^2 u|(x) + |\nabla u|^2(x) \leq C_2\rho^{-2}
\]
for all $x \in B(x_0, \rho/4)$.

**Remark.** The same argument used in the proofs of Lemma 3.1 and Proposition 3.2 can be used to show that any $\Gamma$-admissible solution of (1.13) will satisfy the inequalities (3.2), (3.4), and (3.5). Note that the homogeneity assumption on $F$ is crucial in this respect.

### 3.2. Integral estimates.
We now turn to integral estimates. The first result shows that any local $L^p$-bound on $e^u$ immediately gives a global sup-bound.
Proposition 3.3. Let \( u \in C^2(M^n) \) and assume \( g_u = e^{-2u}g \) has non-negative scalar curvature. Suppose there is a ball \( B = B(x, \rho) \subset M^n \) and constants \( \alpha_0 > 0 \) and \( B_0 > 0 \) with
\[
\int_{B(x, \rho)} e^{\alpha_0 u} \; d\text{vol}_g \leq B_0. \tag{3.6}
\]
Then there is a constant
\[
C = C(g, \text{vol}(B(x, \rho)), \alpha_0, B_0),
\]
such that
\[
\max_{M^n} u \leq C. \tag{3.7}
\]

Proof. If \( R_u \) denotes the scalar curvature of \( g_u \), then (1.4) implies
\[
\frac{1}{2(n-1)} R_u e^{-2u} = \frac{1}{2(n-1)} R + \Delta u - \frac{(n-2)}{2} |\nabla u|^2.
\]
Therefore, if \( R_u \geq 0 \) we conclude
\[
-\Delta u + \frac{(n-2)}{2} |\nabla u|^2 + \frac{1}{2(n-1)} R \geq 0; \tag{3.8}
\]
hence
\[
-\Delta u + \frac{(n-2)}{2} |\nabla u|^2 \geq -C. \tag{3.9}
\]
In what follows, it will simplify our calculations if we let \( v = e^{-\frac{(n-2)}{2} u} \). In terms of \( v \), the bound (3.6) becomes
\[
\int_{B(x, \rho)} v^{p_0} \; d\text{vol}_g \leq B_0 \tag{3.10}
\]
where \( p_0 = \frac{(n-2)}{2} \alpha_0 \). Also, inequality (3.8) becomes
\[
\Delta v - \frac{(n-2)}{4(n-1)} Rv \leq 0, \tag{3.11}
\]
and (3.9) becomes
\[
\Delta v \leq Cv. \tag{3.12}
\]
It follows that any global \( L^p \)-bound of the form (3.10) implies a lower bound on \( v \) (and therefore an upper bound on \( u \)). That is, if \( p > 0 \), then
\[
\int_{M^n} v^{-p} \; d\text{vol}_g \leq C_0 \Rightarrow \inf_{M^n} v \geq C(C_0) > 0. \tag{3.13}
\]
There are various ways to see this; for example, by using the Green’s representation. It therefore remains to prove that one can pass from the local \( L^p \)-bound of (3.10) to a global one:
Lemma 3.4. For $p \in (0, p_0)$ sufficiently small, there is a constant

$$C = C(g, \text{vol}(B(x, \rho)), p, B_0),$$

such that

$$\int_{M^n} v^{-2p}d\text{vol}_g \leq C.$$  

(3.14)

Proof. This is Lemma 4.3 of [CGY02b] (see also Lemma 4.1 of [Gur93]).

This completes the proof of Proposition 3.3.

Remark. If $u \in C^2$ is a $\Gamma$-admissible solution of (1.13), then by definition the scalar curvature of $g_u = e^{-2u}g$ is positive. Therefore, Proposition 3.3 is applicable.

The next result is an integral gradient estimate for admissible metrics. Before we give the precise statement, a brief remark is needed about the regularity assumptions of the result and their relationship to curvature.

If $u \in C^{1,1}$, then Rademacher’s Theorem says that the Hessian of $u$ is defined almost everywhere, and therefore by (1.4) the Schouten tensor $A_u$ of $g_u$ is defined almost everywhere. In particular, the notion of $k$-admissibility (respectively, $\Gamma$-admissibility) can still be defined: it requires that the eigenvalues of $A_u$ are in $\Gamma_k^+(\mathbb{R}^n)$ (resp., $\Gamma$) at almost every $x \in M^n$. Likewise, the condition of non-negative Ricci curvature (a.e.) is well defined.

Theorem 3.5. Let $u \in C^{1,1}_{\text{loc}}(A(\frac{1}{2}r_1, 2r_2))$, where $x_0 \in M^n$ and $A(\frac{1}{2}r_1, 2r_2)$ denotes the annulus $A(\frac{1}{2}r_1, 2r_2) \equiv B(x_0, 2r_2) \setminus B(x_0, \frac{1}{2}r_1)$, with $0 < r_1 < r_2$. Assume $g_u = e^{-2u}g$ satisfies

$$\text{Ric}(g_u) - 2\delta\sigma_1(A_u)g \geq 0$$

almost everywhere in $A(\frac{1}{2}r_1, 2r_2)$ for some $0 \leq \delta < \frac{1}{2}$. Define

$$\alpha_\delta = \frac{(n-2)}{(1-2\delta)} \delta \geq 0.$$  

(3.16)

Then given any $\alpha > \alpha_\delta$, there are constants $p \geq n$ and $C = C((\alpha - \alpha_\delta)^{-1}, n) > 0$ such that

$$\int_{A(r_1, r_2)} |\nabla u|^p e^{\alpha u}d\text{vol}_g \leq C \left( \int_{A(\frac{1}{2}r_1, 2r_2)} |\text{Ric}_g|^{p/2}e^{\alpha u}d\text{vol}_g ight. $$

$$+ r_1^{-p} \int_{A(\frac{1}{2}r_1, r_1)} e^{\alpha u}d\text{vol}_g + r_2^{-p} \int_{A(2r_2, r_2)} e^{\alpha u}d\text{vol}_g \bigg).$$  

(3.17)

In fact, we can take

$$p = n + 2\alpha_\delta \geq n.$$  

(3.18)
Now suppose \( g_u = e^{-2u} g \) is \( k \)-admissible, with \( k > n/2 \). By a result of Guan-Viaclovsky-Wang ([GVW03, Th. 1]), inequality (3.15) holds for any \( \delta \) satisfying \( \delta \leq \frac{(2k-n)(n-1)}{2n(k-1)} \). Therefore,

**Corollary 3.6.** Let \( u \in C^{1,1}_{\text{loc}}(A(\frac{1}{2}r_1,2r_2)) \), where \( x_0 \in M^n \) and \( A(\frac{1}{2}r_1,2r_2) \) denotes the annulus \( A(\frac{1}{2}r_1,2r_2) = B(x_0,2r_2) \setminus B(x_0,\frac{1}{2}r_1) \), with \( 0 < r_1 < r_2 \). Assume \( g_u = e^{-2u} g \) is \( k \)-admissible with \( k > n/2 \). Suppose \( \delta \geq 0 \) satisfies

\[
0 \leq \delta \leq \frac{1}{2} \left( \frac{2k-n}{n-1} \right),
\]

and define

\[
\alpha_{\delta} = \frac{(n-2)}{(1-2\delta)} \delta.
\]

Then given any \( \alpha > \alpha_{\delta} \), there are constants \( p > n \) and \( C = C((\alpha - \alpha_{\delta})^{-1}, n) > 0 \) such that

\[
(3.19) \quad \int_{A(r_1,r_2)} |\nabla u|^p e^{\alpha u} \, d\text{vol}_g \leq C \left( \int_{A(\frac{1}{2}r_1,2r_2)} |\text{Ric}_g|^p/2 e^{\alpha u} \, d\text{vol}_g \right) + \int_{A(\frac{1}{2}r_1,r_1)} e^{\alpha u} \, d\text{vol}_g + \int_{A(r_2,2r_2)} e^{\alpha u} \, d\text{vol}_g.
\]

We now give the proof of Theorem 3.5.

**Proof.** Let

\[
S = S_g = \text{Ric}_g - 2\delta \sigma_1(A_g) g.
\]

By the curvature transformation formula (1.4), for any conformal metric \( g_u = e^{-2u} g \) the relationship between \( S_u = S_{g_u} \) and \( S_g \) is given by

\[
(3.21) \quad S_u = (n-2)\nabla^2 u + (1-2\delta)\Delta u g + (n-2)du \otimes du - (n-2)(1-\delta)|\nabla u|^2 g + S_g.
\]

Now assume \( g_u \) is a metric for which \( S_u \geq 0 \) a.e. in \( A = A(\frac{1}{2}r_1,2r_2) \). From (3.21), it follows that

\[
(3.22) \quad 0 \leq \frac{1}{(n-2)} S_u(\nabla u, \nabla u) = \nabla^2 u(\nabla u, \nabla u) + \frac{(1-2\delta)}{(n-2)} \Delta u |\nabla u|^2 + \delta |\nabla u|^4 + \frac{1}{(n-2)} S_g(\nabla u, \nabla u)
\]

a.e. in \( A \). Using this identity we have
Lemma 3.7. For any $\alpha \in \mathbb{R}, \delta \geq 0$, $u$ satisfies

$$\nabla_i(|\nabla u|^{p-2}e^{\alpha u}\nabla_i u) \geq (\alpha - \alpha_\delta)|\nabla u|^{p}e^{\alpha u} - \frac{1}{(1-2\delta)}|S_g||\nabla u|^{p-2}e^{\alpha u}$$

almost everywhere in $A$, where $\alpha_\delta$ and $p$ are defined as in (3.16) and (3.18), respectively.

Proof. Since $u \in C^{1,1}_{loc}$ and $p > 2$, the vector field

$$X = |\nabla u|^{p-2}e^{\alpha u}\nabla u$$

is locally Lipschitz. Therefore, its divergence is defined at any point where the Hessian of $u$ is defined—in particular, almost everywhere in $A$. Moreover, at any point where (3.22) is valid we have

$$\nabla_i(|\nabla u|^{p-2}e^{\alpha u}\nabla_i u) = \nabla_i(|\nabla u|^{p-2})e^{\alpha u}\nabla_i u + |\nabla u|^{p-2}\nabla_i(e^{\alpha u})\nabla_i u + |\nabla u|^{p-2}e^{\alpha u}\Delta u$$

$$= (p-2)|\nabla u|^{p-4}e^{\alpha u}\nabla^2 u(\nabla u, \nabla u) + |\nabla u|^{p-2}e^{\alpha u}\Delta u + \alpha|\nabla u|^{p}e^{\alpha u}. $$

Since $p > 2$ we can substitute inequality (3.22) into (3.25) to get

$$\nabla_i(|\nabla u|^{p-2}e^{\alpha u}\nabla_i u) \geq [1 - (p-2)\frac{1-2\delta}{n-2}]|\nabla u|^{p-2}e^{\alpha u}\Delta u$$

$$+ [\alpha - \delta(p-2)]|\nabla u|^{p}e^{\alpha u} - \frac{(p-2)}{(n-2)}|S_g||\nabla u|^{p-2}e^{\alpha u}. $$

Then (3.23) follows from (3.26) by taking

$$p = \frac{n - 4\delta}{1-2\delta} = n + 2\alpha_\delta. $$

Let $\eta$ be a cut-off function satisfying

$$\eta(x) = \begin{cases} 
0 & x \in B(x_0, \frac{3}{4}r_1), \\
1 & x \in A(r_1, r_2), \\
0 & x \in B(x_0, 2r_2) \setminus B(x_0, \frac{3}{2}r_2), 
\end{cases}$$

and

$$|\nabla \eta(x)| \leq \begin{cases} 
Cr_1^{-1} & x \in A(\frac{1}{2}r_1, r_1), \\
Cr_2^{-1} & x \in A(r_2, 2r_2), 
\end{cases}$$

and $|\nabla \eta| = 0$ otherwise. Multiplying both sides of (3.23) by $\eta^p$ and applying the divergence theorem (which is valid since the vector field $X$ in (3.24) is
Lipschitz), we get

\[ (3.27) \quad \int -p \langle \nabla \eta, \nabla u \rangle \eta^{p-1} |\nabla u|^{p-2} e^{\alpha u} d\text{vol}_g \]

\[ \geq (\alpha - \alpha \delta) \int |\nabla u|^p e^{\alpha u} \eta^p d\text{vol}_g - \frac{1}{(1-2\delta)} \int |S_g||\nabla u|^{p-2} e^{\alpha u} \eta^p d\text{vol}_g. \]

Using the obvious bound \(|S_g| \leq C|\text{Ric}_g|\) and rearranging terms in (3.27) gives

\[ (3.28) \quad \int |\nabla u|^p e^{\alpha u} \eta^p d\text{vol}_g \leq C((\alpha - \alpha \delta)^{-1}, \delta, n) \left( \int |\text{Ric}_g||\nabla u|^{p-2} e^{\alpha u} \eta^p d\text{vol}_g \right) + \int |\nabla \eta||\nabla u|^{p-1} e^{\alpha u} \eta^{p-1} d\text{vol}_g. \]

Applying Hölder’s inequality to the two integrals on the RHS we have

\[ \int |\nabla u|^p e^{\alpha u} \eta^p d\text{vol}_g \]

\[ \leq C(\theta, \delta, n) \left( \left( \int |\nabla u|^p e^{\alpha u} \eta^p d\text{vol}_g \right)^{(p-2)/p} \left( \int |\text{Ric}_g|^p/2 e^{\alpha u} \eta^p d\text{vol}_g \right)^{2/p} \right. \]

\[ + \left. \left( \int |\nabla u|^p e^{\alpha u} \eta^p d\text{vol}_g \right)^{(p-1)/p} \left( \int |\nabla \eta|^p e^{\alpha u} d\text{vol}_g \right)^{1/p} \right], \]

which implies

\[ \int |\nabla u|^p e^{\alpha u} \eta^p d\text{vol}_g \leq C \left[ \int |\text{Ric}_g|^p/2 e^{\alpha u} \eta^p d\text{vol}_g \right. \]

\[ + \left. \int |\nabla \eta|^p e^{\alpha u} d\text{vol}_g \right]. \]

Therefore, using the properties of the cut-off function \(\eta\) we conclude

\[ \int_{A(r_1, r_2)} |\nabla u|^p e^{\alpha u} d\text{vol}_g \leq \int |\nabla u|^p e^{\alpha u} \eta^p d\text{vol}_g \]

\[ \leq C \left[ \int |\text{Ric}_g|^p/2 e^{\alpha u} \eta^p d\text{vol}_g + \int |\nabla \eta|^p e^{\alpha u} d\text{vol}_g \right] \]

\[ \leq C \int_{A(\frac{1}{2}r_1, 2r_2)} |\text{Ric}_g|^p/2 e^{\alpha u} d\text{vol}_g \]

\[ + Cr_1^{-p} \int_{A(\frac{1}{2}r_1, r_1)} e^{\alpha u} d\text{vol}_g + Cr_2^{-p} \int_{A(r_2, 2r_2)} e^{\alpha u} d\text{vol}_g. \]

This completes the proof of Theorem 3.5. \(\square\)

Theorem 3.5 has a global version:
Corollary 3.8. Let \( u \in C^{1,1}_{\text{loc}}(M^n) \), and assume \( g_u = e^{-2u}g \) is \( k \)-admissible with \( k > n/2 \). Suppose \( \delta \geq 0 \) satisfies
\[
0 \leq \delta \leq \min \left\{ \frac{1}{2}, \frac{(2k - n)(n - 1)}{2n(k - 1)} \right\},
\]
and define
\[
\alpha_\delta = \frac{(n - 2)}{(1 - 2\delta)^\delta}.
\]
Then given any \( \alpha > \alpha_\delta \), there are constants \( p \geq n \) and \( C = C((\alpha - \alpha_\delta)^{-1}, n, g) > 0 \) such that
\[
\int_{M^n} |\nabla u|^p e^{\alpha u} \, d\text{vol}_g \leq C \int_{M^n} e^{\alpha u} \, d\text{vol}_g.
\]

By the Sobolev Imbedding Theorem, Corollary 3.8 implies a pointwise estimate:

Corollary 3.9. Let \( u \in C^{1,1}_{\text{loc}}(M^n) \), and assume \( g_u = e^{-2u}g \) is \( k \)-admissible with \( k > n/2 \). Suppose \( \delta > 0 \) satisfies
\[
0 < \delta \leq \min \left\{ \frac{1}{2}, \frac{(2k - n)(n - 1)}{2n(k - 1)} \right\},
\]
and define
\[
\alpha_\delta = \frac{(n - 2)}{(1 - 2\delta)^\delta}.
\]
Then given any \( \alpha > \alpha_\delta \), there is a constant \( C = C((\alpha - \alpha_\delta)^{-1}, n, g) > 0 \) such that
\[
\| e^{(\alpha/p)u} \|_{C^{\gamma_0}} \leq C \| e^{(\alpha/p)u} \|_{L^p},
\]
where
\[
\gamma_0 = \frac{2\alpha_\delta}{n + 2\alpha_\delta} > 0.
\]

Proof. Inequality (3.29) implies
\[
\| e^{(\alpha/p)u} \|_{W^{1,p}} \leq C \| e^{(\alpha/p)u} \|_{L^p},
\]
where \( W^{1,p} \) denotes the Sobolev space of functions \( \varphi \in L^p \) with \( |\nabla \varphi| \in L^p \).

The Sobolev Imbedding Theorem implies the bound (3.32) for
\[
\gamma_0 = 1 - \frac{n}{p}.
\]
If we take \( p = n + 2\alpha_\delta \) as in (3.18), then (3.33) follows. \( \square \)
3.3. Local estimates for other symmetric functions. As we observed in the remarks following the proofs of Propositions 3.2 and 3.3, any $\Gamma$-admissible solution of (1.13) automatically satisfies the conclusions of Lemma 3.1 and Propositions 3.2 and 3.3. Furthermore, the condition (1.11) implies that any $\Gamma$-admissible solution satisfies inequality (3.15) of Theorem 3.5. Therefore, this result and its corollaries remain valid for $\Gamma$-admissible solutions.

Furthermore, suppose $\{u_i\}$ is a sequence of solutions to $\tilde{\Psi}_t[u_i] = 0$, as described in Section 2.1. Then the conclusion of Proposition 4.1 also holds for this sequence, since the proof just relies on the local estimates of S. Chen.

4. The blow-up

In this section we begin a careful analysis of a sequence $\{u_i\}$ of solutions to (2.1). We may assume that $u_{t_i} = u_i$ with $t_i > 1/2$; this implies $\psi(t_i) = 1$, and so (2.1) becomes

$$
\sigma_k^{1/k} \left( A + \nabla^2 u_i + du_i \otimes du_i - \frac{1}{2} |\nabla u_i|^2 g \right) = (1 - t_i) \left( \int e^{-(n+1)u_i} d\text{vol}_g \right)^{\frac{2}{n+1}} + f(x)e^{-2u_i}.
$$

(4.1)

In particular, the metrics $g_i = e^{-2u_i}g$ are $k$-admissible.

Our first observation is that the sequence $\{u_i\}$ must have $\min u_i \to -\infty$.

**Proposition 4.1.** If there is a lower bound

(4.2) \[ \min u_i \geq -C \]

then there is an upper bound as well; i.e.,

\[ \|u_i\|_{L^\infty} \leq C. \]

Therefore, we must have

(4.3) \[ \min u_i \to -\infty. \]

**Proof.** From [GV04, Lemma 2.5] we know that $\min u_i$ is bounded above. Therefore, assuming (4.2) holds, we have

(4.4) \[ -C \leq \min u_i \leq C. \]

By Lemma 3.1, the lower bound (4.2) implies a gradient bound, which gives a Harnack inequality of the form

(4.5) \[ \max u_i \leq \min u_i + C'. \]

Combining (4.4) and (4.5) we conclude

\[ \max u_i \leq C + C'. \]

Consequently, (4.3) must hold.
The next lemma will be used to show that the sequence \( \{u_i\} \) can only concentrate at finitely many points:

**Lemma 4.2.** The volume and Ricci curvature of the metrics \( \{g_i\} \) satisfy

\[
\text{vol}(g_i) \leq v_0, \tag{4.6}
\]

\[
\text{Ric}_{g_i} \geq c_0 g_i, \tag{4.7}
\]

where \( c_0 > 0 \).

**Proof.** Since each \( g_i \) is \( k \)-admissible with \( k > n/2 \), by Theorem 1 of [GVW03] the Ricci curvature of \( g_i \) satisfies

\[
\text{Ric}_{g_i} \geq \frac{(2k-n)(n-1)}{(k-1)} \left( \frac{n}{k} \right)^{-1/k} \sigma_k^{1/k}(A_{g_i}) g_i. \tag{4.8}
\]

By equation (4.1) this implies

\[
\text{Ric}_{g_i} \geq \frac{(2k-n)(n-1)}{(k-1)} \left( \frac{n}{k} \right)^{-1/k} f(x) g_i \geq c(k,n,\min f) g_i \tag{4.9}
\]

for some \( c_0(k,n,\min f) > 0 \). This proves inequality (4.7). Also, by Bishop’s Theorem ([BC64]) it gives an upper bound on the volume of \( g_i \), proving (4.6).

\( \square \)

**Remark.** It is easy to see that inequalities (4.6) and (4.7) are valid for any sequence \( \{u_i\} \) of \( \Gamma \)-admissible solutions to (1.13). This follows from (1.11), (1.12), and a lower bound for the scalar curvature. More precisely, we claim that

\[
F(\lambda) \leq C_0 \sigma_1(\lambda) \tag{4.10}
\]

for some constant \( C_0 > 0 \) and any \( \lambda \in \Gamma \). To see this, by the homogeneity of \( F \) it suffices to prove that it holds for \( \lambda \in \hat{\Gamma} = \{ \lambda \in \Gamma : |\lambda| = 1 \} \). Now, (1.11) implies that \( \sigma_1(\lambda) > 0 \) for \( \lambda \in \hat{\Gamma} \), because if \( \sigma_1(\lambda) = 0 \) for some \( \lambda \in \hat{\Gamma} \) then by (1.11) we would have \( \hat{\lambda} = 0 \), a contradiction. Therefore, \( \sigma_1(\lambda) \geq c_0 > 0 \) on \( \hat{\Gamma} \), so that \( F(\lambda)/\sigma_1(\lambda) \) is bounded above on \( \hat{\Gamma} \), which proves (4.10). Appealing to (1.12) and (1.13), we see that the Ricci curvature of \( g_i = e^{-2u_i} g \) satisfies

\[
\text{Ric}_{g_i} \geq 2C_0^{-1} \delta f(x) g_i \geq c g_i,
\]

for some \( c > 0 \). Arguing as we did above, we obtain (4.6) and (4.7).

Given \( x \in M^n \), define the **mass** of \( x \) by

\[
m(x) = m(\{u_i\}; x) = \lim_{r \to 0} \limsup_{i \to \infty} \int_{B(x,r)} e^{-nu_i} d\text{vol}_g. \tag{4.11}
\]
This notation is intended to emphasize the dependence of the mass on the sequence \{u_i\}. In particular, if we restrict to a subsequence (as we will soon do), the mass of a given point may decrease.

The \(\varepsilon\)-regularity result of Proposition 3.2 implies that, on a subsequence, only finitely many points may have non-zero mass:

**Proposition 4.3** ([Gur93, §2]). The set \(\Sigma[\{u_i\}] = \{x \in M^n | m(x) \neq 0\}\) is non-empty. In addition, there is a subsequence (still denoted \{u_i\}) such that with respect to this subsequence \(\Sigma\) is non-empty and consists of finitely many points: \(\Sigma = \Sigma[\{u_i\}] = \{x_1, x_2, \ldots, x_\ell\}\).

4.1. Behavior away from the singular set. While the sequence \{u_i\} is concentrating at the points \(\{x_1, x_2, \ldots, x_\ell\}\), away from these points the \(u_i\)'s remain bounded from below, and the derivatives up to order two are uniformly bounded:

**Proposition 4.4.** Given compact \(K \subset M^n \setminus \Sigma\), there is a constant \(C = C(K) > 0\) that is independent of \(i\) such that

\[
\min_K u_i \geq -C(K),
\]

\[
\max_K \left[|\nabla^2 u_i| + |\nabla u_i|^2\right] \leq C(K),
\]

for all \(i \geq J = J(K)\).

**Proof.** Given \(x \in K\), since \(m(x) = 0\) there is radius \(r = r_x\) such that

\[
\int_{B(x,r_x)} e^{-nu_i} d\text{vol} \leq \frac{1}{2} \varepsilon_0
\]

for all \(i \geq J = J_x\). By Proposition 3.2 there is a constant \(C = C(r_x) > 0\) such that

\[
\inf_{B(x,r_x/2)} u_i \geq -C,
\]

\[
\sup_{B(x,r_x/2)} \left[|\nabla^2 u_i| + |\nabla u_i|^2\right] \leq C,
\]

for all \(i \geq J_x\). The balls \(\{B(x,r_x/2)\}_{x \in K}\) define an open cover of \(K\), and since \(K\) is compact we can extract a finite subcover \(K \subset \bigcup_{\nu=1}^N B(x_\nu, r_\nu/2)\). Let \(J = \max_{1 \leq \nu \leq N} J_\nu\); then (4.14) and (4.15) imply that (4.12) and (4.13) hold for all \(i \geq J\).

Now, fix a “regular point” \(x_0 \not\in \Sigma\). There are two possibilities to consider, depending on whether

\[
\limsup_i u_i(x_0) < +\infty
\]
or

\[ \limsup_{i} u_i(x_0) = +\infty \]  

(recall that (4.12) only provides a lower bound for the sequence off the singular set). These possibilities reflect different scenarios for the convergence of (a subsequence of) \( \{u_i\} \) on \( M^n \setminus \Sigma \). If (4.16) holds, it will be possible to extract a subsequence that converges on compact subsets of \( M^n \setminus \Sigma \) to a smooth limit \( u \in C^\infty(M^n \setminus \Sigma) \). But if (4.17) holds, a subsequence diverges to \( +\infty \) uniformly on compact subsets of \( M^n \setminus \Sigma \). As we shall see, the integral gradient estimate (Corollary 3.9) can be used to preclude (4.16).

To this end, assume

\[ \limsup_{i} u_i(x_0) < +\infty. \]  

Then if \( K \subset M^n \setminus \Sigma \) is a compact set containing \( x_0 \), the bounds (4.12), (4.13), and (4.18) imply there is a constant \( C = C(K) > 0 \) such that

\[ \max_K \left[ |\nabla^2 u_i| + |\nabla u_i|^2 + |u_i| \right] \leq C(K) \]  

for all \( i \geq J = J(K) \). This estimate implies that equation (4.1) is uniformly elliptic on \( K \). Since it is concave, by the results of Evans ([Eva82]) and Krylov ([Kry93]) one obtains interior \( C^{2,\gamma} \)-bounds for solutions. The Schauder interior estimates then give estimates on derivatives of all orders: More precisely, given \( K' \subset K \), \( m \geq 1 \), and \( \gamma \in (0,1) \), there is a constant \( C = C(K',m,\gamma) \) such that

\[ \|u_i\|_{C^{m,\gamma}(K')} \leq C. \]  

After applying a standard diagonal argument, we may extract a subsequence \( u_i \rightarrow u \in C^\infty(M^n \setminus \Sigma) \), where the convergence is in \( C^m \) on compact sets away from \( \Sigma \).

As we observed above, when restricting to subsequences it is possible that one reduces the singular set. However, it is always possible to choose a subsequence of \( \{u_i\} \) and a sequence of points \( \{P_i\} \) with

\[ \lim_{i} u_i(P_i) = -\infty, \quad P_i \rightarrow P \in \Sigma, \]  

say \( P = x_1 \). That is, we can always choose a subsequence for which there is at least one singular point. For, if such a choice were impossible, then the original sequence would have a uniform lower bound, and this would violate the conclusions of Proposition 4.1.

Using Proposition 3.3 and Corollary 3.9, we can obtain more precise information on the behavior of the limit \( u \) near the singular point \( x_1 \).

**Proposition 4.5.** Under the assumption (4.18), the function \( u = \lim_{i} u_i \) has the following properties:
There is a constant $C_1 > 0$ such that
\[ \sup_{M \setminus \Sigma} u \leq C_1. \] (4.22)

There is a neighborhood $U$ containing $x_1$ with the following property:
Given $\theta > 0$, there is a constant $C = C(\theta)$ such that
\[ u(x) \leq (2 - \theta) \log d_g(x, x_1) + C(\theta) \] for all $x \neq x_1$ in $U$.

Proof. To prove (4.22), let $K \subset M^n \setminus \Sigma$ be a compact set containing $x_0$. By (4.19), we have a bound
\[ \int_K e^{\alpha u} d\text{vol}_g \leq C_\alpha \] for any $\alpha > 0$. Therefore, by Proposition 3.3 we have a global bound
\[ \max_{M^n} u_i \leq C_1. \] (4.24)
Thus the limit must satisfy
\[ \sup_{M^n \setminus \Sigma} u \leq C_1. \]

Turning to the proof of (4.23), note that the bound (4.24) allows us to apply Corollary 3.9. Therefore, for fixed $\delta > 0$ satisfying (3.30) and any $\alpha > \alpha_\delta \equiv \frac{(n-2)}{(1-2\delta)}$, we have
\[ \| e^{(\alpha/p)u} \|_{L^p} \leq C \| e^{(\alpha/p)u} \|_{L^p} \leq C, \] (4.25)
where
\[ p = n + 2\alpha_\delta, \]
\[ \gamma_0 = \frac{2\alpha_\delta}{n + 2\alpha_\delta} > 0. \]

Choose a small neighborhood $U$ of $x_1$ that is disjoint from the other singular points. For $i > J$ sufficiently large we may assume that $P_i \in U$, where $P_i \to x_1$ is the sequence in (4.21). If $x \neq x_1$ is a point in $U$, then by (4.25)
\[ |e^{(\alpha/p)u_i(x)} - e^{(\alpha/p)u_i(P_i)}| \leq C d_g(x, P_i)^{\gamma_0}. \] (4.26)
Letting $i \to \infty$ in (4.26), by (4.21) we conclude
\[ e^{(\alpha/p)u(x)} \leq C d_g(x, x_1)^{\gamma_0}. \]
This implies
\[ \sup_{M^n \setminus \Sigma} u \leq C d_g(x, x_1)^{\gamma_0}. \] (4.27)
Using the definition of $p$ in (3.18), the exponent in (4.27) satisfies
\[ \frac{p^\gamma}{\alpha} = 2 \frac{\alpha_\delta}{\alpha} < 2, \]
so that taking logarithms in (4.27) we get
\[ u(x) \leq 2 \left( \frac{\alpha_\delta}{\alpha} \right) \log d_g(x, x_1) + C. \]
(4.28)

Therefore, given $\theta > 0$, we can choose $\alpha > \alpha_\delta$ close enough to $\alpha_\delta$ so that
\[ 2 \frac{\alpha_\delta}{\alpha} \geq 2 - \theta, \]
and (4.23) follows from (4.28).

While Proposition 4.5 gives fairly precise upper bounds on $u = \lim_i u_i$ near $x_1$, the epsilon-regularity result Proposition 3.2 can be used to give lower bounds:

**Proposition 4.6.** There are a neighborhood $U'$ of $x_1$ and a constant $C > 0$ such that
\[ u(x) \geq \log d_g(x, x_1) - C \]
for all $x \neq x_1$ in $U'$.

**Proof.** This result follows from inequality (3.4). More precisely, by the volume bound (4.6),
\[ \text{vol}(g_i) = \int_{M^n} e^{-nu_i} d\text{vol}_g \leq v_0. \]
It follows that $u = \lim_i u_i$ satisfies
\[ \text{vol}(g_u) = \int_{M^n} e^{-nu} d\text{vol}_g \leq v_0. \]
Therefore, for $\rho_0 > 0$ small enough,
\[ \int_{B(x_1, \rho_0)} e^{-nu} d\text{vol}_g \leq \frac{1}{2} \varepsilon_0, \]
where $\varepsilon_0$ is the constant in the statement of Proposition 3.2.

Given $x \neq x_1$ in $U' = B(x_1, \rho_0/2)$, let $\rho = \frac{1}{2} d_g(x, x_1)$. Then $B(x, \rho) \subset B(x_1, \rho_0)$, so that
\[ \int_{B(x, \rho)} e^{-nu} d\text{vol}_g < \int_{B(x_1, \rho_0)} e^{-nu} d\text{vol}_g \leq \frac{1}{2} \varepsilon_0. \]
Therefore, by inequality (3.4),
\[ \inf_{B(x, \rho/2)} u \geq \log \rho - C, \]
which implies
\[ u(x) \geq \log d_g(x, x_1) - C. \]
Combining Propositions 4.5 and 4.6, we conclude that the assumption (4.18) on which they are based cannot be true:

**Corollary 4.7.** The sequence \( \{u_i\} \) must satisfy

\[
\limsup_i u_i(x_0) = +\infty.
\]

Consequently, there are a subsequence (again denoted \( \{u_i\} \)) and a non-empty set of points \( \Sigma_0 = \{x_1, x_2, \ldots, x_\nu\} \subseteq \Sigma \) with the following properties:

(i) Given any compact \( K \subset \mathcal{M}^n \setminus \Sigma_0 \) and number \( N > 0 \), there is a \( J = J(K, N) \) such that

\[
\min_K u_i \geq N
\]

for all \( i \geq J = J(K, N) \).

(ii) For each \( x_k \in \Sigma_0 \), there is a sequence of point \( \{P_{k,i}\} \) such that

\[
\lim_i P_{k,i} = x_k,
\]

and

\[
\lim_i u_i(P_{k,i}) = -\infty.
\]

**Proof.** Taking \( \theta = 1/2 \) in Proposition 4.5 we get

\[
u(x) \leq \frac{3}{2} \log d_g(x, x_1) + C
\]

for \( x \) near \( x_1 \). On the other hand, \((4.29)\) implies

\[
u(x) \geq \log d_g(x, x_1) - C'.
\]

Since these inequalities contradict one another when \( x \) is close enough to \( x_1 \), we conclude that (4.18) is false. Therefore, (4.30) must hold.

Now, according to Proposition 4.4, given any compact \( K \subset \mathcal{M}^n \setminus \Sigma \), there is a constant \( C = C(K) > 0 \) such that

\[
\max_K |\nabla u_i| \leq C(K)
\]

for all \( i \geq J = J(K) \). Therefore, choosing a subsequence so that \( \lim_i u_i(x_0) = \limsup_i u_i(x_0) = +\infty \), we see that the gradient bound (4.34) implies that (4.31) holds for any \( N > 0 \) and all \( i \) sufficiently large, at least for \( K \subset \mathcal{M}^n \setminus \Sigma \). Once again, however, by restricting to a subsequence we may be reducing the singular set.

Near each point \( x_k \in \Sigma = \{x_1, \ldots, x_\ell\} \), there are two possibilities to consider. First, suppose in a neighborhood \( V \) of \( x_k \) we have

\[
u_i \geq -C.
\]
Then the local $C^2$-estimate of Guan and Wang (Lemma 3.1) would imply
\[ |\nabla^2 u_i| + |\nabla u_i|^2 \leq C' \]
in a neighborhood $V' \subset V$. Since $u_i \to +\infty$ pointwise on $M^n \setminus \Sigma$, (4.31) is valid on any compact $K \subset M^n \setminus (\Sigma \setminus \{x_k\})$ for $i$ sufficiently large. In this case, $x_k \notin \Sigma_0$.

The alternative to (4.35) is that near $x_k \in \Sigma$ there is a sequence of points $\{P_{k,i}\}$ satisfying (4.32) and (4.33). In this case, $x_k \in \Sigma_0$.

Finally, note that the subsequence $\{u_i\}$ can always be chosen so that $\Sigma_0 \neq \emptyset$. Otherwise, $\{u_i\}$ would have to be bounded from below near each point in $\Sigma$, and consequently on all of $M^n$. Combining the gradient estimate of Guan-Wang with the fact that $-u_i \to +\infty$ pointwise on $M^n \setminus \Sigma$, we would conclude that
\[ \min_{M^n} u_i \to +\infty. \]
But this contradicts the conclusion of Proposition 4.1.

Remark. Any sequence $\{u_i\}$ of $\Gamma$-admissible solutions of (1.13) has a subsequence which satisfies the conclusions of Corollary 4.7, since the proof just relies on the results of Section 3 and Lemma 4.2. For the same reasons, Corollary 4.7 is valid for any sequence $\{u_i\}$ of solutions to $\check{\Psi}_{t_i}[u_i] = 0$.

5. The re-scaled sequence

Since $\{u_i\}$ is diverging to $+\infty$ away from the singular set $\Sigma_0$, we need to normalize the sequence if we hope to extract a limit. Let $x_0 \notin \Sigma_0$ again be a “regular” point, and define
\[ w_i(x) = w_i(x) - w_i(x_0). \]
Using the properties of $\{u_i\}$ derived in the preceding section, we first show that (a subsequence of) $\{w_i\}$ converges off $\Sigma_0$ to a $C^{1,1}_{\text{loc}}$-limit.

\[ \text{Proposition 5.1. (i) Given } r > 0 \text{ small enough, let } M^n_r = M^n \setminus \bigcup_{x_k \in \Sigma_0} B(x_k, r). \]
Then there is a constant $C > 0$, which is independent of $i$ and $r$, such that
\[ |\nabla^2 w_i|(x) + |\nabla w_i|^2(x) \leq C r^{-2} \]
for $x \in M^n_r$ and all $i > J = J(r)$.

(ii) The sequence $\{w_i\}$ is bounded above:
\[ \max_{M^n} w_i \leq C \]
for some constant $C > 0$. 
Proof. (i) As we saw in Corollary 4.7, the original sequence \( \{u_i\} \) is diverging uniformly to \( +\infty \) on compact sets \( K \subset M^n \setminus \Sigma_0 \). Let \( y \in M^n \); then the ball \( B(y, r/2) \subset M^n \setminus \Sigma_0 \). Therefore,

\[
\lim_{i \to \infty} \inf_{B(y,r/2)} u_i = +\infty.
\]

Applying the local estimate Lemma 3.1 on the ball \( B(y, r/2) \), we conclude that each \( u_i \) satisfies

\[
|\nabla^2 u_i|(x) + |\nabla u_i|^2(x) \leq C \left( r^{-2} + e^{-2\inf_{B(y,r/2)} u_i} \right)
\]

for all \( x \in B(y, r/4) \). Of course, since \( u_i \) and \( w_i \) only differ by a constant, this implies

\[
|\nabla^2 w_i|(x) + |\nabla w_i|^2(x) \leq C \left( r^{-2} + e^{-2\inf_{B(y,r/2)} u_i} \right)
\]

for all \( x \in B(y, r/4) \). By (5.4), there is a \( J = J(y) \) such that

\[
e^{-2\inf_{B(y,r/2)} u_i} < r^{-2}
\]

for \( i > J \). Substituting this into (5.5) we get

\[
|\nabla^2 w_i|(x) + |\nabla w_i|^2(x) \leq Cr^{-2}
\]

for all \( x \in B(y, r/4) \) and \( i > J = J(y) \).

The balls \( \{B(y, r/4)\}_{y \in M^n} \) define an open cover of \( M^n \), and since \( M^n \) is compact we can extract a finite subcover \( M^n \subset \bigcup_{\nu=1}^N B(y_\nu, r_\nu/4) \). Let \( J = \max_{1 \leq \nu \leq N} J_\nu \). For any \( x \in M^n \), there is a ball with \( x \in B(y_\nu, r_\nu/4) \), and inequality (5.6) is valid for \( i > J \). This proves (5.2).

(ii) Since \( w_i(x_0) = 0 \), in view of the bound (5.6) there must be a small ball \( B(x_0, \rho_0) \) and a constant \( C > 0 \) such that

\[
\sup_{B(x_0, \rho_0)} w_i \leq C,
\]

for all \( i \geq 1 \). This implies

\[
\int_{B(x_0, \rho_0)} e^{\alpha w_i} dvol_g \leq C_\alpha
\]

for any \( \alpha > 0 \). By Proposition 3.3, we obtain a global bound:

\[
\max_{M^n} w_i \leq C.
\]
Corollary 5.2. A subsequence of \( \{w_i\} \) converges on compact sets \( K \subset M^n \setminus \Sigma_0 \) in \( C^{1,\beta}(K) \), any \( \beta \in (0, 1) \). Moreover,

(i) the limit \( w = \lim_i w_i \) is in \( C^{1,1}_{\text{loc}}(M^n \setminus \Sigma_0) \).

(ii) The Hessian \( \nabla^2 w(x) \) is defined at almost every \( x \in M^n \).

(iii) The tensor \( S_w(x) \) is positive semi-definite at almost every \( x \in M^n \).

Proof. Most of the statements are immediate consequences of Proposition 5.1, the Arzela-Ascoli theorem, and the fact that \( w_i(x_0) = 0 \). From Rademacher’s theorem, \( \nabla^2 w \) is well-defined almost everywhere (meaning the matrix of second partials is well-defined almost everywhere), and \( \nabla^2 w \in L^\infty_{\text{loc}} \).

Statement (iii) follows from a standard limiting argument using an integration by parts; we therefore omit the details.

Lemma 5.3. We have the following estimates for \( w \):

\[
|\nabla w|_g(x) \leq \frac{C}{d_g(x,x_k)},
\]

and for any \( s > 1 \),

\[
|\nabla w|_{C^{0,1}(A_g(r, sr))} \leq \frac{C}{r^s},
\]

where \( A_g(r, sr) \) is the annulus in the metric \( g \), and we take the Lipschitz seminorm: that is,

\[
\|f\|_{C^{0,1}(\Omega)} = \sup_{x,y \in \Omega, x \neq y} \frac{|f(x) - f(x)|}{d_g(x,y)},
\]

for any domain \( \Omega \).

Proof. The estimates (5.2) hold for the \( w_i \), and since \( w \) is the \( C^{1,1} \)-limit obtained using the Arzela-Ascoli theorem, the lemma follows immediately.

Remark. The preceding analysis can be applied to any sequence of \( \Gamma \)-admissible solutions \( \{u_i\} \) to (1.13), rescaled so as to converge in \( C^{1,\alpha} \) on compact sets in the manner described by Corollary 5.2. In particular, the limit \( w = \lim_i w_i \) will satisfy the conclusions of Corollary 5.2.

In fact, all the results of the next two Sections 6 and 7 apply to such (rescaled) sequences of solutions. For this reason, from now on we will refrain from calling this fact to the reader’s attention.
6. Analysis of the singularities

The main result of this section is Theorem 6.8, which gives a preliminary estimate of the limiting function near each \( x_k \in \Sigma_0 \):

\[
2 \log d_g(x, x_k) - C \leq w(x) \leq 2 \log d_g(x, x_k) + C.
\]

As we shall see, the first inequality above is a fairly easy consequence of the maximum principle; the second inequality, however, is much more delicate. One consequence of this estimate is that the metric

\[
g_w = e^{-2w} g
\]

is complete. In Section 7 we will give further refinements of the asymptotic behavior of \( w \) near \( \Sigma_0 \), which in turn give us a better understanding of the behavior of the metric \( g_w \) near infinity.

We begin with the proof of the first inequality in (6.1). This estimate would be an easy consequence of the maximum principle, except for the fact that \( w \) is not \( C^2 \). Therefore, we need to prove the corresponding statement for the \( w_i \)'s, then take a limit.

**Proposition 6.1.** There is a constant \( C \) such that

\[
w_i(x) \geq 2 \log d_g(x, x_k) - C
\]

for all \( x \) near \( x_k \in \Sigma_0 \).

**Proof.** It will simplify matters if we use the notation introduced in the proof of Proposition 3.3. Let \( v_i = e^{-\frac{(n-2)}{2}w_i} \), then by (3.11) \( v_i \) satisfies

\[
Lv_i = \Delta v_i - \frac{(n-2)}{4(n-1)} Rv_i \leq 0,
\]

where \( L \) is the conformal laplacian. Given \( x_k \in \Sigma_0 \), let \( \Gamma_k = \Gamma(x_k, \cdot) \) denote the Green’s function for \( L \) with singularity at \( x_k \) (note that \( L \) exists since \( R > 0 \)). Define

\[
\Gamma = \sum_k \Gamma_k,
\]

and

\[
G_i = \frac{v_i}{\Gamma}.
\]

Then an easy calculation using (6.4) shows

\[
\Delta G_i + 2\langle \nabla G_i, \nabla \Gamma / \Gamma \rangle \leq 0
\]

on \( M^n \setminus \Sigma_0 \), where \( \langle \cdot, \cdot \rangle \) denotes the inner product. By the maximum principle, for all \( r > 0 \) small enough

\[
\min_{M^n} G_i = \min_{\partial B(x_k, r)} G_i.
\]
Now, by the gradient estimate (5.2),
\[ \max \frac{\partial B}{\partial B(x_k)} w_i - \min \frac{\partial B}{\partial B(x_k)} w_i \leq C_n r \max \left| \nabla w_i \right| \leq C_n r (C/r) = C, \]
and consequently we have the Harnack inequality
\[ \max \frac{\partial B}{\partial B(x_k)} v_i \leq C \min \frac{\partial B}{\partial B(x_k)} v_i, \]
independent of \( r \). Since \( \Gamma \) satisfies a similar inequality, it follows that \( G_i \) must:
\[ \max \frac{\partial B}{\partial B(x_k)} G_i \leq C \min \frac{\partial B}{\partial B(x_k)} G_i. \]
Therefore, by (6.8),
\[ \max_{\cup \partial B(x_k,r)} G_i \leq C \min_{M^n \Sigma_0} G_i. \]
The last inequality implies that \( G_i \) is bounded on all of \( M^n \Sigma_0 \). To see this, first note that for \( r > 0 \) small, if \( x_0 \) is our regular point then (6.9) implies
\[ \max_{\cup \partial B(x_k,r)} G_i \leq C G_i(x_0) = C \Gamma^{-1}(x_0) \leq C. \]
This shows that
\[ \max_{M^n \Sigma_0} G_i \leq C \]
independent of \( i \). Therefore
\[ e^{-\frac{(n-2)w_i}{C}} \leq C. \]
Finally, since
\[ \Gamma(x_k, x) \sim d_g(x_k, x)^{(2-n)}, \]
by taking logarithms we get (6.3).

**Corollary 6.2.** There is a constant \( C \) such that
\[ (6.10) \quad w(x) \geq 2 \log d_g(x, x_k) - C \]
for all \( x \) near \( x_k \in \Sigma_0 \).

**Proof.** Inequality (6.10) follows from (6.3) by letting \( i \to \infty \) and using the fact that \( \{w_i\} \) converges in \( C^{1, \beta} \) off of \( \Sigma_0 \).

To prove the second inequality in (6.1) we proceed in two stages. First, we prove a slightly weaker version of the result:

**Proposition 6.3.** Given \( \theta > 0 \), there is a constant \( C = C(\theta) \) such that near each \( x_k \in \Sigma_0 \),
\[ (6.11) \quad w(x) \leq (2 - \theta) \log d_g(x, x_k) + C(\theta) \]
for all \( x \neq x_k \).
Proof. Using Corollary 4.7, the proof of (6.11) is identical in its details to the proof of Proposition 4.5 (ii), and will therefore be omitted.

In the following, fix $x_k \in \Sigma_0$ and let $\rho = \rho(x) = d_g(x, x_k)$. We will assume that $\rho$ is well defined for $\rho < \rho_0 < 1$. An easy consequence of (6.11) is

**Lemma 6.4.**
\[
\lim_{x \to x_k} \frac{w(x)}{\log \rho(x)} = 2.
\]

**Proof.** Given any $\theta > 0$, by (6.10) and (6.11) we know
\[
2 \log \rho(x) - C \leq w(x) \leq (2 - \theta) \log \rho(x) + C(\theta).
\]
Therefore,
\[
2 \geq \lim_{x \to x_k} \frac{w(x)}{\log \rho(x)} \geq (2 - \theta).
\]
Since $\theta > 0$ was arbitrary, Lemma 6.4 follows.

We now give the proof of the second inequality of (6.1):

**Theorem 6.5.** Near $x_k \in \Sigma_0$, the function $w$ satisfies
\[
w(x) \leq 2 \log \rho(x) + C. \tag{6.12}
\]

**Proof.** As in the preceding proofs, the argument is complicated by the fact that $w$ is not in $C^2$. Moreover, we cannot argue, as we did in the proof of Proposition 6.1, by establishing the result for the sequence $\{w_i\}$ and then passing to a limit: the $w_i$’s clearly do not satisfy (6.12). To get around this difficulty we first prove an estimate for $w$ on a dyadic annulus of fixed radius, then iterate the estimate to bound the growth of $w$ near $x_k$. The key technical ingredient in this analysis is the following proposition:

**Proposition 6.6.** Choose a point, say $x_1 \in \Sigma_0$, and let $B(a)$ denote the geodesic ball of radius $a > 0$ centered at $x_1$. There exist constants $K, a_0 > 0$ such that if $a < a_0$,
\[
\max_{\partial B(a/2)} w \leq \max_{\partial B(a)} w - 2 \log a + \left[2 - K(a/2)^2\right] \log(a/2). \tag{6.13}
\]

**Proof.** For fixed $a > 0$ and small, let
\[
W(x) = w(x) - \max_{\partial B(a)} w + 2 \log a, \tag{6.14}
\]
and
\[
F(x) = \frac{W(x)}{\log \rho}. \tag{6.15}
\]
Later in the proof we will impose further conditions on \( a \), but for now we just require that \( a < 1 \) be small enough so that \( \rho \) is well defined in \( B(a) \). Note that \( \log \rho(x) < 0 \) for \( x \in B(a) \).

Now, by Lemma 6.4 we have

\[
\lim_{x \to x_1} F(x) = 2. \tag{6.16}
\]

Also, if \( x \in \partial B(a) \), then

\[
W(x) = w(x) - \max_{\partial B(a)} w + 2 \log a \leq 2 \log a,
\]

which implies

\[
\min_{\partial B(a)} F \geq 2. \tag{6.17}
\]

From (6.16) and (6.17) we conclude that either

\[
F(x) \geq 2 \quad \forall x \in B(a), \tag{6.18}
\]

or \( F \) attains its minimum in the interior of \( B(a) \setminus \{x_1\} \). However, if (6.18) holds then inequality (6.13) follows almost immediately. To see this, let \( y_0 \) be a point at which \( F \) attains its minimum on \( \partial B(a/2) \). Then (6.18) implies

\[
2 \leq F(y_0) = \frac{\max_{\partial B(a/2)} w - \max_{\partial B(a)} w - 2 \log a}{\log(a/2)} \Rightarrow \max_{\partial B(a/2)} w \leq \max_{\partial B(a)} w - 2 \log a + 2 \log(a/2).
\]

Thus, (6.13) holds with \( K = 0 \). We may therefore assume \( F \) attains its minimum at a point \( z_0 \in B(a) \setminus \{x_1\} \).

To prove (6.13) we want to apply the strong maximum principle to \( F \), though one needs to amend this statement slightly because of regularity considerations. As observed above, \( w \in C^{1,1}_{\text{loc}} \) while the distance function \( \rho \) is smooth on the deleted ball \( B(a) \setminus \{x_1\} \). Thus, \( F \) is \( C^{1,1}_{\text{loc}} \) in a small neighborhood \( U_0 \) of \( z_0 \). Given \( \delta > 0 \), we define a differential operator \( \mathcal{L} \) in \( U_0 \) by

\[
\mathcal{L}u = a^{ij} \nabla_i \nabla_j u,
\]

where \( \{a^{ij}\} \) are the components of the tensor

\[
a = (n - 2)d\rho \otimes d\rho + (1 - 2\delta)g. \tag{6.20}
\]

For \( \delta > 0 \) sufficiently small \( \mathcal{L} \) is obviously strictly elliptic. If \( F \) were \( C^2 \) it would follow that \( \mathcal{L}F(z_0) \geq 0 \), since \( z_0 \) is a minimum point. However, \( F \) is only \( C^{1,1}_{\text{loc}} \), so while \( \nabla^2 F \) exists almost everywhere it may happen that \( \mathcal{L}F(z_0) \) is not defined. Despite this, there must be points nearby for which \( \mathcal{L}F \) is almost non-negative:
Lemma 6.7. There is a sequence of points \( \{ z_j \} \) in \( U_0 \) satisfying

(i) \( z_j \to z_0 \) as \( j \to \infty \),
(ii) \( \nabla^2 F(z_j) \) exists,
(iii) \( \liminf_{j \to \infty} \mathcal{L} F(z_j) \geq 0 \),
(iv) \( \nabla F(z_j) \to 0 \) as \( j \to \infty \).

Proof. Since \( z_0 \) is a minimum point of \( F \in C^{1,1}(U_0) \), conclusion (iv) holds for any sequence of points \( z_j \to z_0 \). If (iii) failed for every sequence satisfying (i) and (ii), then there would be a neighborhood \( U_1 \subseteq U_0 \) such that

\[
\mathcal{L} F(z) \leq 0
\]

at every point \( z \in U_1 \) where \( \nabla^2 F(z) \) exists (in fact, \( \mathcal{L} F(z) < 0 \) at every such point, but for our purposes it is enough to assume the weaker inequality). In particular, (6.21) would hold almost everywhere in \( U_1 \).

Now, \( \mathcal{L} \) is not written in divergence form, but this is easy to do:

\[
\mathcal{L} u = \nabla_i (a^{ij} \nabla_j u) - b^j \nabla_j u,
\]

where \( \{ b^j \} \) are the components of the divergence of \( \{ a^{ij} \} \):

\[
b^j = \nabla_k a^{jk}.
\]

It is important to note that the neighborhoods \( U_1 \subseteq U_0 \) do not contain \( x_1 \), so the distance function \( \rho \), and consequently the coefficients of \( \mathcal{L} \), are all smooth on \( U_1 \).

Returning to inequality (6.21), if \( \varphi \in C_0^\infty(U_1) \), then by (6.21) and (6.22) we have

\[
\int_{U_1} \left( -a^{ij} \nabla_i \varphi \nabla_j F - \varphi b^j \nabla_j F \right) d\text{vol} \leq 0.
\]

Therefore, \( F \) also satisfies (6.21) in \( U_1 \) in a weak \( W^{1,2} \)-sense. By the strong maximum principle for weak supersolutions (see [GT83], Theorem 8.19), it follows that \( F \) cannot have an interior minimum unless \( F \) is constant on \( U_1 \). Since \( z_0 \) is an interior minimum \( F \) must be constant on \( U_1 \), in which case the conclusions of Lemma 6.7 are obviously true. \( \square \)

We now apply Lemma 6.7 by calculating \( \mathcal{L} F \) at the points \( \{ z_j \} \) described above. To begin,

\[
\nabla_l F = \frac{\nabla_l W}{\log \rho} - \frac{W}{(\log \rho)^2} \frac{\nabla_l \rho}{\rho}.
\]

Differentiating again, and using (6.23), we obtain

\[
\nabla_k \nabla_l F = \frac{\nabla_k \nabla_l W}{\log \rho} - \frac{\nabla_k F \nabla_l \rho}{\log \rho} - \frac{\nabla_l F \nabla_k \rho}{\log \rho} + \frac{F}{\log \rho} \frac{\nabla_k \rho \nabla_l \rho}{\rho} + \frac{F}{\log \rho} \frac{\nabla_k \nabla_l \rho}{\rho}.
\]
Tracing (6.24) we have
\[ \Delta F = \frac{\Delta W}{\log \rho} - \frac{2}{\log \rho} \langle \nabla F, \nabla \rho \rangle + \frac{F}{\log \rho} \frac{1}{\rho^2} - \frac{F}{\log \rho} \frac{\Delta \rho}{\rho}. \]

Using (6.24) and (6.25) we can now write the expression for \( \mathcal{L}F \). In doing so we will make use of the following identities:
\[ \mathcal{L}u = (n - 2) \nabla^2 u (\nabla \rho, \nabla \rho) + (1 - 2\delta) \Delta u \]
for any function \( u \), and
\[ |\nabla \rho|^2 = 1, \quad \nabla^2 \rho (\nabla \rho, \nabla \rho) = 0. \]
Thus,
\[ (\log \rho) \mathcal{L}F = \mathcal{L}W + (n - 1 - 2\delta) \frac{F}{\rho^2} - (1 - 2\delta) \frac{\Delta \rho}{\rho} \]
\[ - 2(n - 1 - 2\delta) \langle \nabla F, \nabla \rho \rangle. \]
Since the background metric \( g \) is assumed to be \( k \)-admissible it must have positive Ricci curvature. Therefore, by the Laplacian Comparison Theorem,
\[ \frac{\Delta \rho}{\rho} \leq \frac{(n - 1)}{\rho^2}. \]
Substituting this into (6.27) we get
\[ (\log \rho) \mathcal{L}F \geq \mathcal{L}W + 2\delta(n - 2) \frac{F}{\rho^2} - 2(n - 1 - 2\delta) \langle \nabla F, \nabla \rho \rangle. \]

The next step involves estimating \( \mathcal{L}W \). By Corollary 5.2, for almost every \( z \), the Ricci curvature satisfies
\[ \operatorname{Ric}(g_w) - 2\delta \sigma_1(A_w) g \geq 0 \]
for \( \delta \leq \frac{(2k - n)(n - 1)}{2n(k - 1)}. \) In what follows, we fix a value of \( \delta > 0 \) satisfying this condition. Rewriting (6.29) using (3.20) and (3.21), we get
\[ (n - 2) \nabla^2 W + (1 - 2\delta) \Delta W g + (n - 2) dW \otimes dW \]
\[ - (n - 2)(1 - \delta) |\nabla W|^2 g + (\operatorname{Ric}_g - 2\delta \sigma_1(A_g) g) \geq 0. \]
Using (6.23), (6.26), and the inequality \( |\langle \nabla F, \nabla \rho \rangle| \leq |\nabla F| \), we can rewrite this as
\[ \mathcal{L}W \geq - \delta(n - 2) \frac{F^2}{\rho^2} - 2\delta(n - 2) F \log \rho \langle \nabla F, \nabla \rho \rangle \]
\[ - \delta(n - 2)(1 - \delta)(\log \rho)^2 |\nabla F|^2 - C. \]
Substituting this into (6.28), we finally arrive at
\[ (\log \rho) \mathcal{L}F \geq - \delta(n - 2) \frac{F^2}{\rho^2} + 2\delta(n - 2) \frac{F}{\rho^2} - C + \text{(terms with } \nabla F \text{)}. \]
Keep in mind that we are evaluating both sides of the above inequality at the points \( \{z_j\} \) described in Lemma 6.7. In particular, by property (iv) of this lemma, \(|\nabla F(z_j)| \to 0\) as \( j \to \infty \), and using property (iii) of the lemma along with the fact that \( \rho(z_j) \to \rho(z_0) = \rho_0 \), we see that for all \( j \) sufficiently large
\[
C \geq -\delta(n - 2) \frac{F^2(z_j)}{\rho(z_j)^2} + 2\delta(n - 2) \frac{F(z_j)}{\rho(z_j)^2}.
\]
Letting \( j \to \infty \), and completing the square, we obtain
\[
(F(z_0) - 1)^2 \geq 1 - C\rho_0^2.
\]
Solving this inequality, since \( \rho_0 \ll 1 \), one sees that there are two possible conclusions: either
\[
F(z_0) \geq 2 - C_1\rho_0^2 \tag{6.32}
\]
or
\[
F(z_0) \leq C_2\rho_0^2 \leq C_2a^2. \tag{6.33}
\]
We want to rule out (6.33). To do so we rely on Corollary 6.2, which implies
\[
\max_{\partial B(a)} w \geq 2 \log a - C_3,
\]
and consequently
\[
W(z_0) \leq w(z_0) + C_3.
\]
Therefore,
\[
F(z_0) = \frac{W(z_0)}{\log \rho_0} \geq \frac{w(z_0)}{\log \rho_0} - \frac{C_3}{\log \rho_0} \tag{6.34}
\]
From Lemma 6.4, we may then choose \( a > 0 \) small enough so that
\[
F(z_0) > 1, \tag{6.35}
\]
for all \( x \in B(a) \). At the same time, by (6.33), we can choose \( a > 0 \) small enough (just depending on the constant \( C_2 \)) so that
\[
F(z_0) \leq \frac{1}{2}. \tag{6.36}
\]
Since (6.35) and (6.36) obviously contradict one another, we conclude that (6.32) must hold:
\[
\min_{B(a)} F = F(z_0) \geq 2 - C_1\rho_0^2 \geq 2 - C_1a^2.
\]
Recalling the definition of \( F \), we now have the following:
\[
\frac{w(x) - \max_{\partial B(a)} w + 2 \log a}{\log \rho(x)} \geq 2 - C_1a^2.
\]
If we take $x$ to be a point at which $w$ attains its maximum on $\partial B(a/2)$, we obtain the inequality
\[
\frac{\max_{\partial B(a/2)} w - \max_{\partial B(a)} w + 2 \log a}{\log(a/2)} \geq 2 - C_1 a^2 = 2 - K(a/2)^2.
\]
Multiplying both sides of the above inequality by $\log(a/2)$ and rearranging terms, we arrive at (6.13):
\[
(6.37) \quad \max_{\partial B(a/2)} w \leq \max_{\partial B(a)} w - 2 \log a + 2 \log(a/2) + 2 \log(a/2) + K\left[(a/2)^2 \log(a/2) + \cdots + (a/2^{N})^2 \log(a/2^N)\right].
\]
Since the series
\[
(a/2)^2 \log(a/2) + \cdots = \sum_{k=1}^{\infty} (a/2^k)^2 \log(a/2^k)
\]
clearly converges, (6.38) implies
\[
(6.39) \quad \max_{\partial B(a/2)} w \leq \max_{\partial B(a)} w - 2 \log a + 2 \log(a/2^N) + C_4,
\]
where $C_4 = C_4(a)$.

To pass from Proposition 6.6 to Theorem 6.5, we iterate inequality (6.37) to obtain that for any $N > 1$,
\[
(6.38) \quad \max_{\partial B(a/2^N)} w \leq \max_{\partial B(a)} w - 2 \log a + 2 \log(a/2^N) - K\left[(a/2)^2 \log(a/2) + \cdots + (a/2^{N})^2 \log(a/2^N)\right].
\]
Combining Corollary 6.2 and Theorem 6.5, we have

**Theorem 6.8.** There is a constant $C$ such that
\[
(6.40) \quad 2 \log d_g(x, x_k) - C \leq w(x) \leq 2 \log d_g(x, x_k) + C
\]
for all $x$ near $x_k \in \Sigma_0$. 

7. Volume growth estimates and completion of proof

In this section we refine our estimates of the asymptotic behavior of \( w \) near the singular set, with the eventual goal of showing that the metric \( g_w = e^{-2w}g \) is isometric to the Euclidean metric.

7.1. Preliminary asymptotic behavior. As before, we write \( g_w = e^{-2w}g \), and the singular set is denoted \( \Sigma_0 = \{x_1, \ldots, x_\nu\} \). For \( x_k \in \Sigma_0 \), let \( r_{x_k}(x) = d_g(x_k, x) \) denote the distance in the background metric. Note that \( r_{x_k}^2 \) is Lipschitz on \( M^n \), and is smooth in a neighborhood of \( x_k \).

Let \( \tilde{r} \) be a smooth function on \( M^n \), positive on \( M^n \setminus \Sigma_0 \), such that \( \tilde{r} = r_{x_k} \) in a neighborhood of each singular point \( x_k \in \Sigma_0 \). We write the metric as

\[
g_w = e^{-2w}g = e^{-2\Psi} \cdot \tilde{r}^{-4}g = e^{-2\Psi} g_*
\]

where

\[
\Psi = w - 2 \log \tilde{r},
\]

\[
g_* = \tilde{r}^{-4}g.
\]

In this notation, Theorem 6.8 can be restated as

**Theorem 7.1.** There exists a constant \( C_1 > 0 \) so that

\[
-C_1 \leq \Psi(x) \leq C_1,
\]

for all \( x \in M^n_{\text{reg}} = M^n \setminus \Sigma_0 \).

Therefore, the metric \( g_w \) is a bounded perturbation of the metric \( g_* \). The asymptotic behavior of \( g_* \) is given by

**Lemma 7.2 ([LP87]).** For \( x_k \in \Sigma_0 \), let \( \{y^j\} \) be a Riemannian exponential normal coordinate system for \( g \) in a neighborhood \( U_k \) of \( x_k \). Let \( z^j = |y|^{-2}y^j \) denote inverted normal coordinates on \( U_k \setminus \{x_k\} \). Then with respect to these coordinates,

(i) \( r_{x_k}(y) = |y| = \sqrt{(y^1)^2 + \ldots (y^n)^2} \).

(ii) Let \( \rho(z) = |z| = \sqrt{(z^1)^2 + \ldots (z^n)^2} \); then \( g_* = \rho^4g \).

(iii) \( g_* \) is asymptotically flat of order two; i.e.,

\[
(g_*)_{ij} = \delta_{ij} + O(\rho^{-2}), \quad \frac{\partial}{\partial z^j}(g_*)_{ij} = O(\rho^{-3}), \quad \frac{\partial^2}{\partial z^j \partial z^m}(g_*)_{ij} = O(\rho^{-4}).
\]

**Remark.** The metric \( g_* \) is asymptotically flat of order 2, with a Euclidean end corresponding to each \( x_k \in \Sigma_0 \).

Lemma 7.2 implies the following expansion for the metric \( g_w \).
Lemma 7.3. Near each singular point, in inverted normal coordinates \(\{z^i\}\),

\[
e^{-2C_1}\delta_{ij} + O(\rho^{-2}) \leq (g_w)_{ij} \leq e^{2C_1}\delta_{ij} + O(\rho^{-2}),
\]

\[
\frac{\partial}{\partial z^l}(g_w)_{ij} = O(\rho^{-1}).
\]

Furthermore, for any \(s > 1\) and any \(l = 1 \ldots n\),

\[
\left\| \frac{\partial}{\partial z^l}(g_w)_{ij} \right\|_{C^{0,1}(A_0(\rho, sr))} = O(r^{-2}),
\]

where \(A_0(\rho, sr) = \{z : \rho < \rho(z) < sr\}\), and \(\left\| \cdot \right\|_{C^{0,1}(A_0(\rho, sr))}\) denotes the Lipschitz seminorm on the annulus with respect to the Euclidean metric.

Proof. Inequalities (7.5)–(7.7) follow from elementary calculations using Lemma 7.2, along with the estimates for \(w\) contained in Lemma 5.3 and Theorem 7.1.

7.2. Geodesic completeness. Let us fix \(x_0 \in M^n_{\text{reg}}\) and write

\[
M^n \setminus \Sigma_0 = M^n_{\text{reg}} = M_0 \cup M_1,
\]

where \(M_0\) is a compact smooth Riemannian manifold with boundary containing \(x_0\), and

\[
M_1 \approx \Pi^\nu_1(R^n \setminus B(0, R_0)),
\]

where \(B(0, R_0)\) denotes the open ball of radius \(R_0 > 0\) in \(R^n\). On each component we also have the inverted coordinates \(\{z^i\}\) as described in Lemma 7.2. We will call these components ends, denote them by \(\{N_j\}_{j=1}^\nu\), and implicitly use inverted coordinates to identify each \(N_j\) with \(R^n \setminus B(0, R_0)\). In particular, the coordinates \(\{z^i\}\) on \(N_j\) define a Euclidean metric \(ds^2\) with Euclidean distance function \(|\cdot|_0\). For example, given a point \(p \in N_1\), in inverted coordinates, we write \(p = (z^1, \ldots, z^n)\), and \(|p|_0 = \text{dist}(0, p) = |z| = \rho(z)\).

Since \(g_w\) is \(C^{1,1}\), the geodesic equation is a second order system of ODEs with Lipschitz coefficients. The local existence and uniqueness of solutions follow from a standard ODE theorem; see, for example, [CL55] or [Har82]. In particular, the exponential map \(\exp_{x_0} : T_{x_0}M^n \to M^n\) is defined in some neighborhood of the origin in \(T_{x_0}M^n\). The next proposition says that, in fact, geodesics can be infinitely extended.

Proposition 7.4. The manifold \((M \setminus \Sigma_0, e^{-2w}g)\) is geodesically complete. That is, for any \(x_0 \in M^n_{\text{reg}}\), the exponential map \(\exp_{x_0} : T_{x_0}M^n \to M^n_{\text{reg}}\) (of the metric \(g_w = e^{-2w}g\)) is defined on all of \(T_{x_0}M^n\).

Proof. Let \(x_0 \in M^n_{\text{reg}}\), and let \(\gamma(t)\) be a unit-speed geodesic with \(\gamma(0) = x_0\). Assume the maximal domain of definition of \(\gamma\) is \([0, T)\); we want to show that \(T = \infty\).
We will make use of the following property of geodesics: \( \gamma : [0, T) \rightarrow M_{\text{reg}}^n \) must leave every compact subset of \( M_{\text{reg}}^n \) as \( t \rightarrow T \). That is, given any compact subset \( K \subset M_{\text{reg}}^n \), there exists a \( t_K \) such that \( \gamma(t) \in M_{\text{reg}}^n \setminus K \) for all \( t > t_K \). For a simple proof of this fact, see [Pet98, p. 109].

Therefore, without loss of generality, we may assume there is a time \( 0 < a < T \) such that \( \gamma(t) \in M_1 \) for \( t \geq a \). Without loss of generality, we may assume that \( \gamma(t) \in N_1 \) for \( t \geq a \). For \( t \geq a \), by (7.5)

\[
|\dot{\gamma}(t)|_{g_w}^2 = (g_w)_{ij}(\gamma(t))\dot{\gamma}^i(t)\dot{\gamma}^j(t)
\]

(7.8)

\[
\leq \left( e^{2C_1} + O(|\gamma(t)|_0^{-2}) \right)|\dot{\gamma}(t)|^2
\]

\[
\leq \left( e^{2C_1} + \frac{C}{|\gamma(t)|_0^2} \right)|\dot{\gamma}(t)|_0^2.
\]

Note that in (7.8), and the inequalities which follow, we are using the identification \( M_1 = \mathbb{R}^n \setminus B(0, R_0) \); hence for \( t \geq a \) we have \( \gamma(t), \dot{\gamma}(t) \in \mathbb{R}^n \), and \( |\cdot|_0 \) denotes the Euclidean norm. Similarly, using (7.5) again we have

\[
|\dot{\gamma}(t)|_{g_w}^2 \geq \left( e^{-2C_1} - \frac{C}{|\gamma(t)|_0^2} \right)|\dot{\gamma}(t)|_0^2.
\]

Now let \( b \in (a, T) \), so that \( \gamma(b) \in M_1 \). Since \( \gamma \) has unit speed, the length of \( \gamma([0, b]) \) is given by

\[
b = L(\gamma([0, b])) = \int_0^b |\dot{\gamma}(t)|_{g_w} dt = \int_0^a |\dot{\gamma}(t)|_{g_w} dt + \int_a^b |\dot{\gamma}(t)|_{g_w} dt
\]

(7.9)

\[
\geq a + \int_a^b \left( e^{-C_1} - \frac{C}{|\gamma(t)|_0} \right)|\dot{\gamma}(t)|_0 dt.
\]

By the definition of \( a \),

\[
|\gamma(a)|_0 = \min_{t \in [a, b]} |\gamma(t)|_0,
\]

and so the integrand in (7.9) can be estimated as

\[
\left( e^{-C_1} - \frac{C}{|\gamma(t)|_0} \right)|\dot{\gamma}(t)|_0 \geq \left( e^{-C_1} - \frac{C}{|\gamma(a)|_0} \right)|\dot{\gamma}(t)|_0.
\]

Substituting this into (7.9) we obtain

\[
b \geq a + \left( e^{-C_1} - \frac{C}{|\gamma(a)|_0} \right) \int_a^b |\dot{\gamma}(t)|_0 dt.
\]

(7.10)

Since segments minimize distance in the Euclidean metric, we have

\[
\int_a^b |\dot{\gamma}(t)|_0 dt \geq |\gamma(b) - \gamma(a)|_0.
\]

Therefore,

\[
b - a \geq \left( e^{-C_1} - \frac{C}{|\gamma(a)|_0} \right)|\gamma(b) - \gamma(a)|_0.
\]

(7.11)
Now, recall that given any compact set $K \subset M_{reg}^n$, there must be a time $t_K$ with $\gamma(t) \in M_{reg}^n \setminus K$ for $t > t_K$. Therefore, by choosing a large enough compact set we can arrange so that $\gamma(b) \in M_{reg}^n \setminus K$ and $|\gamma(b) - \gamma(a)|_0$ is as large as we like. By (7.11), this means we can choose $b$ as large as we like, i.e., $T = \infty$. It follows that $(M_{reg}^n, g_w)$ is geodesically complete. 

7.3. Properties of the distance function. The distance function $d_w$ is defined on $M_{reg}^n \times M_{reg}^n$ by

\[ d_w(p, q) = \inf_{\gamma} \{ L_w(\gamma), \gamma : [t_0, t_1] \to M_{reg}^n \text{ is a piecewise } C^1 \text{ path joining } p \text{ and } q \}, \]

and

\[ L_w(\gamma) = \int_{t_0}^{t_1} |\dot{\gamma}(t)|_{g_w} \, dt. \]

We begin with a preliminary lemma on the convergence of the distance functions.

**Lemma 7.5.** For any compact subset $K \subset M_{reg}^n$,

\[ \lim_{i \to \infty} d_{g_i} = d_w, \]

uniformly on $K \times K$.

**Proof.** Take $p, q \in K$. First we show that

\[ \limsup_{i} d_{g_i}(p, q) \leq d_w(p, q). \]

Choose $\varepsilon > 0$, and let $\gamma_w$ denote a piecewise $C^1$ curve from $p$ to $q$ in $M_{reg}^n$ with $L_w(\gamma_w) \leq d_w(p, q) + \varepsilon$. If $L_{g_i}[\gamma_w]$ denotes the length of $\gamma_w$ with respect to $g_i$, then

\[ d_i(p, q) \leq L_{g_i}[\gamma_w]. \]

Letting $i \to \infty$, since $g_i \to g$ on compact sets,

\[ \limsup_{i} d_{g_i}(p, q) \leq L_w[\gamma_w] \leq d_w(p, q) + \varepsilon. \]

Since $\varepsilon$ is arbitrary, we obtain (7.14).

We now turn to the (more difficult) opposite inequality. To this end, let $\gamma_i : [\alpha_i, \beta_i] \to M_{reg}^n$ denote a minimizing geodesic from $p$ to $q$ in the metric $g_i$.

**Claim 7.6.** For $i \gg 1$ sufficiently large, there is a compact set $K \subset M_{reg}^n$ containing $p$ and $q$, such that the image of $\gamma_i$ lies entirely in $K$. 

Proof. To verify this claim, we argue by contradiction. Write \( \Sigma = \{x_1, \ldots, x_\nu\} \), and let
\[
M_r = M^n \setminus \bigcup_{k=1}^\nu B_g(x_k, r),
\]
where \( B_g \) means a ball in the background metric \( g \). Suppose that, for every \( r > 0 \), there is an infinite number of points \( x_i = \gamma_i(t_i) \) with \( x_i \in \partial M_r \). Since \( \{w_i\} \) converges in \( C^{1,\alpha} \) on \( M_r \), inequality (7.19) holds on \( M_r \) for every tangent vector \( X \) and all sufficiently large \( i \). Therefore,
\[
d_i(p, x_i) = \int_{\alpha_i}^{t_i} \sqrt{g(\dot{\gamma}_i, \dot{\gamma}_i)} dt \geq (1 - \delta)^{1/2} \int_{\alpha_i}^{t_i} \sqrt{g_w(\dot{\gamma}_i, \dot{\gamma}_i)} dt
\]
(7.18)
\[
\geq (1 - \delta)^{1/2} d_w(p, x_i)
\]
\[
\geq (1 - \delta)^{1/2} d_w(p, \partial M_r),
\]
for \( i \) sufficiently large, where \( d_w(p, \partial M_r) \) denotes the distance from \( p \) to \( \partial M_r \) in the metric \( g_w \).

From equation (7.11), it follows that
\[
d_w(p, \partial M_r) \to \infty \text{ as } r \to 0.
\]
In particular, (7.18) tells us that by first choosing \( r > 0 \) small enough, we can make \( d_i(p, x_i) \) as large as we like for \( i \) sufficiently large. More precisely: Given \( D \gg 1 \), there is a \( J = J(D) \) such that \( d_i(p, x_i) \geq D \) for all \( i > J \). But this implies
\[
d_i(p, q) \geq d_i(p, x_i) \geq D,
\]
for \( i > J \). If \( D \) is chosen large enough (say, \( D = 2d_w(p, q) \)), this obviously contradicts (7.14). \( \square \)

Now to complete the proof, since \( w_i \to w \) in \( C^{1,\alpha}(K) \), given \( \delta > 0 \) there is a \( J \gg 1 \) such that for all tangent vectors \( X \),
\[
g_i(X, X) = e^{-2w_i} g(X, X)
\]
(7.19)
\[
= e^{-2(w_i - w)} g_w(X, X) \geq (1 - \delta) g_w(X, X)
\]
for all \( i > J \). Therefore,
\[
d_i(p, q) = L_{g_i}[\gamma_i] = \int_{\alpha_i}^{\beta_i} \sqrt{g_i(\dot{\gamma}_i, \dot{\gamma}_i)} dt
\]
\[
\geq (1 - \delta)^{1/2} L_{g}[\gamma_i] \geq (1 - \delta)^{1/2} d_w(p, q).
\]
Taking the limit we obtain
\[
\liminf_i d_i(p, q) \geq (1 - \delta)^{1/2} d_w(p, q).
\]
Since this holds for all \( \delta > 0 \), we have
\[
\liminf_i d_i(p, q) \geq d_w(p, q).
\]
Proposition 7.7 (Bishop volume comparison). Fix any basepoint \( x_0 \in M_{\text{reg}}^n \). Then the ratio
\[
\frac{\text{Vol}_{g_\omega}(B_{g_\omega}(x_0, r))}{r^n} \leq \omega_n,
\]
and is a non-increasing function of \( r \), where \( \omega_n \) is the Euclidean volume growth constant.

Proof. Let \( g_j = e^{-2w_j}g \), where \( \{w_j\} \) is the sequence constructed in Section 5. By Corollary 5.2 the metrics \( \{g_j\} \) converge to \( g_\omega = e^{-2w}g \) in the \( C^{1,\alpha} \)-norm, for any \( \alpha < 1 \), on compact subsets of \( M_{\text{reg}}^n \). Let \( d_j(x) = d_{w_j}(x_0, x) \) denote the distance from \( x_0 \) in the metric \( g_j \), and let \( d(x) = d_w(x_0, x) \).

Since each \( g_j \) is a smooth metric with positive Ricci curvature, inequality (7.20) holds for each \( g_j \) (see [Pet98, Lemma 9.1.6]). That is, if \( r_2 \geq r_1 \) then
\[
\frac{\text{Vol}_{g_j}(B_{g_j}(x_0, r_2))}{r_2^n} \leq \frac{\text{Vol}_{g_j}(B_{g_j}(x_0, r_1))}{r_1^n} \leq \omega_n.
\]

Claim 7.8. The volume of balls satisfies
\[
\lim_{j \to \infty} \frac{\text{Vol}_{g_j}(B_{g_j}(x_0, r))}{r^n} = \frac{\text{Vol}_{g_\omega}(B_{g_\omega}(x_0, r))}{r^n}
\]
as \( j \to \infty \).

Proof. This follows directly from Lebesgue’s dominated convergence theorem. \( \square \)

To complete the proof of Proposition 7.7, we take the limit in (7.21). \( \square \)

Lemma 7.9. For each point \( x_0 \in M_{\text{reg}}^n \), there exists a radius \( r_{x_0} \) so that the distance function \( d_w(x_0, \cdot) \in C^{1,1}(B_{g_\omega}(x_0, r_{x_0}) \setminus \{x_0\}) \). Furthermore, the exponential map in the \( g_\omega \) metric, \( \exp_{x_0} : T_{x_0}M \cap B(0, r_{x_0}) \to B_{g_\omega}(x_0, r_{x_0}) \), is a Lipschitz homeomorphism.

Proof. By Proposition 5.1 and Corollary 5.2, the sequence \( \{w_j\} \) and its derivatives up to order two are uniformly bounded on \( B_0 = B_w(x_0, r_0) \), for some radius \( r_0 \). It follows that the metrics \( \{g_j\} \) have uniformly bounded curvature on \( B_0 \):
\[
\max_{B_0} |\text{Riem}_{g_j}| \leq C.
\]

If we take \( r_2 = r_0 \) and \( r_1 = r \) in (7.21), then
\[
\text{Vol}_{g_j}(B_{g_j}(x_0, r_0))r_0^{-n} \leq \text{Vol}_{g_j}(B_{g_j}(x_0, r))r^{-n}.
\]
Letting \( j \to \infty \) and using (7.22) imply
\[
\text{Vol}_{g_j}(B_{g_j}(x_0, r_0)) \to \text{Vol}_{g_\omega}(B_{g_\omega}(x_0, r_0)) > 0.
\]
In particular, we have a lower bound
\[(7.24) \quad \text{Vol}_{g_j}(B_{g_j}(x_0, r)) \geq v_0 \cdot r^n\]
for some $v_0 > 0$ and all $r < r_0$.

From the curvature bound (7.23) and the volume bound (7.24), by [CGT82, Th. 4.7] we conclude that the injectivity radius $\text{inj}_{g_j}(x_0)$ of $g_j$ at $x_0$ is strictly bounded from below, with the estimate
\[\text{inj}_{g_j}(x_0) \geq \Lambda r_0 > 0,\]
for some constant $\Lambda > 0$. In particular, for $r < \Lambda r_0$, the distance function $d_j^2 = d_j(x_0, \cdot)^2$ is smooth inside of $B_{g_j}(x_0, r)$.

Furthermore, using the curvature bound (7.23), from [Pet98, Lemma 10.4.2], we obtain a bound $|\nabla^2 d_j^2| \leq C$ on a possibly smaller ball $B_{g_j}(x_0, \Lambda' r_0)$. We have shown in Lemma 7.5 that $d_j \to d_w$ on compact subsets. From Arzela-Ascoli, by passing to another subsequence if necessary, we have $d_j^2 \to d_w^2$ in $C^{1,\alpha}$, and that $d_w^2 \in C^{1,1}$ in $B_{g_w}(x_0, \Lambda' r_0)$. This proves the first statement.

For the statement about the exponential map, the Lipschitz differentiability follows from the standard ODE dependence on initial conditions, see [Har82, Ch. V, Th. 8.1]. The exponential map must be injective on $B(0, r_{x_0})$; this follows since $d^2(x_0, \cdot)$ is $C^{1,1}$ there. To see why, suppose $v_1, v_2 \in B(0, r_{x_0}) \subset T_{x_0}M$ satisfied $\exp_{x_0}(v_1) = \exp_{x_0}(v_2) = q$. Then there would be two distinct geodesics starting from $x_0$ ending at $q$. Without loss of generality, we may assume $q$ is the first intersection point after $x_0$. From local uniqueness of geodesics through $q$ mentioned above, we would then have two distinct radial directions at $q$, which would imply that the distance function is not even $C^1$ at $q$, a contradiction.

\[\square\]

\textbf{Proposition 7.10 (Hopf-Rinow [Pet98]).} For each $x \in M_{\text{reg}}^n$, the exponential map in the $g_w$ metric, $\exp_x : T_x M^n \to M_{\text{reg}}^n$, is onto. Therefore, any $x_1, x_2 \in M_{\text{reg}}^n$ can be joined by a $C^2$-geodesic $\gamma : [0, d_w(x_1, x_2)] \to M_{\text{reg}}^n$.

\textbf{Proof.} The local unique minimizing property of geodesics follows from Lemma 7.9 (see [Pet98, Lemma 5.3.6]), and from the identity $|\nabla_w d_w| = 1$ on $B(x, r_x) \setminus \{x\}$. However, the local minimizing property, together with the properties of the exponential map proved in Lemma 7.9, are the key ingredients in the standard proof of Hopf-Rinow (see, for example, [Pet98, Th. 5.7.1]). \[\square\]

\textbf{7.4. Distance function estimates.} In the previous section, we showed that the manifold $(M_{\text{reg}}^n, g_w)$ is complete, but we need more precise information about the behavior of $g_w$ at infinity. We next show that for points in the same end of $M_{\text{reg}}^n$, distances measured with respect to $g_w$ are comparable to distances measured in the induced Euclidean metric.
Recall that $M^n = M_0 \cup M_1$, with
\[ M_1 \approx \Pi^w_1(R^n \setminus B(0, R_0)). \]
We denote the ends by $\{N_j\}_{j=1}^\nu$, and as before use inverted coordinates to identify each $N_j$ with $R^n \setminus B(0, R_0)$.

**Proposition 7.11.** Fix $x_0 \in M_0$ as in Proposition 7.4 and an end, say $N_1$. Then there are constants $R_1 > 0$ and $C_2 > 0$ such that for any $x \in N_1$ with $d_w(x_0, x) \geq R_1$, we have the distance estimates
\[
ed^{-C_2} |x|_0 - C_2 \leq d_w(x_0, x) \leq ed^{C_2} |x|_0 + C_2. \tag{7.25} \]

**Proof.** We will establish (7.25) through a series of technical lemmas. We begin with an estimate which was proved in Proposition 7.4.

**Lemma 7.12.** Let $p_1, p_2$ be in the same component of $M_1$ and assume that the geodesic between $p_1$ and $p_2$ in the $g_w$ metric lies entirely in $M_1$. Let $\gamma(a) = p_1$, and $\gamma(b) = p_2$, and assume that $|\gamma(a)|_0 = \min_{t \in [a, b]} |\gamma(t)|_0$.\tag{7.26}
Then
\[
ed^{-C_1} - \frac{C}{|p_1|_0}|p_2 - p_1|_0 \leq d_w(p_1, p_2). \tag{7.27} \]

**Proof.** This is a consequence of the formula (7.11). \hfill \square

**Lemma 7.13.** There exist constants $R_1 > 0$ and $C_3 > 0$ such that for $x \in N_1$ with $d_w(x_0, x) \geq R_1$, we have the distance estimate
\[
ed^{-C_3} |x|_0 - C_3 \leq d_w(x_0, x). \tag{7.28} \]

**Proof.** Let $x \in N_1$. From Proposition 7.10, there exists a unit-speed minimizing geodesic $\gamma$ with $\gamma(0) = x_0$ and $\gamma(d_w(x_0, x)) = x$. Choose $R' < |x|_0$ so that $B_w(x_0, R') \supset M_0$, where $B_w(x_0, R')$ denotes the geodesic ball in the $g_w$ metric (the existence of such an $R'$ also follows from Proposition 7.10). Let
\[
t_0 = \max\{t : |\gamma(t)|_0 = R', \gamma(t) \in N_1 \text{ for } t > t_0\}. \tag{7.29} \]
Let $p_0 = \gamma(t_0)$; then by Lemma 7.12
\[
ed^{-C_1} - \frac{C}{R'}|x - p_0|_0 \leq d_w(p_0, x). \tag{7.30} \]
If $|x|_0$ is sufficiently large, say $|x|_0 > R_1 \gg 1$, then $R'$ can be chosen large enough so that
\[
ed^{-C_1} - \frac{C}{R'} \geq e^{-2C_1}. \]
Thus,

\[ e^{-2C_1 |x - p_0|_0} \leq d_w(p_0, x). \]  

(7.31)

From the triangle inequality,

\[ d_w(p_0, x) \leq d_w(p_0, x_0) + d_w(x_0, x) \leq R' + d_w(x_0, x). \]

Substituting this into (7.31),

\[ d_w(x_0, x) \geq d_w(p_0, x) - R' \geq e^{-2C_1 |x - p_0|_0} - R' \geq e^{-2C_1 (|x|_0 - R')} - R', \]

which implies

\[ e^{-C_3} |x|_0 - C_3 \leq d_w(x_0, x) \]  

(7.32)

for some \( C_3 = C_3(C_1, R'). \)

**Lemma 7.14.** Let \( p_2 \in N_1 \) with \( |p_2|_0 \geq R_1 \), where \( R_1 \) is as given in Lemma 7.13. Let \( p_1 = \frac{R_1}{|p_2|_0} p_2 \in N_1 \). Then

\[ d_w(p_1, p_2) \leq \left( e^{C_1} + \frac{C}{R_1} \right) |p_2 - p_1|_0. \]  

(7.33)

**Proof.** Let \( \gamma \) denote the line segment in \( N_1 \) joining \( p_1 \) and \( p_2 \), and assume \( \gamma \) has unit speed (as measured in the Euclidean metric). Thus, \( \gamma : [0, |p_2 - p_1|_0] \rightarrow N_1 \) with \( |\dot{\gamma}(t)|_0 = 1, \gamma(0) = p_1 \), and \( \gamma(|p_2 - p_1|_0) = p_2 \). Then the length of \( \gamma \) in the \( g_w \) metric is

\[ L_{g_w}(\gamma) = \int_0^{|p_2 - p_1|_0} |\dot{\gamma}(t)|_{g_w} dt. \]

Clearly,

\[ |p_1|_0 = |\gamma(0)|_0 = \min_{0 \leq t \leq |p_2 - p_1|_0} |\gamma(t)|_0. \]

By the estimate (7.8),

\[ L_{g_w}(\gamma) \leq \int_0^{|p_2 - p_1|_0} \left( e^{C_1} + \frac{C}{|p_1|_0} \right) |\dot{\gamma}(t)|_0 dt \]

\[ \leq \left( e^{C_1} + \frac{C}{|p_1|_0} \right) \int_0^{|p_2 - p_1|_0} |\dot{\gamma}(t)|_0 dt \]

\[ = \left( e^{C_1} + \frac{C}{R_1} \right) |p_2 - p_1|_0. \]

Since the distance is the infimum of the length of all paths, we obtain

\[ d_w(p_1, p_2) \leq \left( e^{C_1} + \frac{C}{R_1} \right) |p_2 - p_1|_0. \]

\[ \square \]
Lemma 7.15. There is a constant $C_4 > 0$ such that for any $x \in N_1$, we have the distance estimate

\begin{equation}
    d_w(x_0, x) \leq e^{C_4|x|_0} + C_4.
\end{equation}

Proof. Let $x \in N_1$, then $|x|_0 \geq R_1$. Let $p_1 = \frac{R_1}{|x|_0} x$, and apply the previous lemma (with $p_2 = x$) to get

\begin{align*}
    d_w(p_1, x) &\leq \left(e^{C_1} + \frac{C}{R_1}\right)|x - p_1|_0 \\
    &\leq \left(e^{C_1} + \frac{C}{R_1}\right)(1 - \frac{R_1}{|x|_0})|x|_0 \\
    &\leq \left(e^{C_1} + \frac{C}{R_1}\right)|x|_0.
\end{align*}

Applying the triangle inequality

\begin{equation*}
    d_w(x_0, x) \leq d_w(x_0, p_1) + d_w(p_1, x),
\end{equation*}

we obtain

\begin{equation*}
    d_w(x_0, x) \leq d_w(x_0, p_1) + \left(e^{C_1} + \frac{C}{R_1}\right)|x|_0.
\end{equation*}

By construction, $|p_1|_0 = R_1$. From Proposition 7.10, there is a geodesic ball of radius $R_2$ such that $p_1 \in B_w(x_0, R_2)$ (in particular, the radius of this ball does not depend on the point $x$). Therefore,

\begin{equation*}
    d_w(x_0, x) \leq R_2 + \left(e^{C_1} + \frac{C}{R_1}\right)|x|_0.
\end{equation*}

Choosing $C_4 = C_4(C_1, R_1, R_2)$ large enough, this implies (7.34).

7.5. Tangent cone analysis. Propositions 7.4 and 7.11 give preliminary information about the geometry of the ends $N_j$ by observation of the behavior of the distance function near infinity. We now turn to results which describe the volume growth of $g_w$, which in turn will give us information about the curvature decay.

The first result in this direction is an integral estimate for the conformal factor $\Psi$ defined in (7.2). Recall that $g_w = e^{-2\Psi} g_*$, and that $g_*$ is asymptotically flat of order two (by Lemma 7.2). To pass from information about $g_*$ to information about $g_w$ requires estimation of the conformal factor $\Psi$. This is the motivation of the following result:
Theorem 7.16. For each end $N_j$, $1 \leq j \leq \nu$,
\begin{equation}
\int_{N_j} |\nabla g, \Psi|^n g^* d\text{vol}_{g^*} < \infty.
\end{equation}

Proof. Given radii $0 < r_1 < r_2$, let $A^*(r_1, r_2)$ denote the annulus centered at $x_0 \in M^n_{\text{reg}}$ with inner radius $r_1$ and outer radius $r_2$. Recall that $g_w = e^{-2\Psi} g^*$, and from Theorem 7.1 we know that $|\Psi| \leq C_1$.

Applying Theorem 3.5 with background metric $g^*$, $\delta = 0$, and $p = n$, we have
\begin{equation}
\int_{A^*(r_1, r_2)} |\nabla g, \Psi|^n e^{\alpha \Psi} d\text{vol}_{g^*} \leq C \left( \int_{A^*(\frac{1}{2} r_1, 2r_2)} |\text{Ric}_{g^*}|^{n/2} e^{\alpha \Psi} d\text{vol}_{g^*} 
+ r_1^{-n} \int_{A^*(\frac{1}{2} r_1, r_1)} e^{\alpha \Psi} d\text{vol}_{g^*} + r_2^{-n} \int_{A^*(r_2, 2r_2)} e^{\alpha \Psi} d\text{vol}_{g^*} \right),
\end{equation}
for any fixed $\alpha > 0$. We claim that the integrals on the RHS of (7.36) remain bounded with $r_1 > 0$ fixed and as $r_2 \to \infty$. Once we verify this, (7.35) follows.

By Lemma 7.2, the metric $g^*$ is asymptotically flat of order two. This implies that the curvature and volume growth of $g^*$ satisfy
\begin{equation}
\max_{A^*(r, 2r)} |\text{Ric}_{g^*}| \leq C r^{-4},
\end{equation}
\begin{equation}
\text{Vol}_{g^*}(A^*(r, 2r)) \leq C r^n,
\end{equation}
for some constant $C$ and all large $r \gg 1$. Therefore,
\begin{equation}
\int_{A^*(\frac{1}{2} r_1, 2r_2)} |\text{Ric}_{g^*}|^{n/2} e^{\alpha \Psi} d\text{vol}_{g^*} \leq C r_1^{-n},
\end{equation}
\begin{equation}
r_2^{-n} \int_{A^*(r_2, 2r_2)} e^{\alpha \Psi} d\text{vol}_{g^*} \leq C.
\end{equation}
Thus, (7.35) holds. 

Corollary 7.17. For each end $N_j$, $1 \leq j \leq \nu$,
\begin{equation}
\int_{N_j} |\nabla g_w, \Psi|^n g_w d\text{vol}_{g_w} < \infty.
\end{equation}

Proof. This is a consequence of the conformal invariance of the $L^n$-norm of the gradient. That is, since $g_w = e^{-2\Psi} g^*$,
\begin{equation}
|\nabla g_w, \Psi|^n g_w d\text{vol}_{g_w} = |\nabla g, \Psi|^n g^* d\text{vol}_{g^*}.
\end{equation}
Using Theorem 7.16 and Corollary 7.17, we can now study the volume growth of $g_w$.

**Proposition 7.18.** Fix an integer $m > 1$ and an end, say $N_1$. Let $x_0 \in M_0$ be the same point as in the statements of Propositions 7.4 and 7.11. Then

\[
\lim_{r \to \infty} \text{Vol}_{g_w}(A_1(m^{-1}r, r))r^{-n} = \omega_n(1 - m^{-n}),
\]

where $A_1(m^{-1}r, r) = \{x \in N_1 | m^{-1}r \leq d_w(x_0, x) \leq r\}$ is the annulus in the metric $g_w = e^{-2w}g$ in the end $N_1$, and $\omega_n$ is the volume ratio of Euclidean space.

**Proof.** The proof is based on a construction of the geometric tangent cone corresponding to the end $N_1$, as follows. Take any sequence of numbers $r_i$ such that $r_i \to \infty$ as $i \to \infty$, and consider the sequence of annuli $A_1(2^{-1}r_i, 2r_i) = \{x \in N_1 | 2^{-1}r_i \leq d_w(x_0, x) \leq 2r_i\}$. From now on we will drop the subscript, and it will be understood that for all annuli under consideration we take the component that lives in the end $N_1$.

For $r_i$ large enough there are inverted coordinates $\{z^j\}$ defined on $A_i = A(2^{-1}r_i, 2r_i) \subset N_1$. We introduce the rescaled coordinates $(z^j)' = \frac{z^j}{r_i}$ and the rescaled metrics $\tilde{g}_i = r_i^{-2}g_w$, both of which are defined on the rescaled annuli $(\tilde{A}_i(2^{-1}, 2), \tilde{g}_i) = (A_i, r_i^{-2}g_w)$.

The inequality (7.25) implies that $\tilde{A}_i(2^{-1}, 2)$ are bounded domains in $\mathbb{R}^n$, and are contained in a Euclidean annulus $A_0 = A_0(\varepsilon, \varepsilon^{-1})$ of bounded size. By the estimates (7.5), (7.6), and (7.7) and by the Arzela-Ascoli theorem it follows that for some subsequence (which we continue to index by $i$), $\tilde{g}_i \to g_\infty$ on compact subsets of $A_0$ in $C^{1,\alpha}$, for any $\alpha < 1$.

Now, by the scale-invariance of the estimate in Corollary 7.17,

\[
\lim_{i \to \infty} \int_{\tilde{A}_i} |\nabla \tilde{g}_i \Psi|_{\tilde{g}_i}^n d\text{vol}_{\tilde{g}_i} = \lim_{i \to \infty} \int_{A_i} |\nabla g_w \Psi|_{g_w}^n d\text{vol}_{g_w} = 0.
\]

It follows that $g_\infty$ must be a constant times the Euclidean metric. In particular, the limiting metric is flat.

**Claim 7.19.** The distance function to the basepoint $d_w = d_w(x_0, \cdot)$ is a viscosity solution of the Hamilton-Jacobi equation $|\nabla_w d_w|_w = 1$, away from the base point $x_0$.

**Proof.** First we observe that each $d_{w_i} = d_{w_i}(x_0, \cdot)$ is a viscosity solution of the Hamilton-Jacobi equation $|\nabla d_{w_i}|_{w_i} = 1$ away from $x_0$ (see [MM03], [AFLM05]). Using the convergence of the $d_i$ from Lemma 7.5, and convergence of the metrics in $C^{1,\alpha}$, the claim then follows from the well-known fact...
that a uniform limit of viscosity solutions to a sequence of uniformly convergent equations is a viscosity solution of the limiting equation (see [CEL84, Th. 1.4], or [CL83, Th. I.2]). Alternatively, using Lemma 7.9 and the Hopf-Rinow Proposition 7.10, the method of proof of [AFLM05, Th. 6.23] shows directly that $d_w$ is a viscosity solution of $|\nabla d_w| w = 1$.

Next, consider the rescaled distance functions $\rho_i(z') = r_i^{-1} d_w(p_0, r_i z')$. These are Lipschitz continuous functions on $\tilde{A}_i$ which also satisfy $|\nabla g, \rho_i| = 1$ in the viscosity sense. Again, by the Arzela-Ascoli theorem, some subsequence converges on compact subsets of $A_0$ in $C^\alpha$, for any $\alpha < 1$, to a limit $\tilde{\rho}$. Since the subsequence $\rho_i$ converges to a limit, the domains $\tilde{A}_i = \tilde{A}_i(2^{-1}, 2)$ converge to a limiting domain $\tilde{A}(2^{-1}, 2)$. Note that $\tilde{\rho}$ is Lipschitz continuous, and is a viscosity solution of $|\nabla g, \tilde{\rho}| = 1$ on the domain $\tilde{A}(2^{-1}, 2)$.

Claim 7.20. For $z' \in \tilde{A}(2^{-1}, 2)$,

$$e^{-C_2} |z'| \leq \tilde{\rho}(z') \leq e^{C_2} |z'|.$$  \hfill (7.41)

Proof. Given $z' \in \tilde{A}(2^{-1}, 2)$, let $z_i = r_i z'$. The distance estimates from Proposition 7.11 are

$$e^{-C_2} |z_i|_0 - C_2 \leq d_w(x_0, z_i) \leq e^{C_2} |z_i|_0 + C_2.$$

Dividing by $r_i$, we obtain

$$e^{-C_2} |z'|_0 - C_2 r_i^{-1} \leq r_i^{-1} d_w(x_0, z_i) \leq e^{C_2} |z'|_0 + C_2 r_i^{-1}.$$

As $i \to \infty$,

$$e^{-C_2} |z'|_0 \leq \lim_{i \to \infty} r_i^{-1} d_w(x_0, z_i) \leq e^{C_2} |z'|_0.$$

Since

$$\lim_{i \to \infty} r_i^{-1} d_w(x_0, r_i z') = \lim_{i \to \infty} \rho_i(z') = \tilde{\rho}(z'),$$

the claim follows. \hfill $\Box$

For the subsequence of radii $r_i$ chosen above we repeat this procedure for each integer $l > 2$, with annuli of size $A(l^{-1} r_i, lr_i)$, and obtain a nested sequence of limiting domains

$$\tilde{A}(2^{-1}, 2) \subset \tilde{A}(3^{-1}, 3) \subset \cdots \subset \tilde{A}(l^{-1}, l) \subset \cdots .$$

Clearly, the estimate (7.41) holds on every $\tilde{A}(l^{-1}, l)$, from which it easily follows that

$$\bigcup_{l=2}^{\infty} \tilde{A}(l^{-1}, l) = \mathbb{R}^n \setminus \{0\}$$

with the flat metric. Furthermore, the rescaled distance functions $\rho_i$ converge on compact subsets of $\mathbb{R}^n \setminus 0$ to $\tilde{\rho}$ in $C^\alpha$ for any $\alpha < 1$. The inequalities (7.41) imply that any level set $\{\tilde{\rho} = t\}$ is contained in a Euclidean annulus
A_{Euc}(e^{-2C_2 t}, e^{C_2 t}) \subset \mathbb{R}^n \setminus \{0\}. This implies that by definition, \( \tilde{\rho}(0) = 0 \), \( \tilde{\rho} \) has a continuous extension to \( \mathbb{R}^n \), and \( \tilde{\rho} \) is a Lipschitz viscosity solution of the equation \( |\nabla_0 \tilde{\rho}| = 1 \), on \( \mathbb{R}^n \setminus \{0\} \). By a standard uniqueness result for solutions of Hamilton-Jacobi equations ([BCD97, Th. IV.2.6]; see also [MM03, Th. 3.1], [AFLM05, Th. 6.23]), we must have \( \tilde{\rho}(x) = |x|_0 \), the Euclidean distance to the origin.

To complete the proof of Proposition 7.18, given any sequence \( r_i \to \infty \), the annuli \( A(\m r_i, r_i) \subset A(\m r_i, m r_i) \), and the rescalings of the larger annulus converge to Euclidean annuli. It necessarily follows that the rescalings of the smaller annuli also converge to Euclidean annuli, and therefore (7.40) holds. \( \square \)

Remark. Note that we have proved more than claimed—not only does the volume ratio converge, but all rescaled annuli converge to Euclidean annuli. In geometric terms, we have shown there is a unique tangent cone at infinity, which is Euclidean space.

Corollary 7.21. For each end \( N_j \),

\[
\lim_{r \to \infty} \text{Vol}_{g_w}(B(x_0, r) \cap N_j)r^{-n} \geq \omega_n.
\]

Proof. Fix an integer \( m > 0 \). We have \( A(m^{-1} r, m^{-1} r, r) \subset B(x_0, r) \), so that

\[
\text{Vol}_{g_w}(A(m^{-1} r, r)) r^{-n} \leq \text{Vol}_{g_w}(B(x_0, r)) r^{-n}.
\]

Taking the limit, and using Proposition 7.18, we have

\[
\omega_n (1 - m^{-n}) \leq \lim_{r \to \infty} \text{Vol}_{g_w}(B(x_0, r)) r^{-n}.
\]

This holds for any \( m > 0 \), so that the corollary follows when \( m \to \infty \). \( \square \)

7.6. Completion of proof. By Corollary 7.21, the asymptotic growth of the volume of geodesic balls in the metric \( g_w \) is Euclidean. If \( g_w \) were a (smooth) metric of non-negative Ricci curvature, the equality case of the Bishop comparison theorem would imply that \( g_w \) is flat. The goal of this section is to show that a “weak” version of Bishop’s theorem remains valid, and therefore we can still conclude \( g_w \) is flat. We do not attempt to prove a general result for \( C^{1,1} \) metrics, but instead rely on the special fact that \( g_w \) is the limit of smooth metrics with positive Ricci curvature.

At the end of the section we complete the proof of Theorem 2.2 by showing that, if \( g_w \) is the Euclidean metric, then \( (M^n, g) \) is conformally equivalent to the round sphere.

Proposition 7.22. The function \( w \in C^\infty(M^n_{\text{reg}}) \), is smooth. That is, the metric \( g_w = e^{-2w} g \) is smooth and there exists a smooth isometry

\[
\Phi: (M^n_{\text{reg}}, g_w) \to (\mathbb{R}^n, g_{Euc}),
\]

where \( g_{Euc} \) denotes the Euclidean metric.
Proof. Fix any point \( x_0 \in M_{\text{reg}} \). Combining Corollary 7.21 and Proposition 7.7, we see that there can be at most one end; that is, \( M_{\text{reg}}^n = M^n \setminus \{ x_1 \} \), and furthermore,

\[
Vol(B_{g_w}(x_0, r)) = \omega_n \cdot r^n
\]

for all \( r > 0 \).

Recall that we have shown in Lemma 7.9 that \( d_w^2 \in C^{1,1} \) in \( B_{g_w}(x_0, r_{x_0}) \), and \( d_j^2 \to d_w^2 \) in \( C^{1,\alpha} \). Inside the cutlocus, \( d_j^2 \) is smooth, so by the Laplacian comparison theorem we have

\[
\Delta_j d_j^2 \leq 2n.
\]

(7.46)

Since \( d_j \) converges to \( d_w \), this implies that the Laplacian comparison theorem

\[
\Delta_w d_w^2 \leq 2n
\]

(7.47)

holds for \( g_w \) in the weak \( W^{1,2} \) sense. Since \( d_w^2 \in C^{1,1}(B_{g_w}(x_0, r_{x_0})) \), Rademacher’s Theorem implies that

\[
\Delta_w d_w^2 \leq 2n \text{ a.e. in } B_{g_w}(x_0, r_{x_0}).
\]

(7.48)

Next, fix \( 0 < r_1 < r_2 < r_{x_0} \). Integrating by parts, we obtain

\[
\int_{A_{g_w}(r_1, r_2)} \Delta_w d_w^2 dV_w = 2\{r_2 \mathcal{H}^{n-1}(S(r_2)) - r_1 \mathcal{H}^{n-1}(S(r_1))\},
\]

(7.49)

where \( \mathcal{H}^{n-1}(S(r)) \) denotes the surface area (with respect to the metric \( g_w \)) of the submanifold \( S(r) = \{ x : d_w(x_0, x) = r \} \). Since \( d_w \) is \( C^{1,1} \) inside of \( A_{g_w}(r_1, r_2) \), this formula follows from the divergence theorem, and is also valid for \( C^{1,1} \) metrics. We then obtain

\[
2n \omega_n (r_2^n - r_1^n) = 2n Vol(A_{g_w}(r_1, r_2)) \geq \int_{A_{g_w}(r_1, r_2)} \Delta_w d_w^2 dV_w
\]

\[
= 2\{r_2 \mathcal{H}^{n-1}(S(r_2)) - r_1 \mathcal{H}^{n-1}(S(r_1))\}.
\]

Substituting in the above, we find that

\[
\int_{A_{g_w}(r_1, r_2)} \Delta_w d_w^2 dV_w = 2n \omega_n (r_2^n - r_1^n).
\]

Since \( d_w \) is \( C^{1,1} \), differentiating (7.45) implies that

\[
\mathcal{H}^{n-1}(S(r)) = n \omega_n r^{n-1}.
\]

Substituting in the above, we find that

\[
\int_{A_{g_w}(r_1, r_2)} \Delta_w d_w^2 dV_w = 2n \omega_n (r_2^n - r_1^n).
\]

We conclude that \( d_w \) is a \( C^{1,1} \) solution of the equation

\[
\Delta_g d_w^2 = 2n \text{ a.e. in } B_{g_w}(x_0, r_{x_0}).
\]

(7.50)

We next write out the above equation with respect to the background metric. Recall the following formulas for the conformal change of the Hessian:

\[
\Delta_{g_w} d_w^2 = \Delta_g d_w^2 + \frac{2n}{\omega_n} R_{g_w} d_w^2
\]

where \( R_{g_w} \) is the scalar curvature of \( g_w \). Since \( R_{g_w} \) is smooth in \( B_{g_w}(x_0, r_{x_0}) \), this formula follows from the Laplacian comparison theorem, and is also valid for \( C^{1,1} \) metrics. We then obtain

\[
\int_{A_{g_w}(r_1, r_2)} \Delta_{g_w} d_w^2 dV_w = 2n \omega_n (r_2^n - r_1^n).
\]

We conclude that \( d_w \) is a \( C^{1,1} \) solution of the equation

\[
\Delta_{g_w} d_w^2 = 2n \text{ a.e. in } B_{g_w}(x_0, r_{x_0}).
\]

(7.50)
**Proposition 7.23 ([Via00b]).** For any function $h$, 
\begin{equation}
\nabla^2_w h = \nabla^2_g h + dw \otimes dh + dh \otimes dw - \langle dw, dh \rangle g,
\end{equation}
and 
\begin{equation}
\Delta_w h = e^{-2w} (\nabla^2_g h + (2-n)\langle dw, dh \rangle g).
\end{equation}
Equation (7.50) therefore is 
\begin{equation}
\Delta_g d^2 w + (2-n)\langle dw, d(dw)^2 \rangle g = 2 ne^{-2w} \text{ a.e. in } B_{g_w}(x_0, r_{x_0}).
\end{equation}
Notice that the second term on the left-hand side is in $W^{1,p}$ for any $p < \infty$. By a standard regularity theorem (see [GT83]), we conclude that $d^2_w \in W^{3,p}(B_{g_w}(x_0, r_{x_0})$ for any $1 < p < \infty$.

Since $|\nabla d_w| = 1$, equation (7.50) is equivalent to 
\begin{equation}
\Delta_g w d_w = \frac{n - 1}{d_w}.
\end{equation}

**Claim 7.24.** The distance function $d_w$ satisfies 
\begin{equation}
\langle \nabla \Delta d_w, \nabla d_w \rangle + |\nabla^2 d_w|^2 = - \text{Ric}_{g_w}(\nabla d_w, \nabla d_w),
\end{equation}
a.e. in $B_{g_w}(x_0, r_{x_0}) \setminus \{x_0\}$.

**Proof.** We recall the Bochner-Lichnerowicz formula ([Lic58]): If $F \in C^3$ is any function, and $h \in C^2$ is any Riemannian metric, then 
\begin{equation}
\frac{1}{2} \Delta_h |\nabla F|^2_h = |\nabla^2 F|^2_h + \langle \nabla \Delta_h F, \nabla F \rangle_h + \text{Ric}_h(\nabla F, \nabla F).
\end{equation}
By an approximation argument, formula (7.56) is valid for any $F \in W^{3,p}$, $p > 1$. If $h$ is of the form $h = e^{-2w} g$, for a smooth function $v$, then using Proposition 7.23, we see that (7.56) involves at most second derivatives of $v$. By another approximation argument, (7.56) holds for $v \in C^{1,1} = W^{2,\infty}$. In particular, we can take $F = d_w$ on $B_{g_w}(x_0, r_{x_0}) \setminus \{x_0\}$, and $h = g_w = e^{-2w} g$, and we are done.

Using the inequality 
\begin{equation}
\frac{1}{n - 1} (\Delta d_w)^2 \leq |\nabla^2 d_w|^2,
\end{equation}
and equation (7.54), we obtain 
\begin{equation}
0 = \langle \nabla \left( \frac{n - 1}{d_w} \right), \nabla d_w \rangle + \frac{1}{n - 1} (\Delta d_w)^2
\end{equation}
\begin{equation}
\leq \langle \nabla \Delta d_w, \nabla d_w \rangle + |\nabla^2 d_w|^2 = - \text{Ric}_{g_w}(\nabla d_w, \nabla d_w).
\end{equation}
From Corollary 5.2, the Ricci curvature of $g_w$ is non-negative almost everywhere. Therefore (7.58) implies that 
\begin{equation}
\text{Ric}_{g_w}(\nabla d_w, \nabla d_w) = 0,
\end{equation}
almost everywhere in $B_{g_w}(x_0, r_{x_0})$. 

From the inequality $\text{Ric}_{g_w} \geq 2\delta_1(A_{g_w})g_w$ of Corollary 5.2, we find that $R_{g_w} = 0$ almost everywhere in $B_{g_w}(x_0, r_{x_0})$. Consequently $v = e^{-\frac{(n-2)}{2}w}$ satisfies

\begin{equation}
\Delta_g v - \frac{(n-2)}{4(n-1)}R_g v = 0
\end{equation}

almost everywhere in $B_{g_w}(x_0, r_{x_0})$. From elliptic regularity (see [GT83, Ch. 9]), it follows that $w \in C^\infty(B_{g_w}(x_0, r_{x_0}))$.

We can repeat the above argument for any other basepoint $x_0$, to conclude that the metric $g_w$ is smooth in $M_{\text{reg}}$. By the standard version of Bishop’s theorem for smooth metrics, it follows that $g_w$ is isometric to the Euclidean metric (see [Cha93, Th. 3.9]).

Theorem 2.2 follows almost immediately. To see this, note that Proposition 7.22 implies, in particular, that $(M^n_{\text{reg}}, g)$ is locally conformally flat, so from continuity, $(M^n, g)$ is locally conformally flat (by vanishing of the Cotton tensor in $n = 3$, or vanishing of the Weyl tensor in $n > 3$; see [Eis97]). We also see that $M^n \setminus \{x_1\}$ is diffeomorphic to $\mathbb{R}^n$, so that $M^n \setminus \{x_1\}$ is the one-point compactification of $\mathbb{R}^n$ and $M^n$ is homeomorphic to $S^n$. In particular, $M^n$ is simply connected and locally conformally flat, and so by Kupier’s Theorem [Kui49], $(M^n, g)$ is conformally equivalent to $(S^n, g_{\text{round}})$, a contradiction.

Note that the same arguments give the proof of Theorem 2.3, based on the remark at the end of Section 5. Also, by the results of Section 2.1, we have completed the proof of Theorem 1.3.

8. Appendix

8.1. On the $A^\tau$-problem. In this section we make a few remarks about Example 3 from the introduction.

**Theorem 8.1.** Let $A^\tau \in \Gamma_k^+$, $k > n/2$, and

\begin{equation}
\tau > \tau_0(n, k) = \frac{2(n-k)}{n}.
\end{equation}

Then there exists a constant $\delta_0(n, k, \tau) > 0$ so that

\begin{equation}
\text{Ric} > 2\delta_0(n, k, \tau)\sigma_1(A) \cdot g.
\end{equation}

**Proof.** It follows from [GVW03] that if $A^\tau \in \Gamma_k^+$, then

\begin{equation}
\text{Ric} \geq \left( \tau + \frac{(k-n)(2n-n\tau - 2)}{n(k-1)} \right) \frac{R}{2(n-1)} g,
\end{equation}

and the theorem follows by simple calculation. \qed
Now, the operator $F$ in equation (1.16) satisfies the desired properties.

### 8.2. Uniform ellipticity of (1.13)

Suppose $u \in C^2$ is a solution of (1.13) with

$$
\|u\|_{L^\infty} + \|\nabla u\|_{L^\infty} + \|\nabla^2 u\|_{L^\infty} \leq C.
$$

We claim that (1.13) is uniformly elliptic. In particular, by the results of Evans [Eva82] and Krylov [Kry93], $u \in C^{2,\alpha}$ and the Schauder estimates give classical regularity.

To prove the claim amounts to verifying the following property of $F$:

(iii)′ If $\lambda \in \Gamma$ satisfies (a) $F(\lambda) \geq c_1 > 0$, and (b) $|\lambda| \leq L$, then there is a constant $\varepsilon_0 = \varepsilon_0(c_1, L)$ such that

$$
\varepsilon_0^{-1} \geq \frac{\partial F}{\partial \lambda_i}(\lambda) \geq \varepsilon_0.
$$

Note that if $u \in C^2$ is a solution satisfying the bound (8.4), then the eigenvalues of $A_u$ will obviously satisfy properties (a) and (b). Moreover, inequality (8.5) says that the linearized operator is uniformly elliptic with ellipticity constant $\varepsilon_0$.

To prove property (iii)′, let $\hat{\Gamma} = \{ \xi \in \overline{\Gamma} : |\xi| = 1 \}$, and $\hat{\lambda} = \lambda/|\lambda| \in \hat{\Gamma}$. We first show there is a constant $\delta_0 > 0$ such that

$$
\text{dist}(\hat{\lambda}, \partial \hat{\Gamma}) \geq \delta_0.
$$

Assuming this for the moment, let us see how (8.5) follows.

Since $F$ is homogeneous of degree one, $\partial F/\partial \lambda_i$ is homogeneous of degree zero. Therefore,

$$
\frac{\partial F}{\partial \lambda_i}(\lambda) = \frac{\partial F}{\partial \lambda_i}(\hat{\lambda}).
$$

But (8.6) says that $\hat{\lambda}$ is a fixed distance from the boundary of $\hat{\Gamma}$. Since $\partial F/\partial \lambda_i > 0$ in $\Gamma$, inequality (8.5) follows from the continuity of $\partial F/\partial \lambda_i$.

Returning to (8.6), we argue by contradiction. Suppose there is a sequence $\{\lambda_i\} \subset \Gamma$ with $|\lambda_i| \leq L$ and $F(\lambda_i) \geq c_1 > 0$, but with

$$
\text{dist}(\hat{\lambda}_i, \partial \hat{\Gamma}) \to 0
$$

as $i \to \infty$, where $\hat{\lambda}_i = \lambda_i/|\lambda_i|$. Choose a subsequence (still denoted $\{\lambda_i\}$) with $\hat{\lambda}_i \to \hat{\lambda}_0 \in \partial \hat{\Gamma}$. By continuity, $F(\hat{\lambda}_i) \to 0$. By homogeneity,

$$
F(\lambda_i) = F(|\lambda_i|\hat{\lambda}_i) = |\lambda_i|F(\hat{\lambda}_i) \to 0,
$$

since $|\lambda_i| \leq L$. However, (8.8) contradicts assumption (a).
References


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